

**TWO-COLOR  
SMALL OFFSET PRESS**

# **Itek Graphix 3985**

**ELECTRICAL SERVICE MANUAL**



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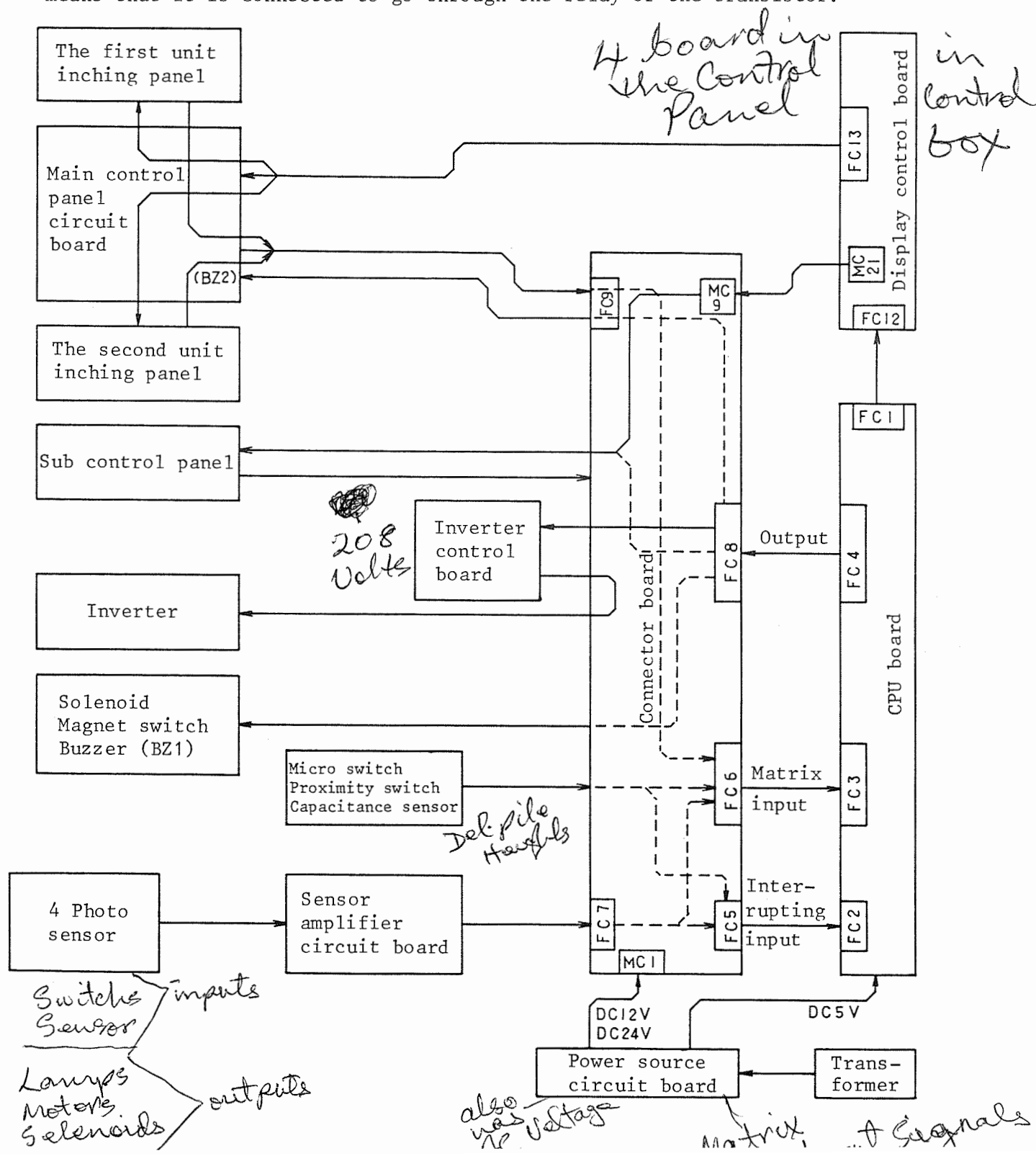
about  
\$3M  
inventor cost



## 1. Outline

## (1) Hardware

This machine's hardware is structured as shown in the illustration below. The direction of the arrow shows the direction of the signal being sent. Also the arrow with the solid line means that the wire or the pattern on the printed circuit board is directly connected. The arrow with the dotted line means that it is connected to go through the relay or the transistor.



The hardware of this machine is made up of seven printed circuit boards. We will briefly explain how each functions.

1 a) CPU board

The CPU board (Central Processing Unit) is the printed circuit board that collects all information such as each switches signal, and the signals from the sensor. The CPU follows the program on the P-ROM and issues the output signals based on the input signal, which controls the solenoid and the LEDs.

2 b) Display control printed circuit board

Next to CPU Board

With the signal from the CPU board, this is the printed circuit board that controls the lighting of the LEDs on the main control panel, the push button switches lamp lighting on each inching control panel and the push button switches lamp lighting on the sub control panel.

3 c) Inverter control printed circuit board

on top of connector

With the signal from the CPU board, this is the printed circuit board that sends the signal for normal rotation, reverse rotation, stop, inching, and the speed setting to the inverter.

4 d) Sensor amplifier printed circuit board

Sensor Board

This is the amplifier printed circuit board for the four photo sensors.

5 e) Main control panel printed circuit board

The indication LEDs, the LED limit resistors and the buzzer (BZ2) are on this board. The inching control panel push button switches on the first and the second units are routed through this printed circuit board and connected to the connector board and the display control board.

6 f) Connector board (Relay Board)

This is used to connect the CPU board and the switches, the solenoids and the other parts.

7 g) Power source printed circuit board (Power Supply Board)

This is the direct current power source for the controller and sends the power to each printed circuit board.

2/C power Supply Bd. will work in perfect.

Perfector Supply Bd. will not work in 2/C.

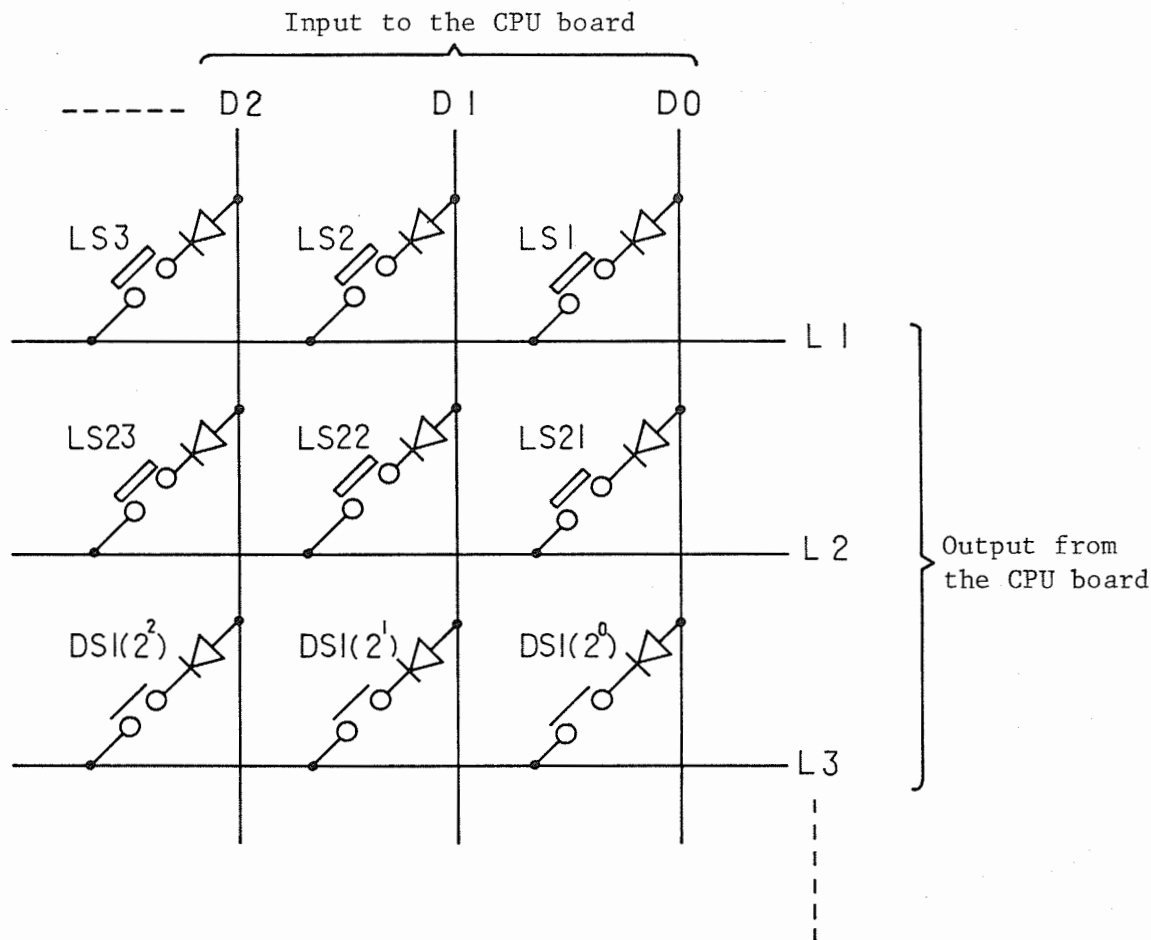
5VDC  
12VDC  
24VDC

(2) Input using the matrix system and the interrupting system

There are two ways to input to the CPU board in this machine, the matrix system and the interrupting system. This machine's program includes the procedure to check the input (switch) condition at certain times (actually every 5/1000 of a second). At this time, the signal that is interrupted from the matrix system is checked. This input can only be checked at certain times, so the CPU will not respond for a second to the input change that occurs at that time. Therefore when the CPU has to know the time of the signal input, this matrix input does not work. For example, before you go to work in the morning, you check the sky and see that it is clear. You work inside all morning then going out for lunch it is raining outside. You did not know when it started to rain. Because you only checked the weather in the morning before coming to work and at lunch time you may not have known that it rained in the morning. The input using the matrix system is the same as this example, the CPU can only check the input at certain times. Therefore you cannot know when the input is changed or when a short signal is inputted. In other words the matrix system does not work when inputting immediate signals or signals that the microcomputer must know when the signal is changed. On the other hand, the good point of the matrix input system is that it allows you to input a lot of information using only a few signals.

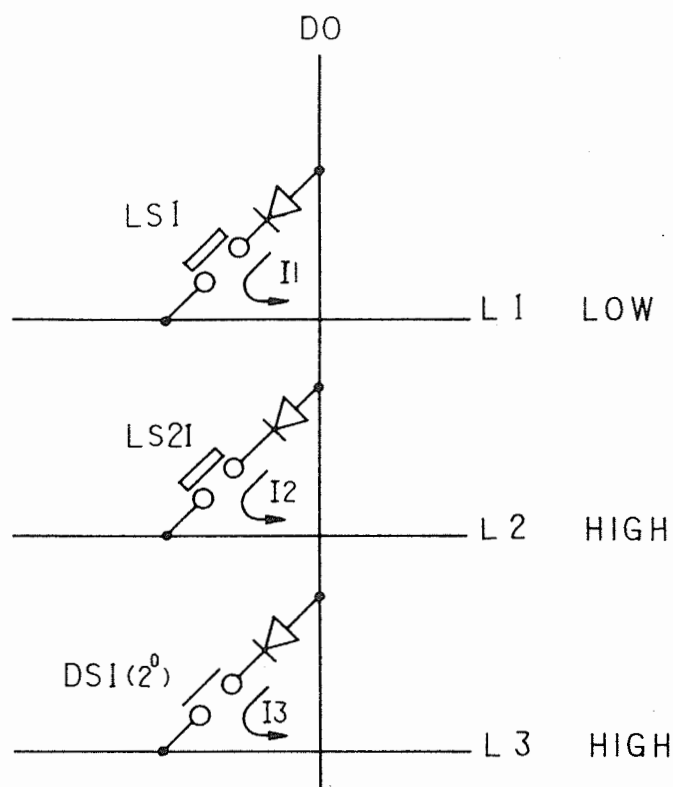
The other type of inputting is the interrupting system. When inputting using the interrupting system, the CPU stops its procedure and then the CPU starts to follow the new input. For example, you have a telephone on your desk in your company. You can answer the telephone as soon as the phone rings while you are working without always watching your phone. Please refer to the 7. input circuit of the connector board illustration item (page 38) for more explanation about the two types of input.

## (3) Input using the matrix system



This indicates a part of the input circuit using the matrix system. The input using the matrix system is the circuit that uses the output wire from the CPU board and the input wire to the CPU board to input a lot of input information with fewer signal wires. This machine's matrix system is sometimes called the diode matrix system because diodes are used in the circuit. The horizontal lines shown above are the output wire from the CPU board and the CPU determines which switch condition is inputted by using these lines. This machine has eleven of these lines and they are called the select lines (L1 ~ L11). The vertical lines shown above are the input lines to the CPU board and the CPU inputs the actual switch condition by using these lines. This machine has eight of these lines and they are called the data lines (D0 ~ D7).

The CPU output is set so that only the select line of L1 through L11 that is used is LOW while the others are HIGH. In other words, when wanting to input the LS1 as shown in the previous illustration, the CPU sets the L1 select line to be LOW and sets all the other select lines after L2 to be HIGH.

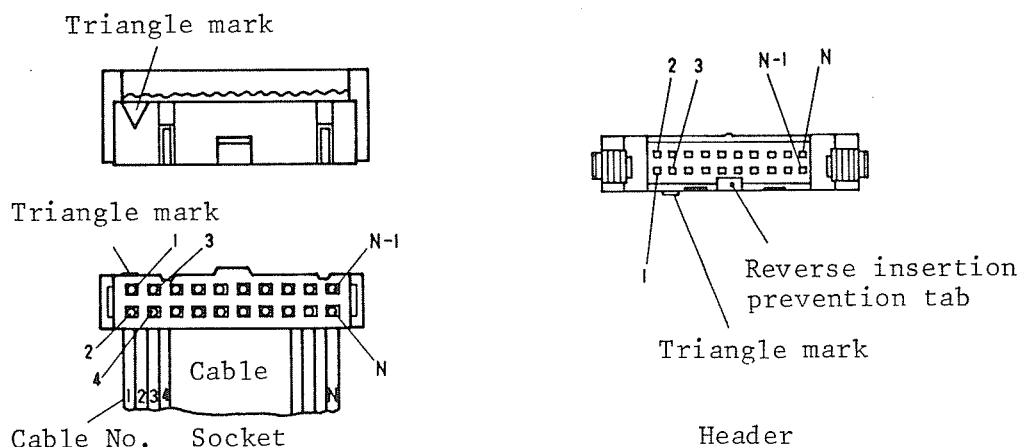


At this time, the electric current that goes to the L1 through the L3 lines from the DO data line are called the I1 through the I3. At this time, the I2 and the I3 will not go on without the LS21 or the DS1 (2°) signal issued because the L2 and the L3 select lines are HIGH. When the LS1 is ON the I1 goes on, and when the LS1 is OFF the I1 will not go on because the L1 line is LOW. Therefore the CPU judges that the LS1 is ON when the electric current comes from the DO, and judges that the LS1 is OFF when the electric current does not come from the DO. The CPU judges the ON/OFF of the switches other than the LS1 in the same way as the explanation above of the LS1.

## (4) The flat cable connector

## a) Connector terminal number

At the flat cable connector, the terminal number is not indicated. The connector has a triangle mark, and based on the triangle mark the terminal number can be determined. As shown in the illustration below, the terminal with the triangle mark is No. 1 and the opposite side of the terminal is No. 2, so then the side of the No. 1 terminal is No. 3 and the rest of them are the same as shown below.



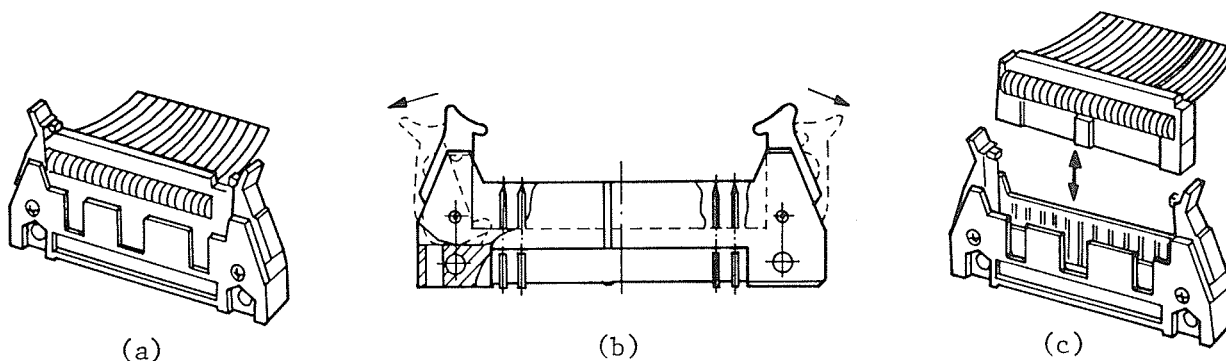
## b) Connector removal and mounting procedures

## ° Removal procedures

Push out the fasteners in the direction of the arrow at the same time as shown in the illustration (b), and then it can be removed as shown in the illustration (c) easily.

## ° Mounting procedure

Open the fasteners as shown by the dotted line in the illustration (b) and mount it straight from the top. This connector cannot be mounted backwards. After mounting, push in the fasteners to lock the connector and check that the socket is correctly connected on the fasteners.



## 2. CPU board

This CPU board is mounted on the rear side of the middle board in the control box, and it judges and processes the inputted information and issues the output signal. On the CPU board, there are the parts and circuits as shown below.

- ° CPU (Z80) ..... The control parts that process the information for the operation of the machine.
- ° P-ROM ..... The memory that has the program and the data for operating the machine is inputted on.
- ° RAM ..... The memory that allows the CPU to process the information.
- ° Oscillator circuit ..... The circuit that generates the clock pulse to run the CPU.
- ° Interface circuit ..... The circuit that connects the input and the output system with the CPU.
- ° Back up circuit ..... The circuit that provides the electric source back up on the RAM.

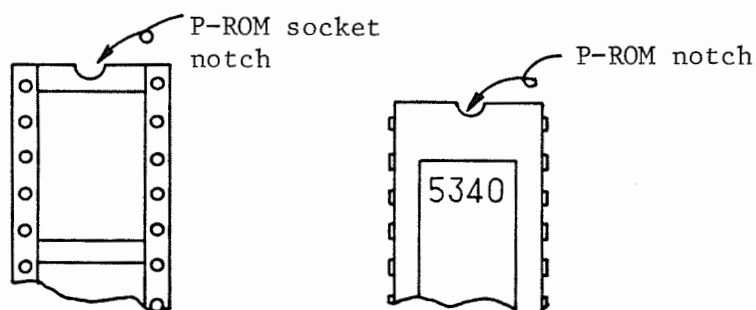
### (1) Replacement of the parts

When the output from the CPU board is not correct even though the input to the CPU board is correct, replace the CPU board with a new one. When replacing parts, please be careful of the following points listed below.

#### a) P-ROM

	[Part No.]
CPU board with P-ROM .....	5340 61 640-2
{ CPU board (without the P-ROM) ....	5330 61 641-1
P-ROM .....	5340 61 801-1

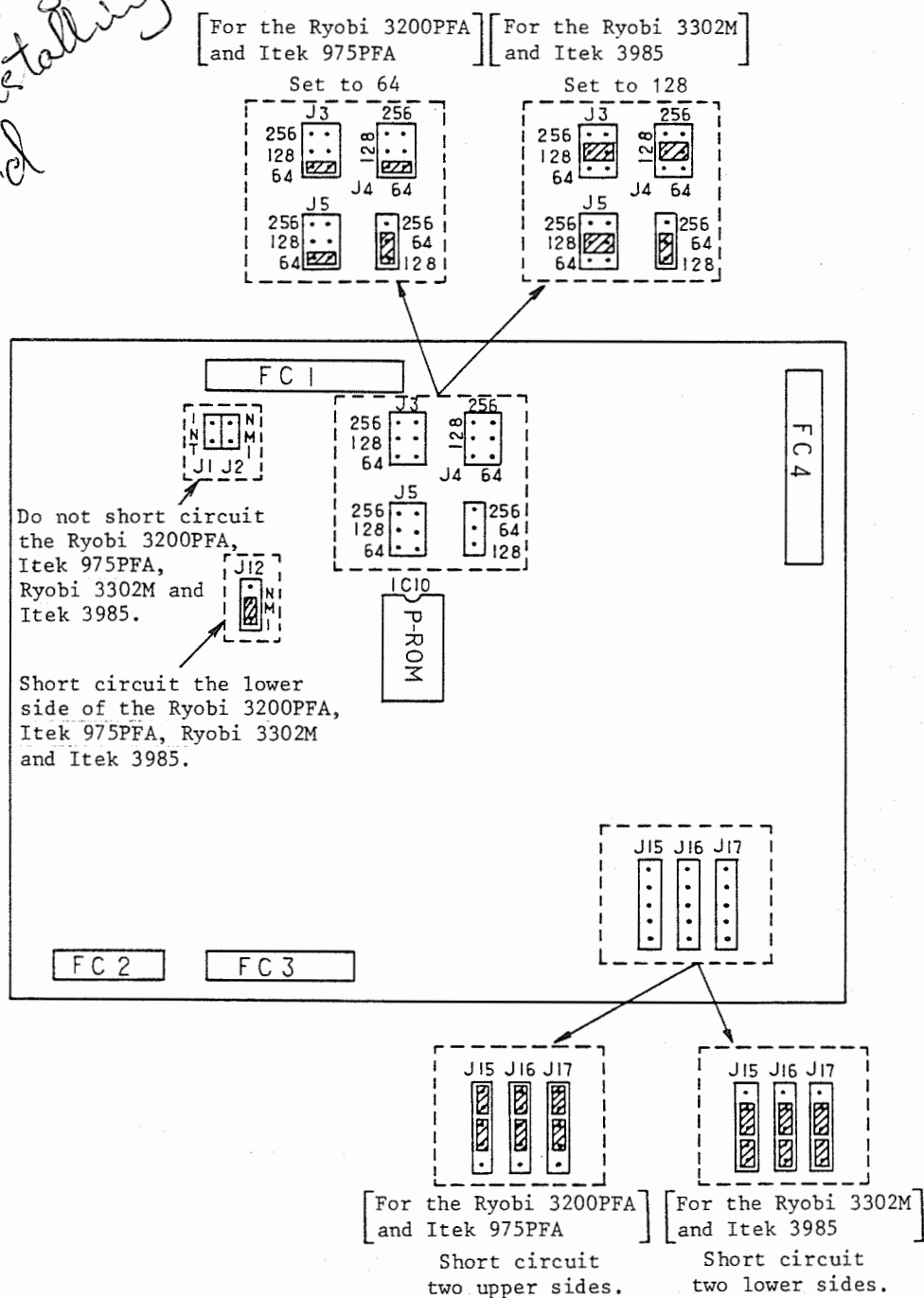
There are two replacement part Nos. for the CPU board, one that includes the P-ROM and the one that does not include the P-ROM. The part number 5340 61 640 is the exclusive basic board for this machine because it includes the P-ROM. 5330 61 641 can also be used for Ryobi 3200PFA and Itek 975PFA. When doing the service using the printed circuit board without the P-ROM, pull off only the P-ROM from the old printed circuit board before replacing it, and mount the P-ROM on the new printed circuit board. At this time, please be careful not to bend the P-ROM pins when removing and mounting the P-ROM. Using the P-ROM removing tool for this is convenient. Also when mounting the P-ROM, be careful of the P-ROM mounting direction. Mount the P-ROM socket notch part in the same direction as the P-ROM notch.



## b) Jumper wire

This machine's CPU board can be also used on the Ryobi 3200PFA and the Itek 975PFA so the jumper wire is used to change the circuits to match the machine. If the jumper wire is not mounted correctly, the CPU board will not work, so when replacing the CPU board with a new one, please check the jumper wire connection position. Refer to the illustration below for the CPU board jumper wire position for this machine.

*check Jumper  
b/y installing  
board*





- c) The interchangeability of the Ryobi 3302M and the Itek 3985 CPU board and the Ryobi 3200PFA and the Itek 975PFA CPU board

The CPU board that is used on the Ryobi 3200PFA and the Itek 975PFA shipped from the factory does not have all the functions that the Ryobi 3302M and Itek 3985 CPU board has. Therefore the CPU board that is mounted on the Ryobi 3200PFA and the Itek 975PFA cannot be used on this machine. The CPU board for this machine can be used on the Ryobi 3200PFA and the Itek 975PFA. The CPU board replacement part can be used on this machine and the Ryobi 3200PFA and the Itek 975PFA.

- (2) Explanation of the battery replacement

*Will last 6 years*

There is a battery on the CPU board used as a back up power source for the memory (RAM) if there is a power failure. If the battery dies, a lamp will light on the main control panel to indicate that the battery is dead. When this occurs, replace the dead battery with a new battery as soon as possible.

The part number for the battery assembly ... 5330 61 646

On this machine, when the battery is dead, the problems listed below will occur.

- a) The lubrication warning lamp and the pump filter cleaning warning lamp will not operate normally.
- b) The preset number of sheets and the number of actual printed sheets on the sheet counter will be reset to 0 when the main power switch is turned OFF.
- c) The speed setting position will always be reset to 3000 rph when the main power switch is turned OFF.

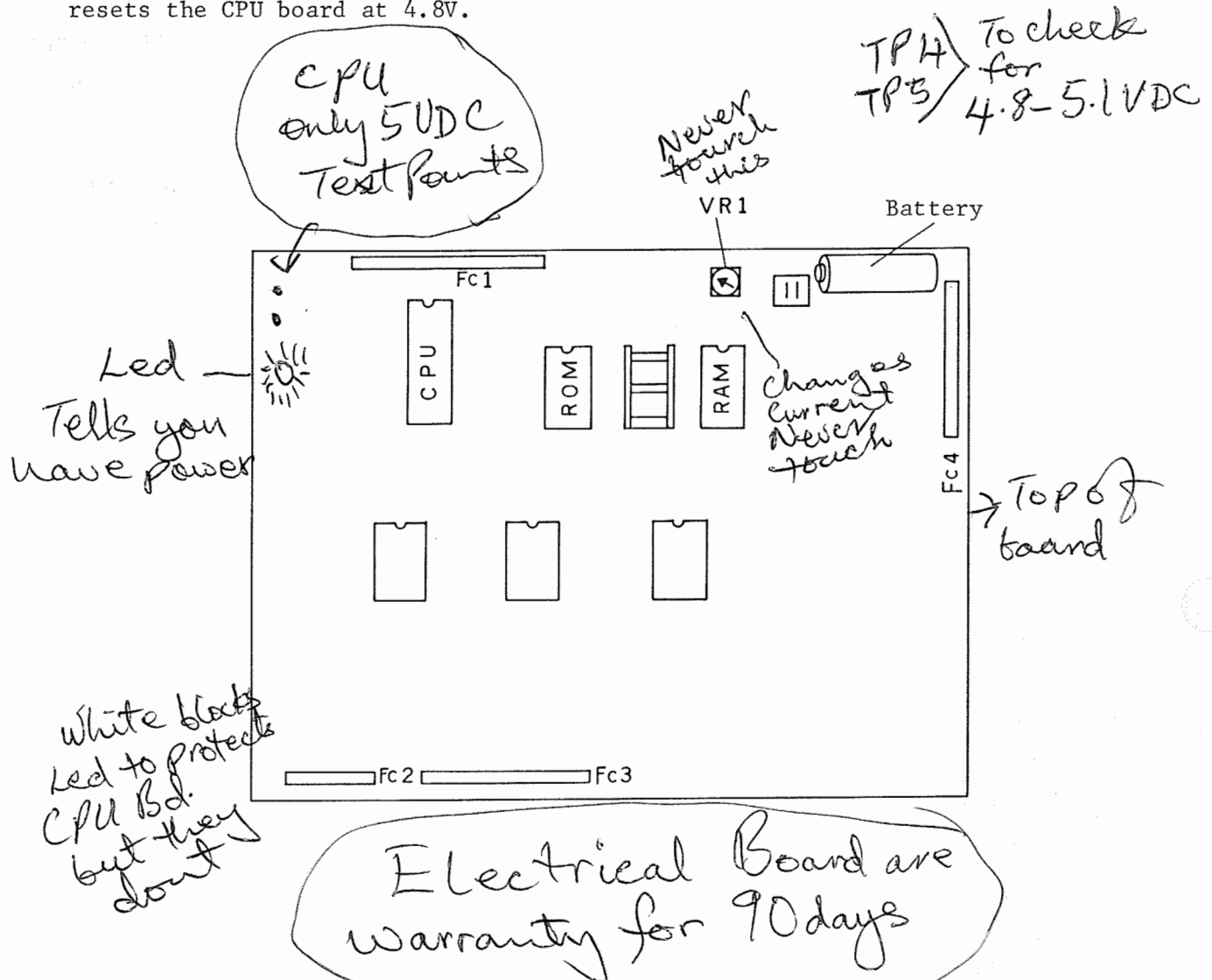
*Copies*  
*1,500,000*  
*1,000,000*

*lubrication  
 Filter Cleaning  
 Warning Lamp*

*When battery drop to 3.6 Volts,  
 Replace*

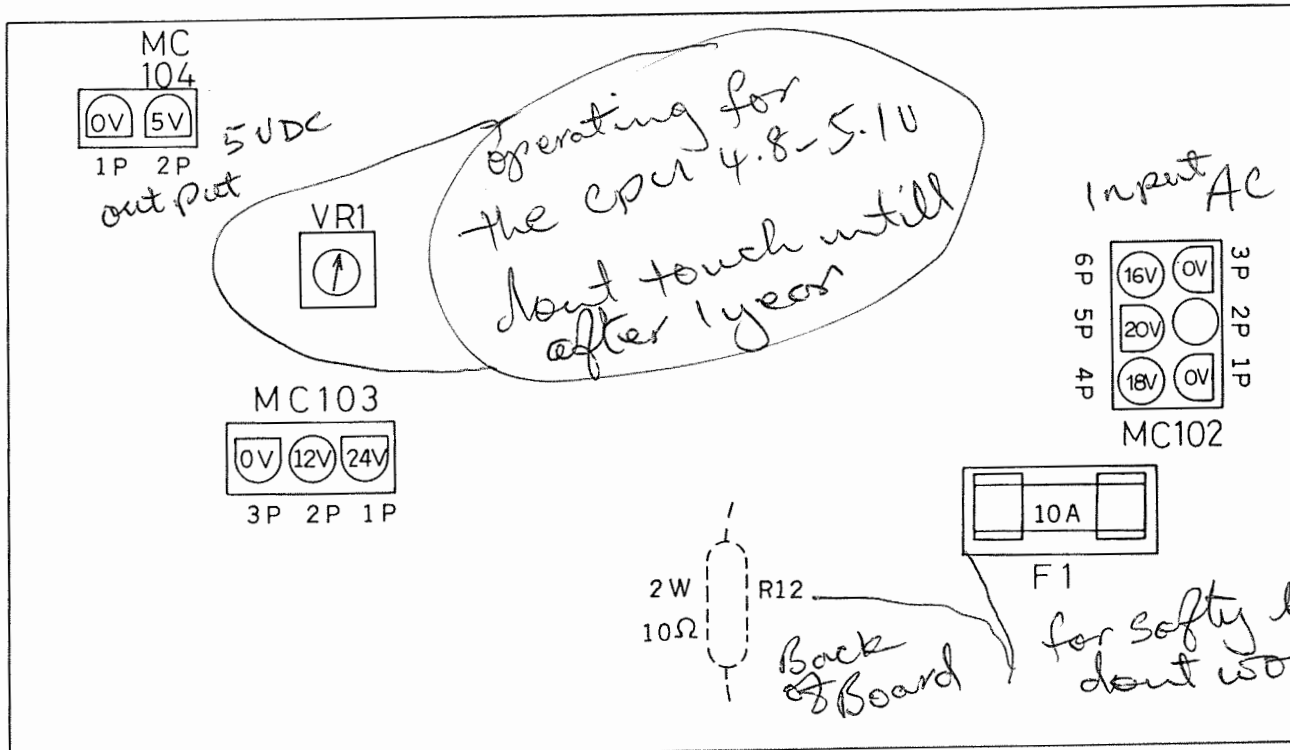
## (3) The power resetting circuit

On the CPU board, there is a circuit to reset the CPU board if there is a voltage drop to the CPU board. A variable resistor VR1 is used on the CPU board to adjust the reset voltage. Please do not touch the variable resistor VR1 because it has already been adjusted in the factory so it resets the CPU board at 4.8V.



## 3. Power source circuit board

can be used  
in perfect  
but not  
vice  
versa



The power source circuit board supplies DC12V and DC24V to be the power source for all of the control circuits other than the CPU and supplies DC5V to be the power of the CPU board.

## a) MC102

AC16V and AC18V is supplied from the transformer at the back of the control box.

- ° No. 1 pin and No. 4 pin, or No. 1 pin and No. 5 pin

They supply the AC power source for DC24V and DC12V. Usually use the AC18V (No. 1 pin and No. 4 pin), but if the DC24V voltage is low, change the line from the AC18V (the No. 4 pin) to the AC20V (the No. 5 pin).

- ° No. 3 pin and No. 6 pin

These supply the AC16V for DC5V.

## b) MC103

It supplies the DC12V and the DC24V to the connector board.

- ° No. 1 pin ..... +24V
- ° No. 2 pin ..... +12V
- ° No. 3 pin ..... 0V

c) MC104

It supplies the DC5V to the CPU board.

- ° No. 1 pin ..... 0V
- ° No. 2 pin ..... +5V

d) VR1

This variable resistor is for the DC5V output voltage adjustment. It has been adjusted to 5.1V for the output voltage in the factory, so do not touch this variable resistor.

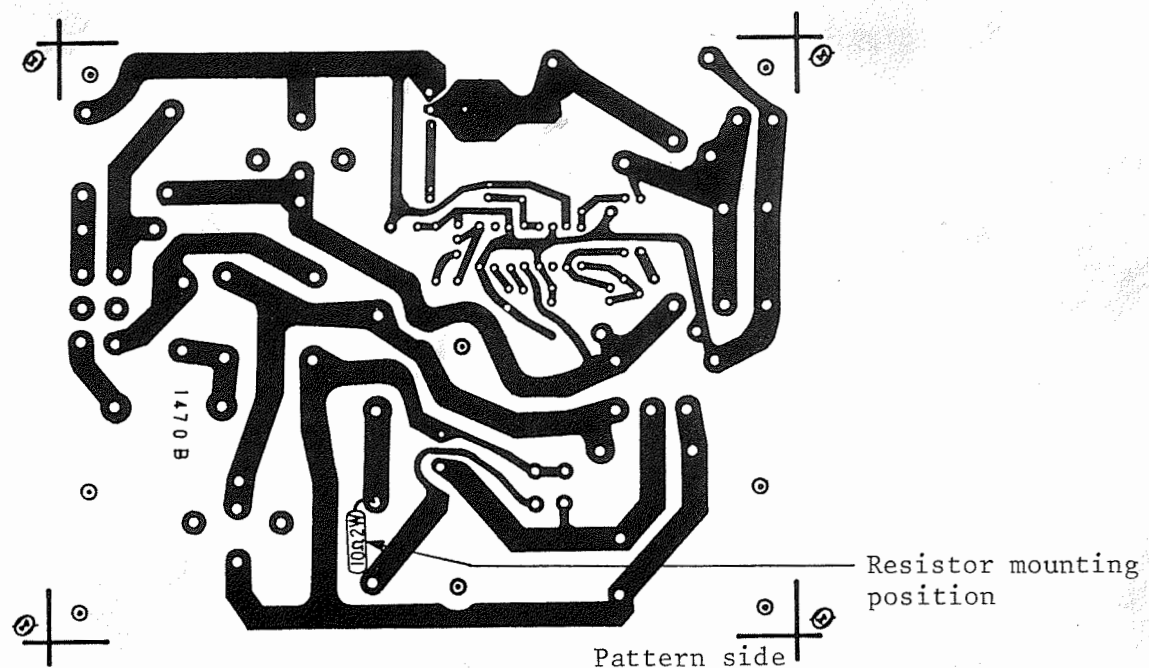
e) F1

This is the fuse for the short circuit protecting the DC24V circuit. When the fuse blows, replace it with a 10A fuse.

10A fuse part No. .... 97 722

f) R12

This limited resistor for the DC12V circuit is mounted at the back of the circuit board. If the DC12V circuit is short circuited, this resistor will heat up and break down. When this resistor breaks down, mount a new 2W10 $\Omega$  resistor on the back surface of the circuit board.

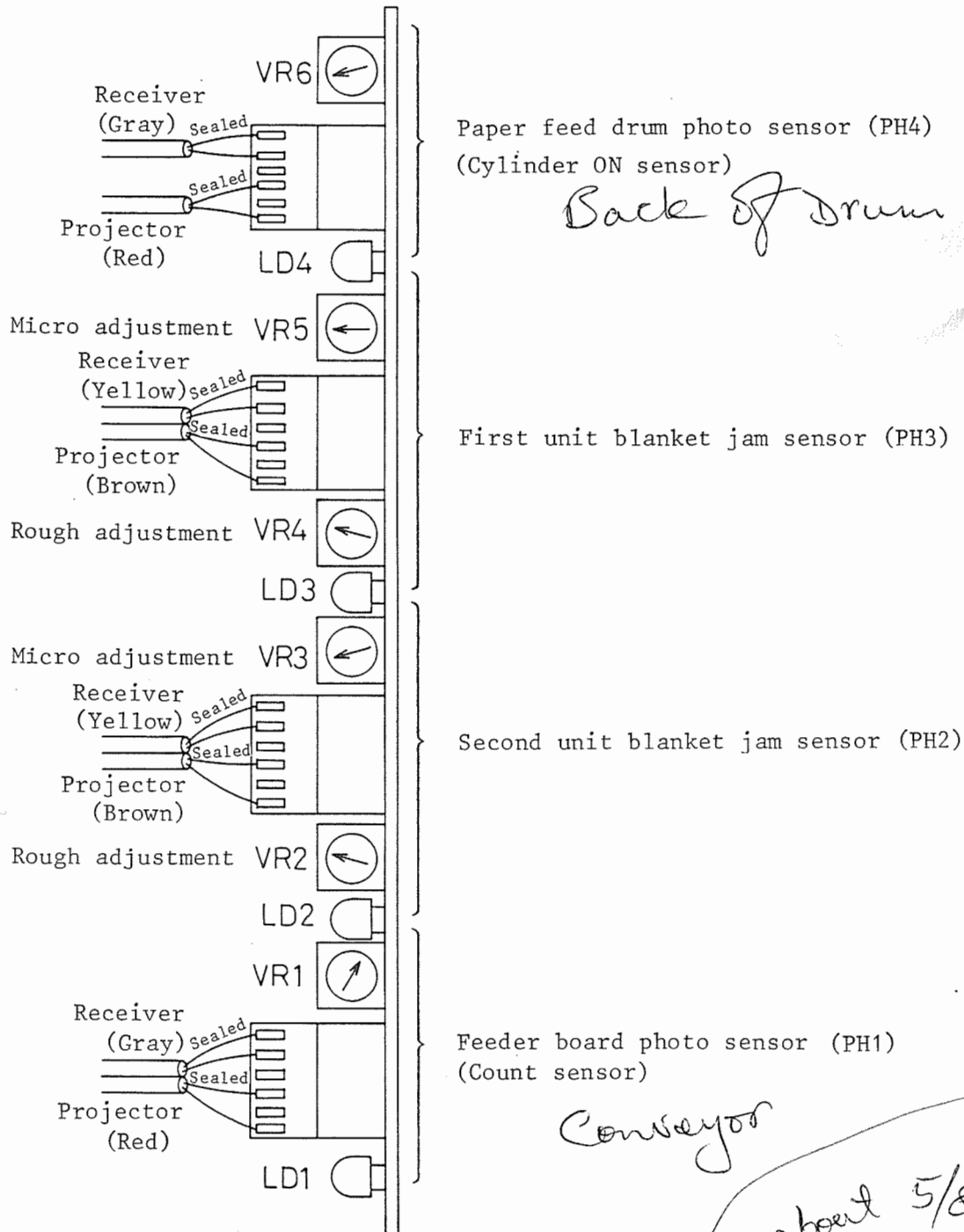


check the jumpers on next page

#### 4. Sensor circuit board

This circuit board holds the four photo sensors amplifiers on it.

(1) How to connect the photo sensor



Conveyor

about 5/8 margin  
3/4  
to activate catching  
sensor

(2) How to adjust the sensor circuit board sensitivity

a) Paper feed drum photo sensor (PH4)

- 1) Stop the machine at 130 degrees on the timing plate.
- 2) Turn the VR6 fully in the clockwise direction and check that the LD4 light goes off.
- 3) If the LD4 light does not go off, turn the VR6 in the counterclockwise direction until the LD4 light goes off.

*on with paper*

b) The first unit blanket jam sensor (PH3)

-- Rough adjustment --

- 1) Set the VR5 for the micro adjustment at the center.
- 2) Turn the VR4 for the rough adjustment in the clockwise direction until the LD3 lights.

-- Micro adjustment --

- 1) Turn the VR5 for the micro adjustment slowly in the counterclockwise direction until the LD3 light goes off.
- 2) After the LD3 light goes off, turn the VR5 in the counterclockwise direction approximately half a scale length.

(Note) When adjusting the sensitivity, check that the blanket is positioned over the sensor. After the adjustment, run the machine and check that the blanket jam detector does not actuate.

c) The second unit blanket jam sensor (PH2)

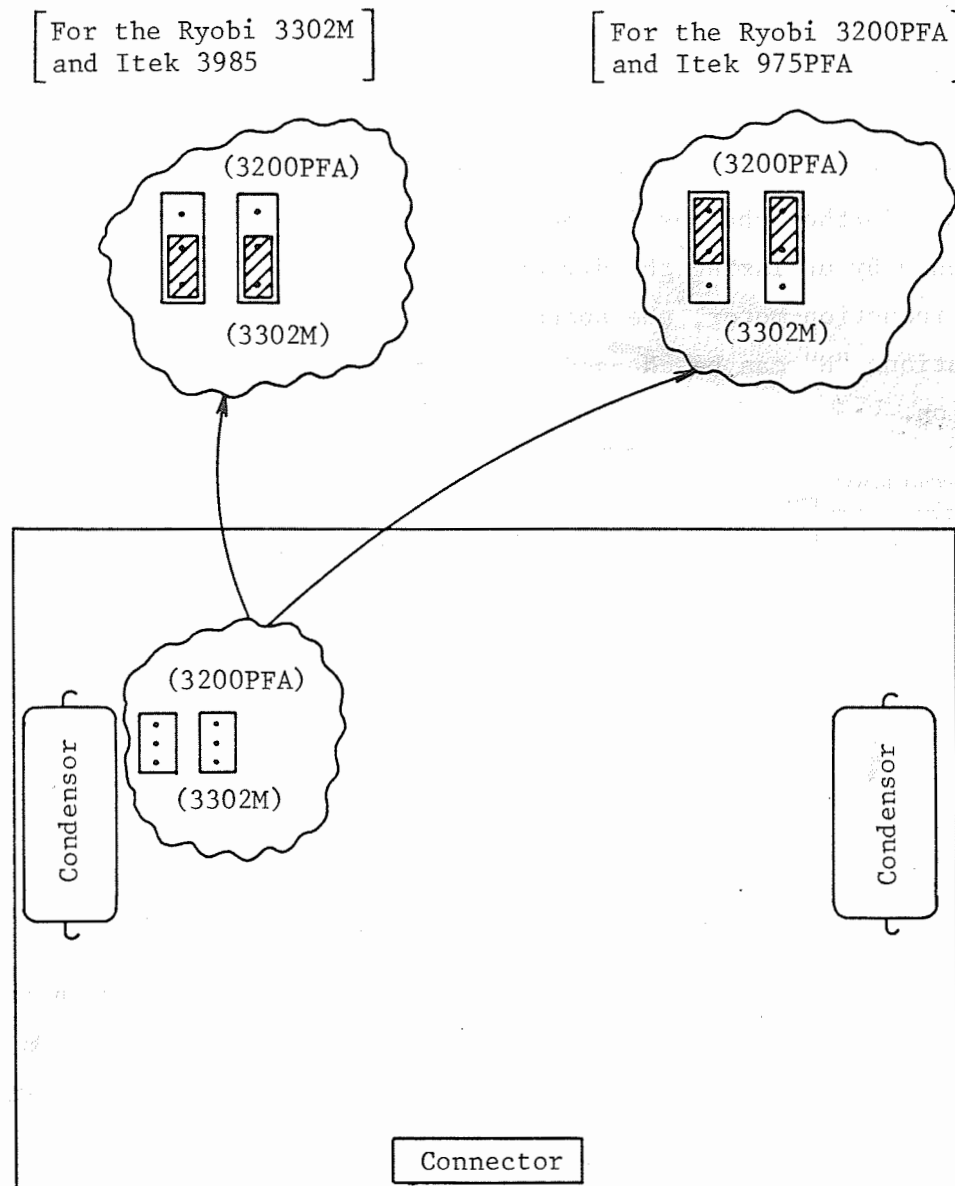
The sensitivity adjustment is the same as the first unit blanket jam sensor.

d) Feeder board photo sensor (PH1)

- 1) Check that no retainers or paper is over the feeder board photo sensor.
- 2) Turn the VR1 fully in the clockwise direction and check that the LD1 light goes off.
- 3) If the LD1 light does not go off, turn the VR1 in the counterclockwise direction until the LD1 light goes off.

- (3) The interchangeability of the Ryobi 3302M and the Itek 3985 sensor printed circuit board and the Ryobi 3200PFA and the Itek 975PFA sensor printed circuit board

These machines printed circuit boards have 2 jumper wires mounted so it can be used on both the Ryobi 3200PFA and the Itek 975PFA. When replacing it with a new one, check that the 2 jumper wires are properly connected the same way as shown in the illustration below.



## 5. Inverter

### (1) What's an inverter?

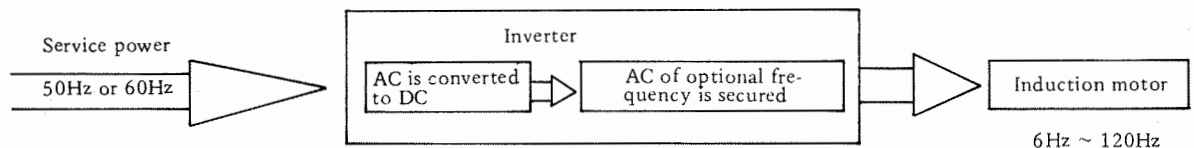
The drive motor of this machine is driven by an inverter. Normally, the relation among the revolution speed and voltage, frequency and torque of an induction motor is as below;

$$N = \frac{120f}{P} (1 - s) \dots\dots\dots (1)$$

$$T \approx K \left( \frac{V}{f} \right)^2 \dots\dots\dots (2)$$

N: Revolution (rpm)	f: Frequency (Hz)
P: Poles of motor	s: Slip
T: Torque	K: Constant
V: Terminal voltage	

An inverter is used to change the alternate current to make direct current and then further changes it back to the alternate current of optional frequency by utilizing the direct current. Then, by changing the frequency of an induction motor, the speed can be controlled. That is the number of revolutions "N" can be changed by changing the value "f" in the above equation.



Therefore, provided the slip of "0", this machine can change the revolution speed of the drive motor from 180 rpm to 3600 rpm.

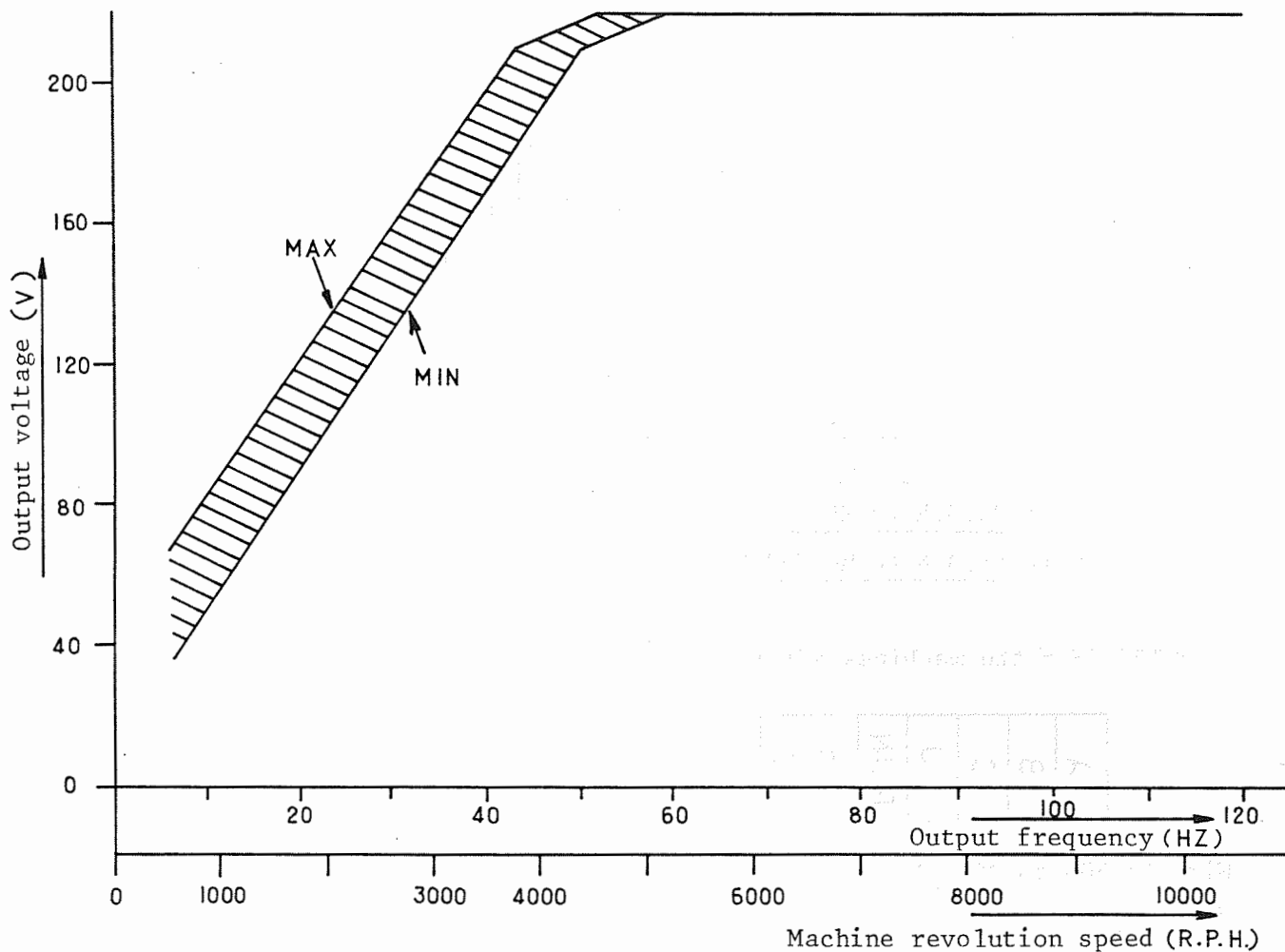
$$N_{\min} = \frac{120 \times 6}{4} = 180 \text{ (rpm)}$$

$$N_{\max} = \frac{120 \times 120}{4} = 3600 \text{ (rpm)}$$

From the above equation (2), however, a constant output torque of the drive motor cannot be obtained only by changing the frequency "f". An inverter is used to keep the V/f constant by changing the voltage "V" applied to the motor simultaneously with the change of frequency "f". This means that the voltage applied to the drive motor of this machine is not always 3 phase 200V, but a voltage corresponding to the frequency is applied to the motor. Shown on the next page is the relation (V/f pattern) between frequency and voltage.



&lt;V/f pattern&gt;

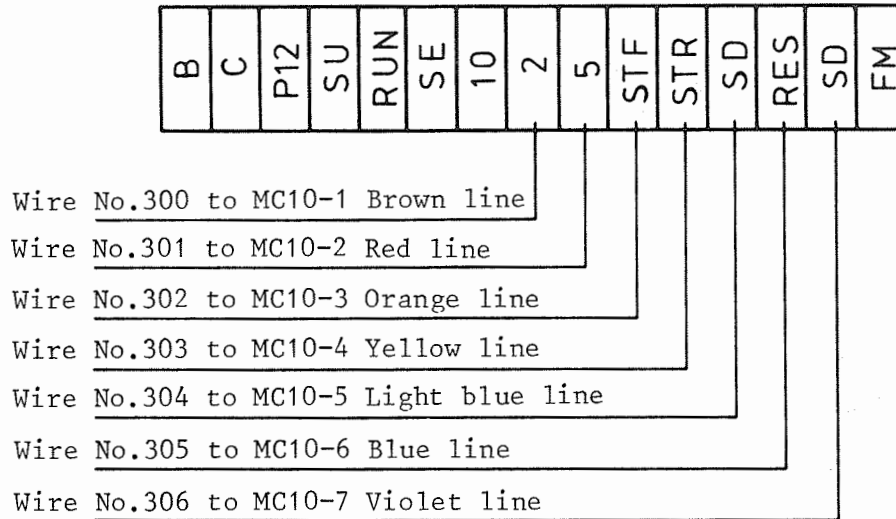


(Note) The horizontal axis shows the output frequency of the inverter and the machine revolution speed, while the vertical axis shows the output voltage of the inverter.

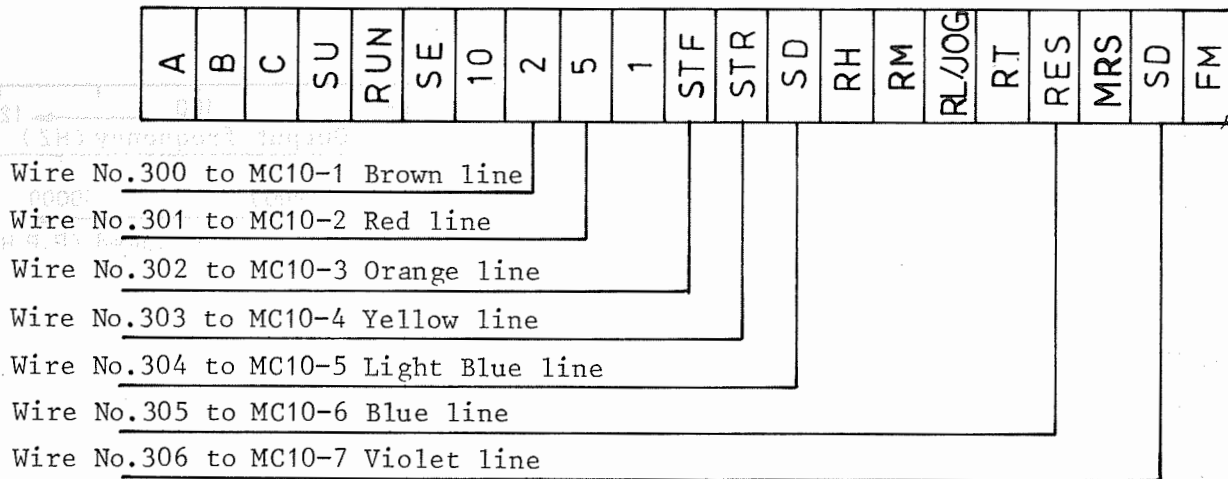
## (2) Explanation of the input and output terminals of the inverter

° The wiring method to the terminal block of inverter is shown below.

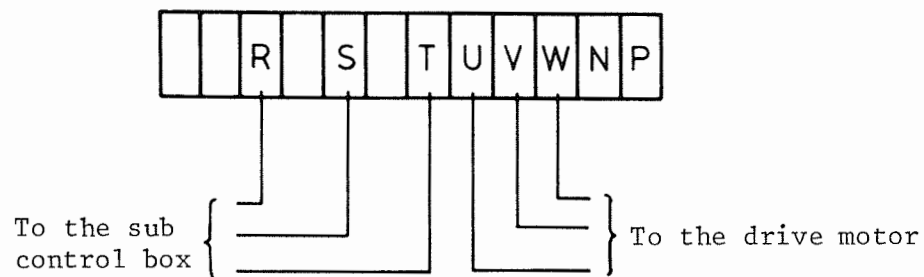
<TB2 (For the machines before #1131)>



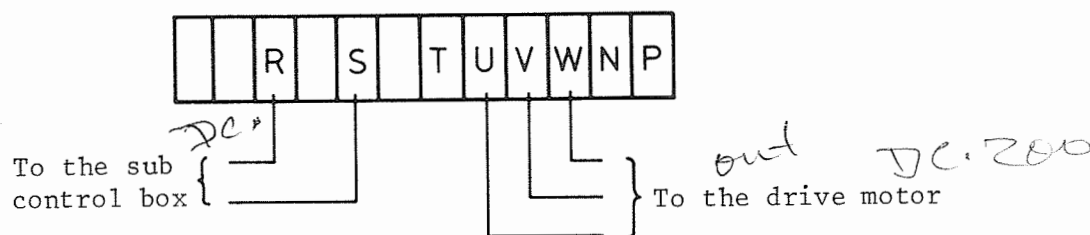
<TB2 (For the machines after #1132)>



<TB1 (for a 3 phase machine)>



<TB1 (for a single phase machine)>



Noise filter is also connected to R, S, and T of the terminal block (TB1) above.

a) Power source ..... R.S.T

3 phase 200V or single phase 200V is supplied to the inverter. In the case of a single phase machine, T-line input terminal is not used.

b) Output terminal ..... U.V.W

Connected to the drive motor.

c) Drive signal ..... STF (Wire No.302), STR (Wire No.303), SD (Wire No.304)

When the relay is connecting the STF and the SD, the drive motor will rotate in the normal direction, and when it is connecting the STR and the SD, the drive motor will rotate in the reverse direction.

d) Reset signal ..... RES (Wire No.305), SD (Wire No.306)

This circuit resets the inverter.

When the relay is connecting the RES and the SD, the inverter will be reset to stop the drive motor quickly.

e) Speed setting terminal ..... 2 (Wire No.300), 5 (Wire No.301)

2 ..... Speed set voltage supplied

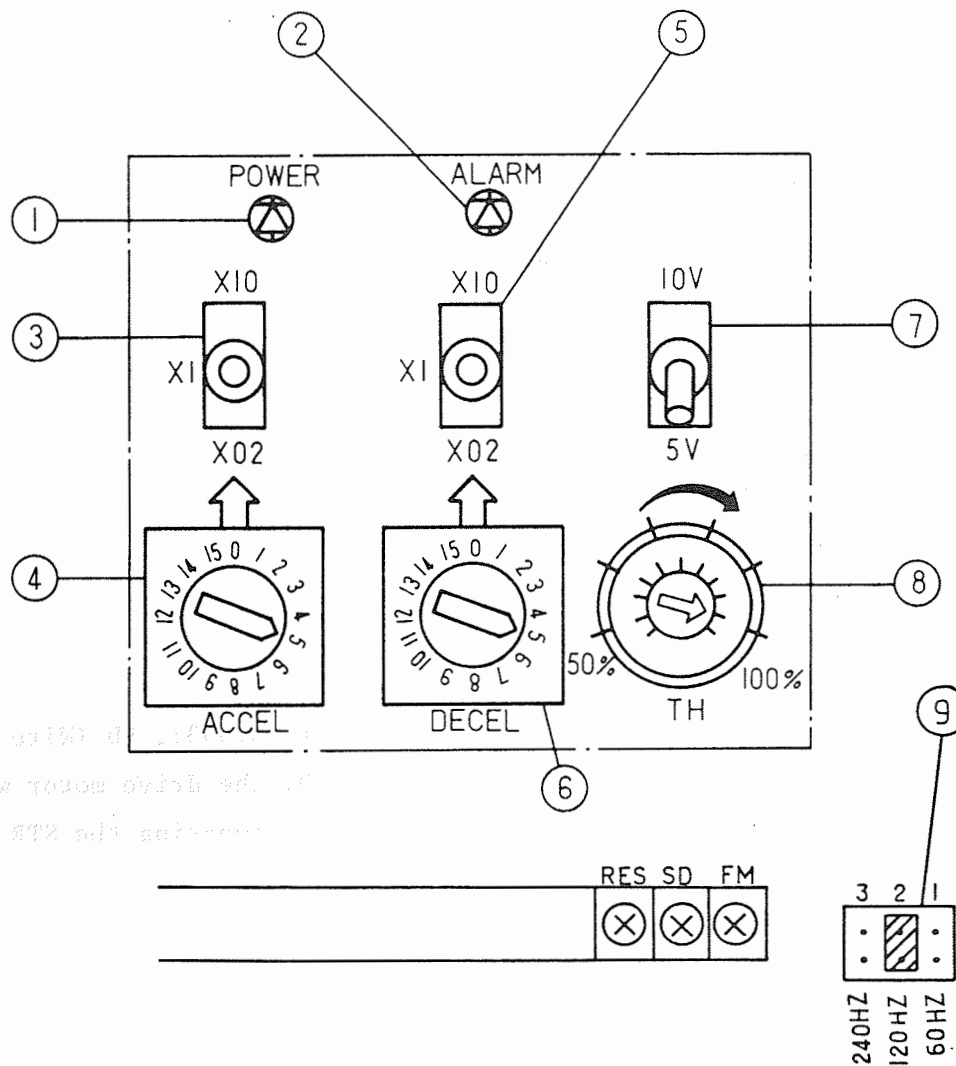
5 ..... 0V

By increasing or reducing the DC voltage to the terminals 2 and 5, the drive motor speed is controlled.

The relationship of the drive motor speed and the voltage is shown in the list below.

Machine speed	Voltage between the terminals 2 and 5
1000rph	about 0.5V
3000rph	about 1.4V
7000rph	about 3.3V
10000rph	about 4.7V

## (3) Inverter adjustment (For the machines before #1131)



## (1) Power ..... Power lamp

When a 3 phase or a single phase power source is supplied to the inverter, this LED lights up.

## (2) Alarm ..... Warning lamp

When the following troubles occur, this LED lights up and the drive motor stops. In this case, first fix the cause of the trouble. Then, push the machine stop button or turn OFF the power, which will reset the inverter allowing re-operation.

	Problem and cause	Actions to be taken
Overcurrent cutoff	Protective circuit actuates against overcurrent exceeding 200% of the rated output current of the inverter.	<ul style="list-style-type: none"> <li>° Check the supply voltage to the inverter.</li> <li>° Check for a proper load on the drive motor.</li> <li>° Check for a proper acceleration/deceleration time. (Refer to (3), (4) and (5), (6))</li> <li>° Check for a short on the output side of the inverter.</li> </ul>
Regenerative overcurrent cutoff	When the output voltage of the inverter is excessive due to regenerative energy, the protective circuit actuates.	<ul style="list-style-type: none"> <li>° Check if the deceleration time is too short. (Refer to (5) and (6))</li> </ul>
Instantaneous power failure protection	The protective circuit actuates against an instantaneous power failure of more than 15 micro seconds to prevent malfunction.	
Overcurrent cutoff (Electro-thermal)	This inverter has a built-in electrothermal relay. An overload on the drive motor actuates the protective circuit.	<ul style="list-style-type: none"> <li>° Check the current in the drive motor and examine the cause of the overload, if any.</li> <li>° Check for a proper setting of the electrothermal relay in the inverter. (Refer to (8))</li> </ul>
Fan overheat protection	When the cooling fans overheat due to the decrease of the cooling effect of the semiconductors in the inverter, the thermal sensor actuates the protective circuit.	<ul style="list-style-type: none"> <li>° Check the cooling fan of the inverter, the ambient temperature, etc.</li> </ul>

### (3),(4) ACCEL ..... Acceleration time setting

A switch is used to set the acceleration time of the drive motor. The multiplying factor is set with the switch (3) and the time with the dial (4).

When the switch (3) is shifted upward (x10), any time from 0 sec. to 150 sec. can be set with the dial (4).

When the switch (3) is shifted downward (x0.2), any time from 0 sec. to 3 sec. can be set with the dial (4).

Set the acceleration time of this machine to 5 seconds. With the switch (3) at the neutral (x1), set the dial (4) to "5".

## (5),(6) DECEL ..... Deceleration time setting

A switch is used to set the deceleration time of the drive motor. The setting method is the same as that of the acceleration time setting. Set the deceleration time of this machine to 5 seconds. With the switch (5) at the neutral (x1), set the dial (4) to "5".

## (7) Speed control voltage change-over switch

Be sure to set this switch downward (5V) on this machine. If it is set upward (10V), the drive motor speed will be reduced by one half the normal speed.

## (8) TH ..... Variable resistor for the electrothermal relay setting

This inverter contains an electrothermal relay. The setting value is adjusted with this variable resistor.

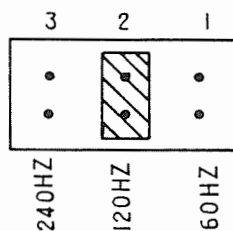
Be sure to set the variable resistor to its 100% position as the motor (1.5kW) for this machine is driven by a 1.5kW inverter.

Never turn the variable resistor fully clockwise as the electrothermal relay will malfunction.

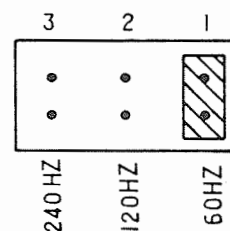
## (9) Changing the maximum output frequency

A frequency from 6Hz to 120Hz can be used on this machine by connecting the jumper wire at the center. For the Ryobi 500K and the 500K-NP the frequency is from 6Hz to 60Hz. When replacing the part, please be sure that the jumper wires are correctly mounted.

[For the Ryobi 3302M  
and Itek 3985]

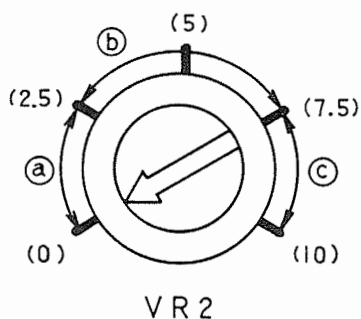


[For the Ryobi 500K  
and 500K-NP]



## (10) The adjustment of the automatic torque boost

This functions to automatically correct the output voltage depending on the load to improve the motor torque. The correction volume of the output voltage can be adjusted by the torque boost adjustment volume (VR2). The location of this VR2 is almost in the center of the printed circuit board and can be adjusted after removing the inverter cover (fixed with two screws). The relationship between the VR2 adjustment position and the VR2 voltage correction volume is shown in the list below.



## ° Length (a)

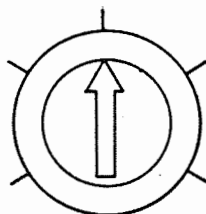
When the automatic torque boost does not actuate. Therefore, the output voltage will remain fixed regardless of the load.

## ° Length (b), (c)

The automatic torque boost actuates. When the more the VR2 is turned in the clockwise direction, the output voltage will be increased. However, at the length (c), despite the adjustment position, the output voltage will stay the same as the "7.5" position on the scale.

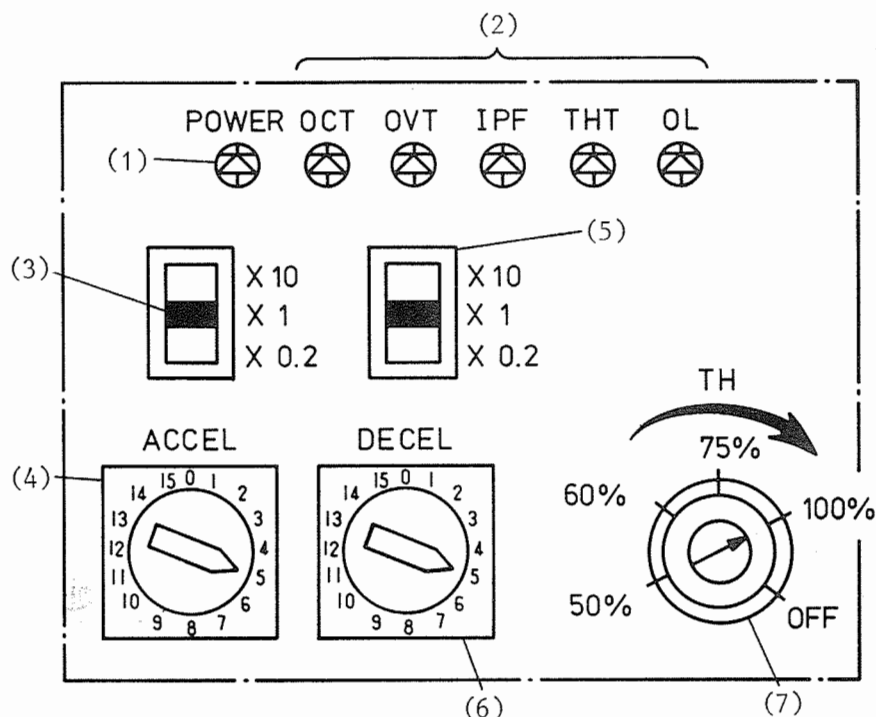
When the automatic torque boost is greatly increased, it may cause too high a voltage to be supplied, which will actuate the protective circuit to protect the inverter, so please be careful.

The VR2 has been adjusted to the position shown in the illustration at the factory.



## (4) Inverter adjustment (For the machines after #1132)

## 1) Setting panel



- Power ..... (1) Power lamp

When a 3 phase or a single phase power source is supplied to the inverter, this LED lights up.

- OCT, OVT, IPF, THT, OL ..... (2) Warning lamps

The inverter incorporates the self-protection function against the overcurrent and the overvoltage. When it actuates, the lamp lights and the drive motor stops. For more information of the OCT, OVT, IPF, THT, OL, please see the pages 27, 28 and 29.

- ACCEL ..... (3), (4) Acceleration time setting

A switch is used to set the acceleration time of the drive motor. The multiplying factor is set with the switch (3) and the time with the dial (4). Set the acceleration time to 5 seconds. With the switch (3) at the neutral ( $\times 1$ ), set the dial (4) to "5".

- DECEL ..... (5), (6) Deceleration time setting

A switch is used to set the deceleration time of the drive motor. The multiplying factor is set with the switch (5) and the time with the dial (6). Set the deceleration time to 5 seconds. With the switch (5) at the neutral ( $\times 1$ ), set the dial (6) to "5".



- TH ..... (7) Variable resistor for the electrothermal relay setting

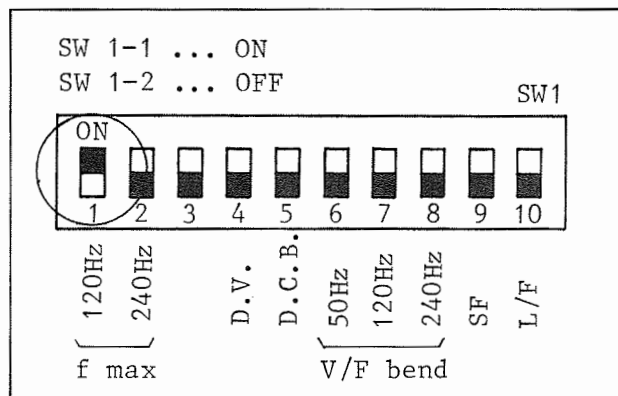
This inverter contains an electrothermal relay. The setting value is adjusted with this variable resistor.

Be sure to set the variable resistor to its 100% position. Never turn the variable resistor fully clockwise as the electrothermal relay will malfunction.

## 2) Frequency setting

The frequency setting switch is used to set the maximum frequency. (Maximum frequency ( $f_{max}$ ) is 120Hz) when the inverter is shipped as a replacement part, the switch is set at 60Hz, so be sure that the switch is set to match the machine it is mounted on.

NB: Do not touch the other switches (2-10).

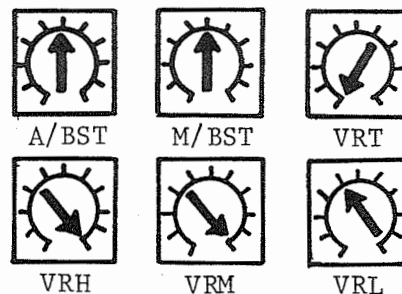


## 3) Other setting volumes.

- Automatic torque boost adjustment volume (A/BST) ..... (1)

This functions to automatically correct the output voltage depending on the load to improve the motor torque. The volume is set at the 12 o'clock position.

Do not touch this volume.

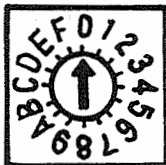


• Manual torque boost adjustment volume (M/BST) ..... (2)

A clockwise turn increases the motor torque. When the volume is greatly increased, vibration and noise may increase and the electric thermal relay (THT) or overcurrent trip (OCT) may be activated during the low-frequency operation. The volume is set at the 12 o'clock position when adjusted at the factory. Adjust this volume only when the motor torque is insufficient.

NB: The other volumes are set as shown in the illustration. Do not touch the other volumes.

4) PWM mode selection dial



This dial can change the motor noise and sound, and the resonant point of the vibration. This volume is usually set at "0". Adjust this dial when the gear noise problem occurs.

NB: The "0" position is the standard setting position.

## [Reference]

OCT, OVT, IPF, THT, OL ..... (2), (7) Warning lamps

Protective functions are incorporated to protect the inverter from overcurrent and overvoltage. When the protective function is activated, the motor comes to a stop after free running. To restart the motor, it is necessary to push the machine stop button or to perform reset by putting on the input power source after shutting it off.

	Problem and cause	Actions to be taken
Overcurrent stall prevention	When current of 150% or more of inverter rated current flows in the motor during the acceleration of motor by the inverter, this function stops the rise of frequency until load current reduces to prevent the inverter from resulting in overcurrent trip. Also, when overcurrent of 150% or more of rated current flows during steady (constant-speed) operation, this function reduces frequency until load current reduces to prevent the inverter from resulting in overcurrent trip. When load current has reduced below 150%, this function increases frequency again and permit acceleration to be continued up to preset frequency.	<input type="checkbox"/> OL lamp flickers.
Regenerative overvoltage stall	When the output voltage of converter rises to over the predetermined value by regenerative energy during deceleration of the motor, this function stops the fall of frequency until the voltage of the capacitor (across terminals P and N) reduces to less than the predetermined value in order to prevent the inverter from resulting in overvoltage trip. As soon as regenerative energy has reduced, this function decreases frequency again to allow deceleration to be continued.	<input type="checkbox"/> OL lamp flickers.

	Problem and cause	Actions to be taken
Overcurrent shut off (OCT)	This function detects the DC current of converter. When overcurrent of 200% or more of inverter rated output current occurs, protective circuit is activated to stop the inverter.	<b>OCT</b> lamp is lit. (Possible causes of OCT are short on the inverter output side, ground fault, excessive load, extremely short setting of acceleration time, start during free running of motor, motor larger than inverter rating, start of special motor, etc. Therefore, restore the circuit after fully examining the cause of trouble.)
Regenerative overvoltage shut off (OVT)	When converter output overvoltage is caused by regenerative energy from the motor, protective circuit is activated to stop the output of transistor and keep it stopped.	<b>OVT</b> lamp is lit. (Cause of OVT include short setting of deceleration time.)
Instantaneous power failure protection (IPF)	When instantaneous power failure occurs for 15m sec or longer (this applies also to the shut off inverter input power source), instantaneous power failure protective function is activated to stop the output of inverter and keep it stopped. In the case of light load, normal operation can be continued up to approximately 100m sec, although it depends on loads. When power failure continues about 10-20 sec, the error alarm is restored to reset state due to the loss of power. When the power is restored 100m sec or later, the protective function is automatically reset. (When the power failure has occurred within 15m sec, or in the case of light load, when the power failure has occurred for about 100m sec, normal operation is performed.)	<b>IPF</b> lamp is lit.
Power source under-voltage protection (IPF)	When the line voltage of inverter is reduced, the control circuit cannot provide normal functions and malfunctions result, such as heat generation of the motor and insufficient torque. Therefore, when the line voltage is reduced to less than 150V, the protective circuit is activated to stop the output of transistor and keep it stopped.	<b>IPF</b> lamp is lit. (Line voltage tends to reduce when the capacity of power source is insufficient or another machine with a large-capacity motor connected to the same circuit is started. Check the power source system.)

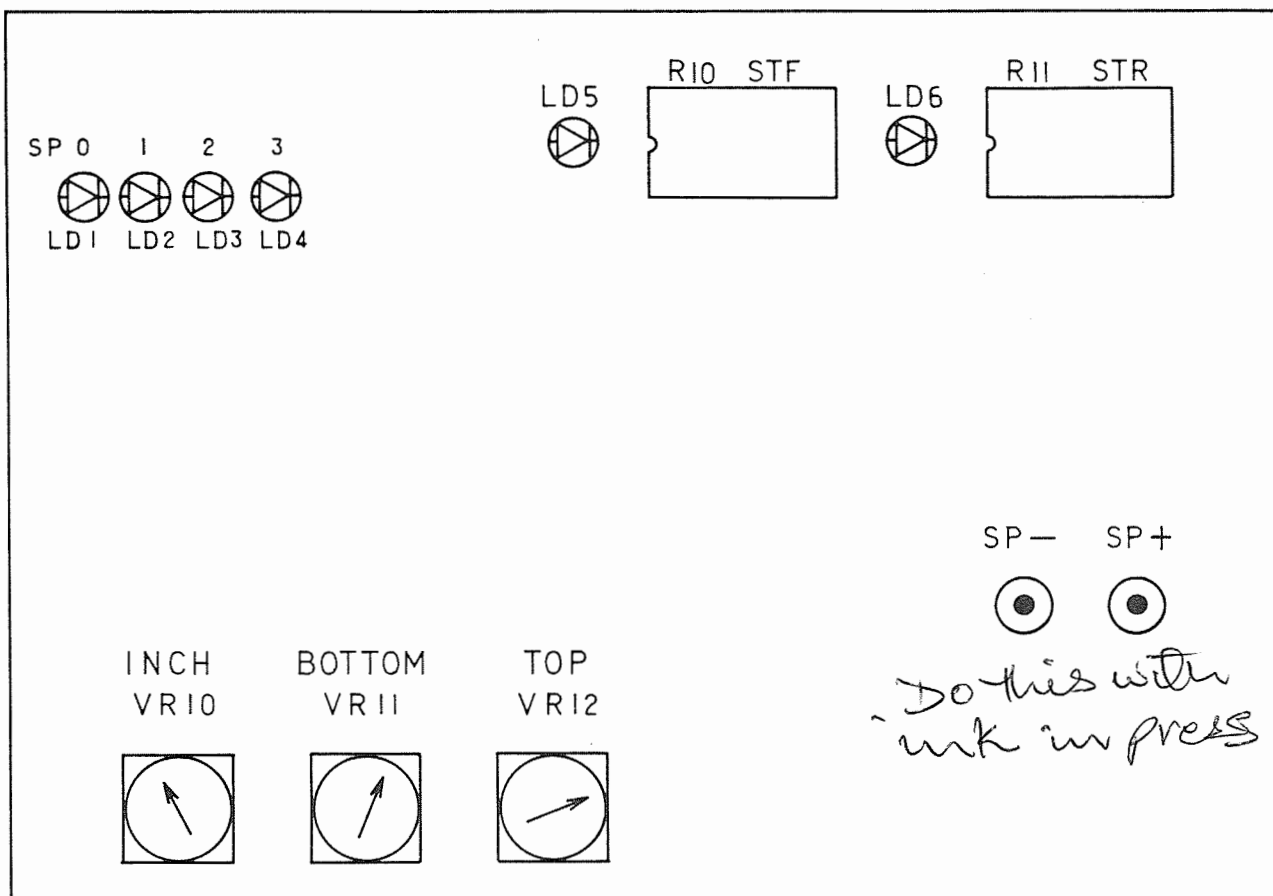
	Problem and cause	Actions to be taken
Overload shut off (Electronic thermal relay) (THT)	Electronic thermal relay detects overload of motor during operation in rated conditions or motor overheating in low-speed operation and protective circuit is activated to stop and protect the inverter output. When a special motor or 2 or more motors are operated, the motor cannot be protected by the electronic thermal relay. Provide a thermal relay on the output side of inverter. In this case, if the electronic thermal relay is set to OFF position, only the transistor protection is activated.	<b>THT</b> lamp is lit. (Examine the cause or overload, and lighten load, change operation pattern, or reconsider inverter and motor capacities.)
Overload alarm (OL)	When motor is overloaded and inverter output current exceed 150% of rated current, the overload alarm (OL) lamp is lit. When the current is reduced to less than 150%, the lamp is turned off. Since the OL lamp detects and indicates an overload state before tripping occurs by overcurrent or overvoltage, it acts as an error alarm.	<b>OL</b> lamp flickers. (If the OL lamp flickers during acceleration or deceleration, set the acceleration or deceleration time longer. If it is activated during constant-speed operation, lighten load or reconsider inverter and motor capacities.)
Fin overheat protection (OVT/THT)	The inverter performs forced cooling with built-in fan. When the cooling fin of semi-conductor is overheated due to the failure of fan, temperature sensor is activated to stop the inverter output and keep it stopped.	<b>OVT</b> and <b>THT</b> lamps are lit at the same time. (Check cooling fin and ambient temperature and also check for obstacle in the way of air.)
Self-diagnosis trip (OCT/THT)	This function monitors if the CPU for control inside the inverter is always operating normally. Since control error results in motor overcurrent and insufficient torque, the protective circuit is activated to protect the inverter. This function is also activated when misoperation, such as the setting change of the maximum output frequency, occurs during operation.	<b>OCT</b> and <b>THT</b> lamps are lit at the same time. (The control circuit may have malfunctioned due to external noise, from another machine etc. Perform reset and check conditions. If this occurs frequently, fully check if noise has entered peripheral circuit.)

## 6. Inverter control board

The inverter control board sends the normal rotation, reverse rotation, stop, inching, and the speed setting signals to the inverter based on the signal from the CPU board.

### (1) Normal rotation and reverse rotation signals

When the R10 turns ON, the drive motor will rotate normally and when the R11 turns ON, the drive motor will rotate reversely. Check the movement of the R10 and the R11 by using the LD5 and the LD6.



### (2) Speed adjustment

#### a) 1,000rph and inching speed

The 1,000rph speed and the inching speed adjustment is done by using the VR10. When turning the VR10 in the clockwise direction, the speed will be increased and when turning it in the counterclockwise direction, the speed will be reduced.

#### b) 3,000rph

The 3,000rph speed adjustment is done by using the VR11. When turning the VR11 in the clockwise direction, the speed will be increased and when turning it in the counterclockwise direction, the speed will be reduced.

## c) 10,000rph

The 10,000rph speed adjustment is done by using the VR12. When turning the VR12 in the clockwise direction, the speed will be increased and when turning it in the counterclockwise direction, the speed will be reduced.

## (3) The speed setting circuit checking procedures

The inverter control board converts the 4 bit digital signal from the CPU to the voltage signal, and sends this voltage signal to the inverter as the speed setting signal. The digital signal from the CPU is checked by the LD1 through the LD4. The voltage signal to the inverter can be measured by the direct circuit voltage range tester by using the check pins SP- and SP+. It shows the relationship between the machine rotation speed and the digital signal from the CPU board and the voltage signal to the inverter below.

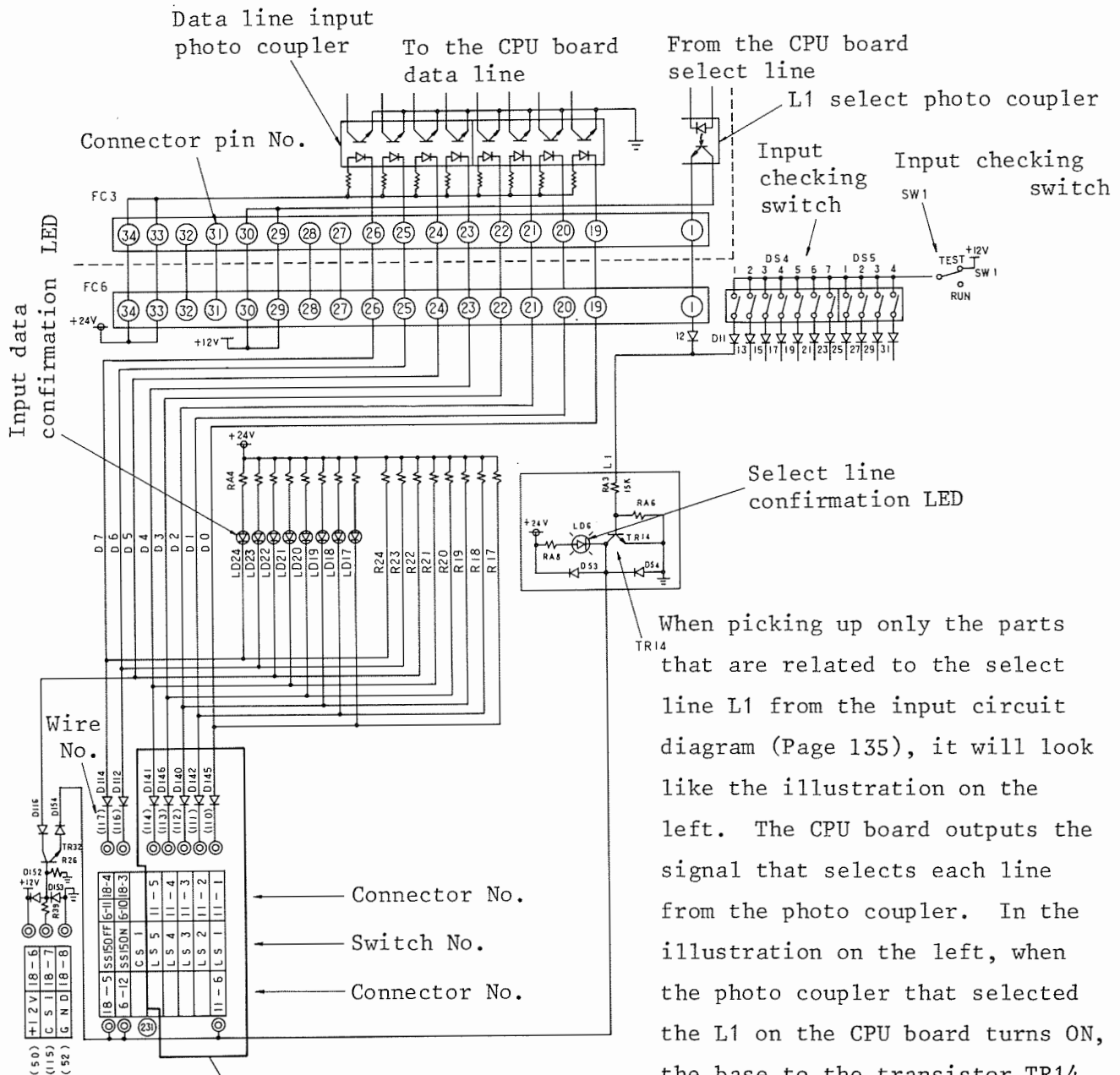
Machine rotation speed	Digital signal from the CPU board				Voltage between SP- and SP+
	LD1	LD2	LD3	LD4	
1000rph and when the machine is stopped	x	x	x	x	0.5V
3000rph	o	x	x	x	1.4V
3500rph	x	o	x	x	1.7V
4000rph	o	o	x	x	1.9V
4500rph	x	x	o	x	2.1V
5000rph	o	x	o	x	2.4V
5500rph	x	o	o	x	2.6V
6000rph	o	o	o	x	2.8V
6500rph	x	x	x	o	3.1V
7000rph	o	x	x	o	3.3V
7500rph	x	o	x	o	3.5V
8000rph	o	o	x	o	3.8V
8500rph	x	x	o	o	4.0V
9000rph	o	x	o	o	4.2V
9500rph	x	o	o	o	4.5V
10000rph	o	o	o	o	4.7V

(Note) x ..... Light off    o ..... Light up

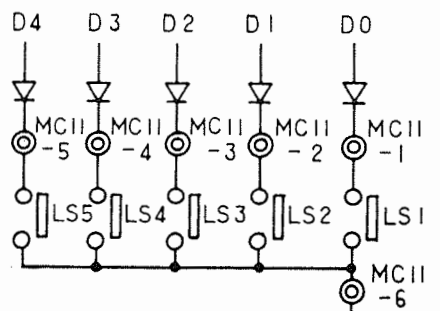




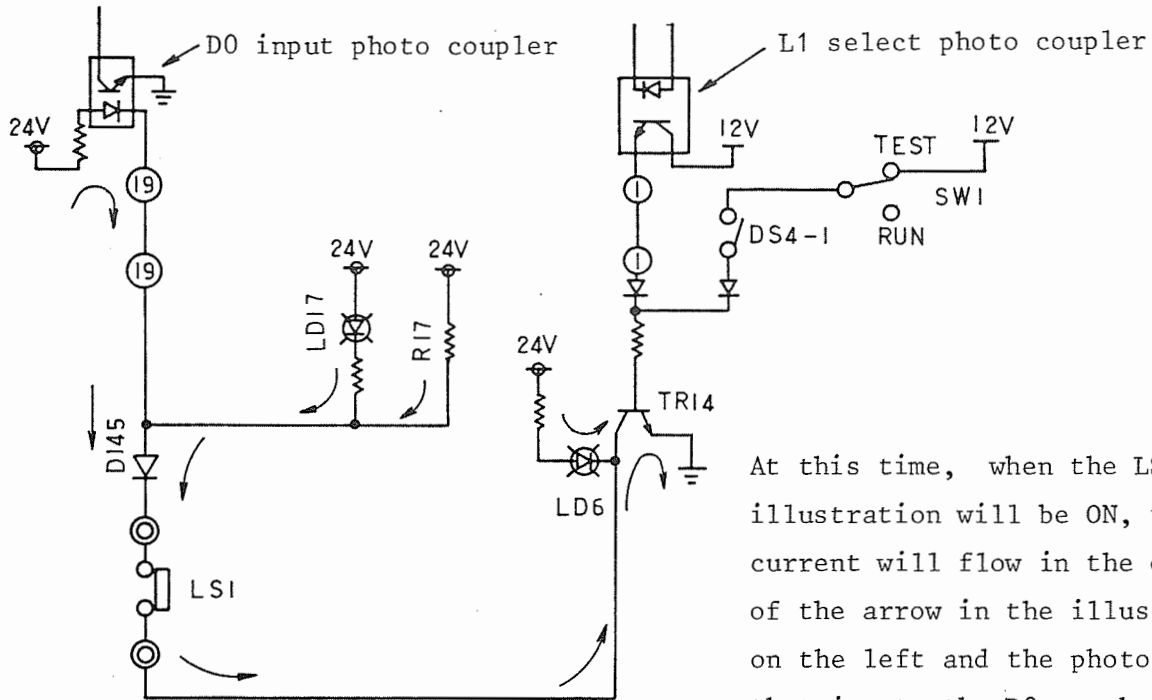
## (2) The matrix system input



The connection of this part show by using another method below.



When picking up only the parts that are related to the select line L1 from the input circuit diagram (Page 135), it will look like the illustration on the left. The CPU board outputs the signal that selects each line from the photo coupler. In the illustration on the left, when the photo coupler that selected the L1 on the CPU board turns ON, the base to the transistor TR14 will be HIGH and the electric current will flow from the TR14 collector and the emitter and the checking LED LD6 will light up. When shifting the SW1 to the TEST side and turning the DS4-1 ON, the same thing will occur.

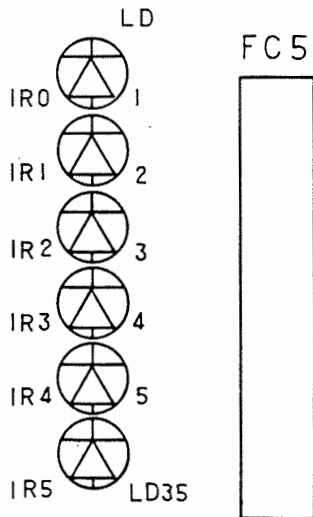


At this time, when the LS1 in the illustration will be ON, the current will flow in the direction of the arrow in the illustration on the left and the photo coupler that inputs the D0 on the CPU board turn ON. Then the CPU is confirmed that LS1 turns ON. At this time, the checking LED LD17 will light up. The L2 through the L11 function the same as the L1. However, the L5 through the L8 are part of the matrix circuit in the main control panel circuit board, therefore see the main control panel circuit board diagram (Page 147).

## 8. The input circuit checking procedure

### (1) The interrupting input system checking procedure

For checking the interrupting input system, the LD1 through the LD5 and the LD35 on the right side of the connector board are used.



#### a) IR0 ... LD1

When the first unit blanket jam sensor (PH3) detects a sheet of paper, the LD1 will light.

#### b) IR1 ... LD2

When the timing switch CS3 turns OFF, the LD2 lights and when the CS3 turns ON, the LD2 light goes off.

#### c) IR2 ... LD3

When the timing switch CS4 turns OFF, the LD3 lights and when the CS4 turns ON, the LD3 light goes off.

#### d) IR3 ... LD4

The IR3 is the signal connected to the output of the CPU board that is used to set the preset number of sheets on the sheet counter by pushing the sheet counter set buttons continuously. Usually the LD4 lights, but when pushing the sheet counter set buttons, the light will go off.

#### e) IR4 ... LD5

When the timing switch CS4 turns ON, the LD5 will light, and when the CS4 turns OFF, the LD5 will go off. (The opposite of the IR2)

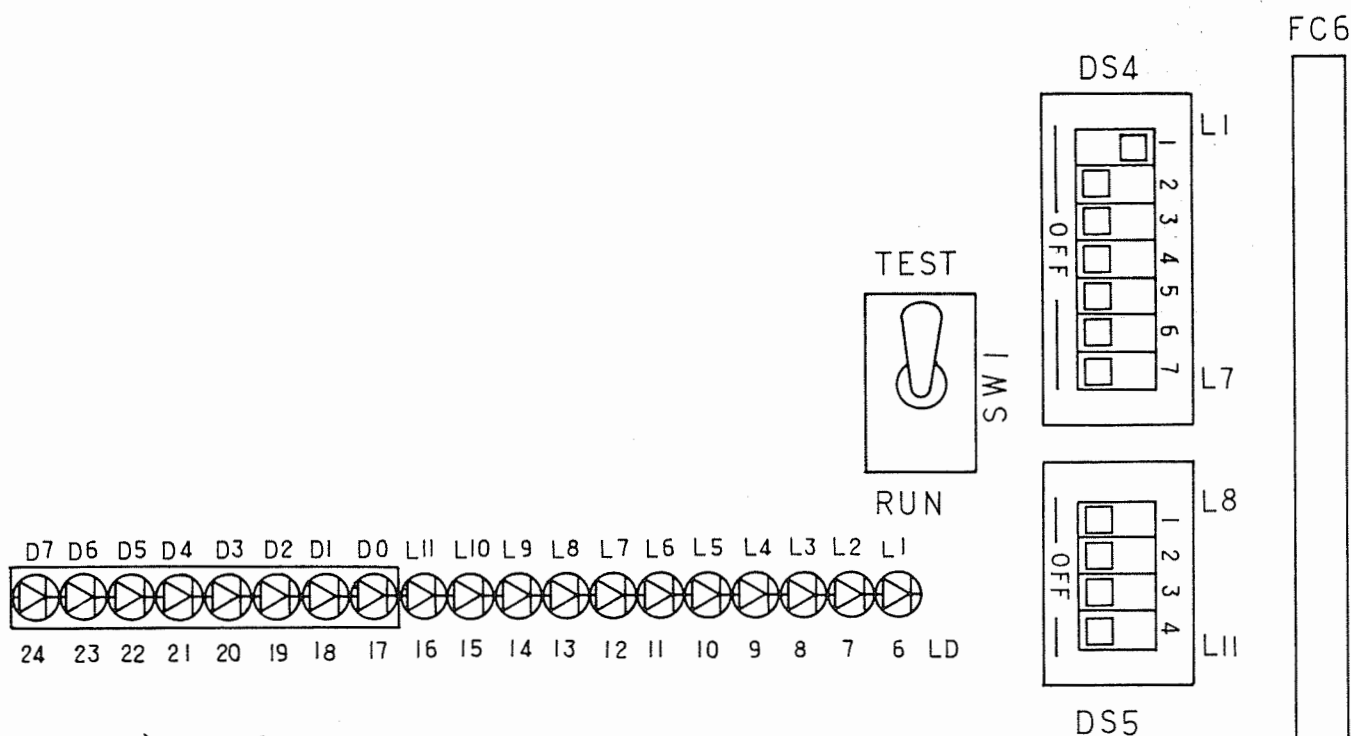
#### f) IR5 ... LD35

When the second unit blanket jam sensor (PH2) detects a sheet of paper, the LD35 will light. This LD35 is not mounted on the machines with the serial numbers from 1001 to 1005.

(Note) The interrupting input system, can be checked by the input checking program too. Please see the input checking program (Page 44).

## (2) Matrix system input checking procedure

The input by the matrix system cannot be checked during the machine operation because the one input line is connected to several switches. The input checking by the matrix system is done by following the procedures. Please refer to the matrix chart (on the back of the control box cover and Page 153).



## a) Procedure

- 1) Set the machine power OFF and remove the flat cable connector FC6.
- 2) Shift the switch SW1 to the TEST side.
- 3) Select the select line of the switch to be checked by the DS4 and the DS5. When the DS4 or the DS5 switch for the select line to be checked is ON, that line will be checked. Only one select line can be checked at a time.
- 4) Turn on the machine.

## b) Checking

- 1) The select line that is selected is shown by the LD6 through the LD16.
- 2) The ON and OFF condition of the switch which is connected to the select line and the data line (D0 ~ D7) is shown by the LD17 through the LD24.

## c) Examples of the checking procedure

The checking of the LS1 through the LS5 operation that inputs the first unit operating lever position.

- 1) By following the procedures given on the previous page, select the select line (L1).
- 2) Check that only the LD6 lights up from the LD6 through the LD16.
- 3) The checking of the LS1 through the LS5 operation is done by using the LD17 through the LD24.

Lever position I .....	LS1	ON .....	LD17 lights up
Lever position II .....	LS2	ON .....	LD18 lights up
Lever position III ....	LS3	ON .....	LD19 lights up
Lever position IV .....	LS4	ON .....	LD20 lights up
Lever position V .....	LS5	ON .....	LD21 lights up

Usually when each input switch is ON, the LD17 through LD21 light up, but please be careful because there are some exceptions.

° SS5 ~ SS8 (Jam ON/OFF switch)

When the switch is set at the OFF position, the LED lights.

° PH1, PH4 (Photo sensor)

When there is a sheet of paper over the sensor, the LED lights.

° PB50, LS52 ~ LS66 (Safety switch)

The switch turns ON, when a safety cover is opened, the LED goes off.

Therefore when the input checking is done, if the LED is not lit, the machine cannot be run.

## d) When operating the machine after the checking procedure

After checking, mount the FC6 after the power is OFF and turn off all the DS4 and the DS5 switches, then set the SW1 to the RUN side.

(Note) The matrix input system, can be checked by the input checking program too. Please see the input checking program (Page 44).

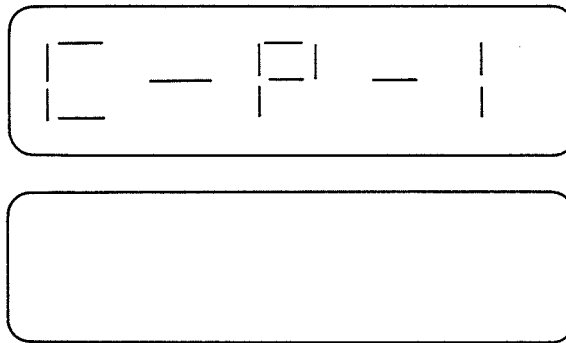
If switch is good you get signal  
If bad no signal

### (3) The input checking program

This machine has input checking programs. Using this program, each input condition to the CPU can be checked easily.

#### a) Procedures

To enter the input checking program, keep pushing the second unit normal rotation inching button and turn on the main power, and C-P-I (Checking Program for the Input) will appear on the sheet counter display as shown the illustration below.



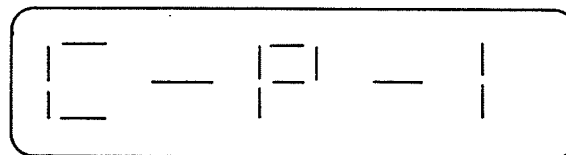
#### b) Confirmation

Turn ON/OFF the switch that you want to check. The ON or OFF switch line number and the data number are indicated and the buzzer sounds. When the line number and the data number are indicated and the buzzer sounds, that switch input to the CPU is OK.

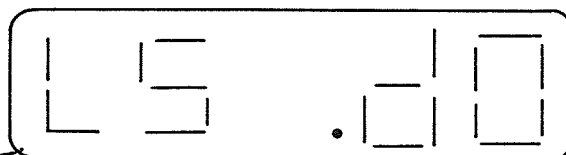
##### ° Example of the matrix system input

When turning the first unit emergency stop button (L5, D0) ON or OFF, it will appear on the sheet counter display as shown the illustration below.

Input Matrix Chart



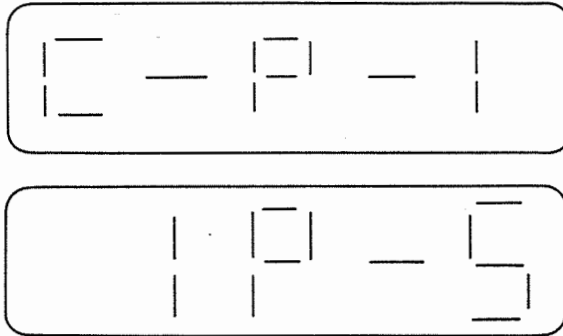
Vertical lines



Horizontal lines

° Example of the interrupting input system

When turning the second unit blanket jam sensor (IR5) ON, it will appear on the sheet counter display as shown the illustration below.

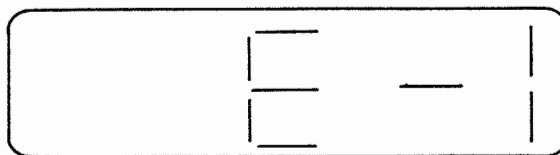


c) After the input checking, when wanting to operate the machine

After the input checking, turn the main power switch OFF once and then turn the power ON, and the machine will return to the normal program.

## 9. Error Indication

This machine has a program that gives an error code when something unusual occurs. The error code E-1 through E-5 will appear on the sheet counter display as shown the illustration below.



### (1) E-1 code ..... The first unit operating lever

When something unusual occurs on the switches (LS1 ~ LS5) that inputs the first unit operating lever position, E-1 code will appear.

The list below shows the problems:

- a) All the LS1 through LS5 switches are OFF when the main power switch is turned ON.
- b) More than two of the LS1 through LS5 switches are ON when the main power switch is turned ON.
- c) When more than two of every other switch are turned ON.  
(Example) The LS1 and the LS3 switches are ON.
- d) When the lever is shifted, the lever skips the next position and it is detected.

(Example) The lever shifts from the I position to the III position and it is detected.

In the case of a) and b), if the LS1 through the LS5 switches become normal, the E-1 code disappears.

In the case of c) and d), the E-1 code will not disappear until the power is turned OFF.

### (2) E-2 code ..... The second unit operating lever

When something unusual occurs on the switches (LS21 ~ LS25) that inputs the second unit operating lever position, the E-2 code will appear. Please refer to the E-1 code list above as the E-2 code is the same as the E-1 code.

### (3) E-3 code ..... CS3

When the timing switch CS3 input does not change after the drive motor starts to rotate, the E-3 code will appear. This code will disappear if the CS3 input returns to normal.



(Note) When something unusual occurs on the drive motor output circuit and the drive motor does not rotate, the E-3 code will appear.

(4) E-4 code ..... CS4

When the timing switch CS4 input does not change after the drive motor starts to rotate, the E-4 code will appear. This code will disappear if the CS4 input returns to normal.

(5) E-5 code ..... Matrix input

When something unusual occurs in the input circuit by the matrix, the E-5 code will appear. In the input by the matrix, when all of the select lines (L1 ~ L11) are not selected, the E-5 code will appear even if there is only one input on the data line (D0 ~ D7). When the E-5 code appears, the drive motor cannot be rotated. So when the E-5 code appears, search for the cause by following the next procedures.

(Note) If trouble occurs when turning on the power, the C-P-I or C-P-O may be indicated instead of the E-5 code.

a) When trouble occurs at the data line side on the CPU board

Pull off the flat cable connector FC6 from the connector board and turn the power ON. At this time if the E-1 code appears, the CPU board is normal. At this time if the E-5 code appears, the trouble is with the CPU board, so replace it with a new CPU board.

b) When trouble occurs at the select line side on the CPU board

With the output checking program group 8 (See the output checking program, page 57), check that there is no trouble with the select lines. If any one of the LD6 through LD16 are always lit, it is unusual. If they are always lit up, pull off the flat cable connector FC6. Then if all those LED lights go off, the trouble is on the CPU board, so replace it with a new CPU board.

If the LED lights do not go off even after pulling off the FC6, the trouble is on the connector board or the cord to any outside switch.

- c) When trouble occurs on the connector board or the cord to any outside switch

When the trouble falls under a) and b), either the connector has trouble or the cord to any outside switch is contacting the machine frame. In this case, check by following the next procedures.

Pull off the flat cable connector FC6 on the connector board and turn the power ON. At this time, check that either the select line checking LEDs (LD6 ~ LD16) or the data line checking LEDs (LD17 ~ LD24) do not light. If any one or all of them is lit, it is unusual. In this case, pull off all of the connectors except the MC1 and the MC12 on the connector board. When pulling off the connectors, if the light goes off on the LED that was lit, this cord is contacting the machine frame.

If the LED is still lit even with only the MC1 and the MC12 connected, pull off the MC12. At this time if the light goes off on the LED that was lit, the feeder safety cover switch cord that connects the MC12 is contacting the machine frame. If only the MC1 connected and the LED is still lit, the trouble is on the connector board. Replace it with a new connector board. The E-5 code will not disappear until the power is turned OFF.

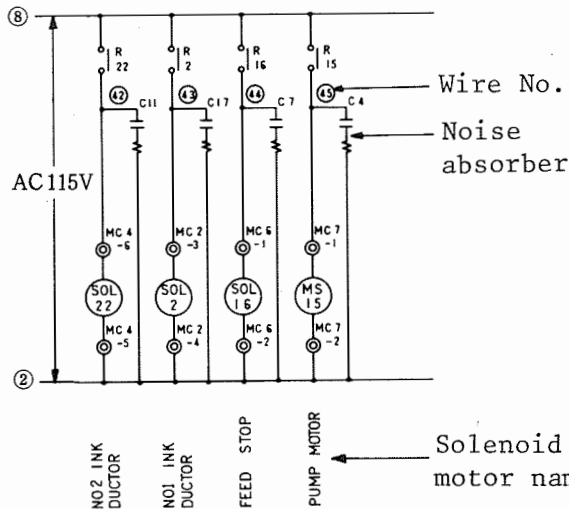
(Reference) The capacitance sensor for lowering the delivery table dolly negative side wire (Wire No. 52) is contacting the sensor body with resistance. Therefore if the switch input line is contacting the machine frame, any one or all of the checking LEDs (LD6 ~ LD24) will light up.

## 10. Output circuit of the connector board illustration

The output signal to the connector board from the CPU board is sent to the connector board through the flat cable connector (FC8).

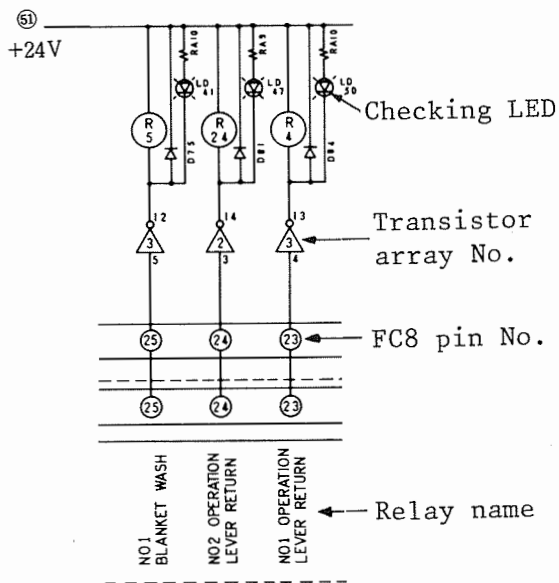
### (1) How to read the output circuit illustration

#### a) Solenoid circuit



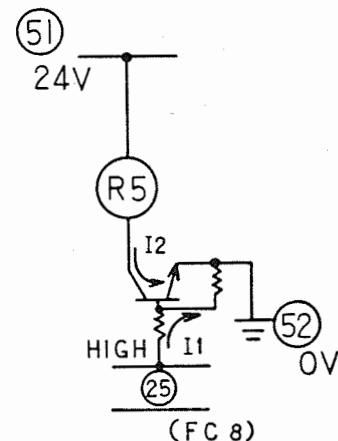
The magnet switch and the solenoid voltage are all AC115V. Noise absorbers are mounted on all of these circuits.

#### b) Relay circuit



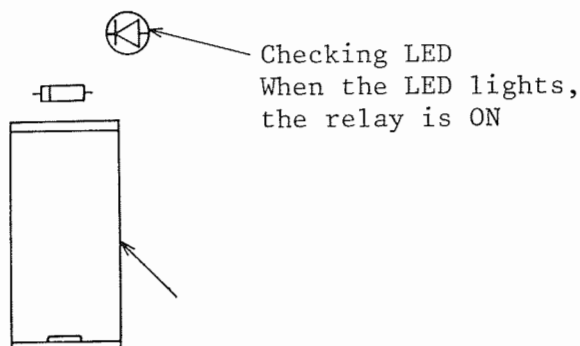
The signal that is outputted from the CPU board photo coupler passes through the FC8 and is inputted into the connector board, and actuates the transistor array to operate the relay. The transistor array is the one that has several transistors on one IC. Therefore when using the transistor and changing the R5 circuit, it will look like the illustration below.

As shown in the diagram on the right, when the HIGH signal is sent to the number 1 pin on the flat cable connector (FC8) from the CPU board, the relay R5 starts to actuate.

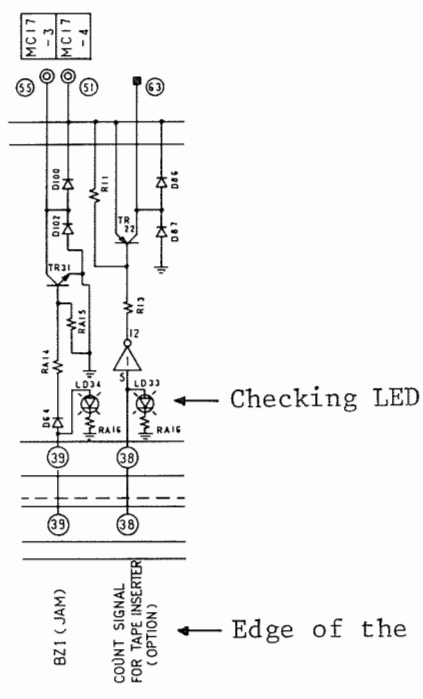


## &lt;Relay operation checking procedure&gt;

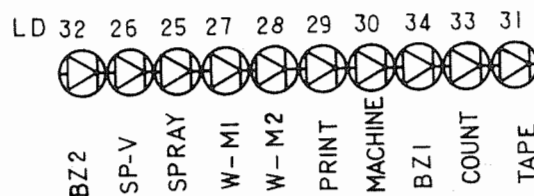
The operation checking LEDs are mounted on all the relays. Check the relay operation using these LEDs.



## c) Transistor output



The following output signals are outputted by the transistor from the connector board. For these output signals, the checking LEDs are mounted on the connector board. The output signal from the CPU is checked by these LEDs.



## ° LD32 (BZ2)

When the LD32 lights up, the main control panel buzzer BZ2 sounds.

## ° LD26 (Spray valve)

When the LD26 lights up, the spray valve turns ON.

## ° LD25 (Spray pump)

When the LD25 lights up, the spray device motor turns ON.

° LD27, LD28

The LD27 and the LD28 will not light up on this machine.

° LD29 (Print counter)

When the LD29 lights up, the print counter will add one.

° LD30 (Machine counter)

When the LD30 lights up, the machine counter will add one.

° LD34 (BZ1)

When the LD34 lights up, the buzzer BZ1 on the delivery control panel will sound.

° LD33 (Count)

When the LD33 lights up, the tape inserter count signal will be outputted.

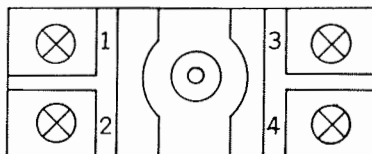
° LD31 (Tape inserter)

When the LD31 lights up, the tape inserter output signal will be outputted.

(2) The machine counter and the print counter

The machine counter and the print counter are powered by a battery.

Therefore even when the main power is turned off, the indicator is continuously ON. The life of this battery is approximately seven years but the battery itself cannot be replaced. When the battery is dead, the whole counter must be replaced.



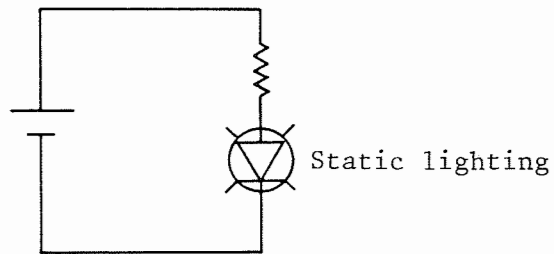
These counters can work by connecting the No.1 and the No.2 terminals together without supplying voltage from an outside source. If connecting the No.3 and the No.4 terminals together, the counter will be reset to 0.

### 11. Display control circuit

With the signal from the CPU board, the display control circuit controls the main control panel LED indication, all of the inching panel push button switch lamps indication and all of the sub control panel push button switch lamps indication. For the LED lighting system, there are two types, the static lighting system and the dynamic lighting system.

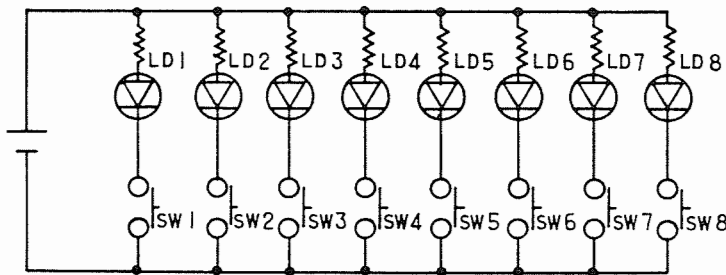
#### ° Static lighting system

The static lighting system is an ordinary lighting system and this system is continuously lights up the LEDs.



#### ° Dynamic lighting system

To the human eye, there is a flicker response characteristic. When the flickering frequency reaches a fixed rate, the human eye cannot see the flickering and it seems that the light is continuously lit.



The SW1 through SW8 go on in order rapidly. As each switch goes on, it lights its LED. As the switches go on rapidly, to the human eye it seems that all the LEDs light at once.

On this machine, the 8 LEDs light up in order and is done using dynamic lighting. The human eye, can see all the 8 LEDs light up at the same time, however they light up one at a time in order. This machine's display control circuit uses the 8 static lighting circuits and the 16 x 8 dynamic lighting circuits.

### (1) Static lighting circuit

The static lighting circuits are the TR1 through TR8 in the display control circuit output section diagram (Page 145). When the TR1 through TR8 turn on, the PL1 through the LD4 light up at the same time.

On the static lighting circuit, the checking LEDs (LD1 ~ LD8) are mounted on the display control circuit board, therefore please check this circuit board using these LEDs.

- ° LD1 ... PL1

When the LD1 lights up, the first unit emergency stop button lights up.

- ° LD2 ... PL2

When the LD2 lights up, the first unit ON/OFF lamp lights up.

- ° LD3

On this machine, the LD3 does not light up.

- ° LD4 ... LD2, PL5

When the checking LD4 lights up, the lubrication warning lamp on the main control panel and the lubrication warning reset button lamp on the sub control panel light up.

- ° LD5 ... PL21

When the LD5 lights up, the second unit emergency stop button lamp lights up.

- ° LD6 ... PL22

When the LD6 lights up, the second unit ON/OFF lamp lights up.

- ° LD7

On this machine, the LD7 does not light up.

- ° LD8 ... LD3, PL4

When the checking LD8 lights up, the pump filter cleaning warning lamp on the main control panel and the pump filter cleaning warning reset button lamp on the sub control panel light up.

(2) Dynamic lighting circuit

The TR9 through the TR24 in the display control circuit output section diagram (Page 145) are the transistors for the dynamic lighting data output. Also, the TR25 through the TR32 are the transistors for the dynamic lighting line output. The TR25 through the TR32 turn on one at a time from the TR25 very rapidly.

The TR25 (Wire No. 351) is connected to the LD33 and the LD41 on the main control panel (See the main control panel circuit board diagram, Page 128). When the TR25 is ON, at the same time the LD33 and the LD41 data is sent from the TR9 through the TR24 (Wire No. 360 ~ 377). At this moment, only the LD33 and the LD41 light up. The next moment, the TR26 will go on.

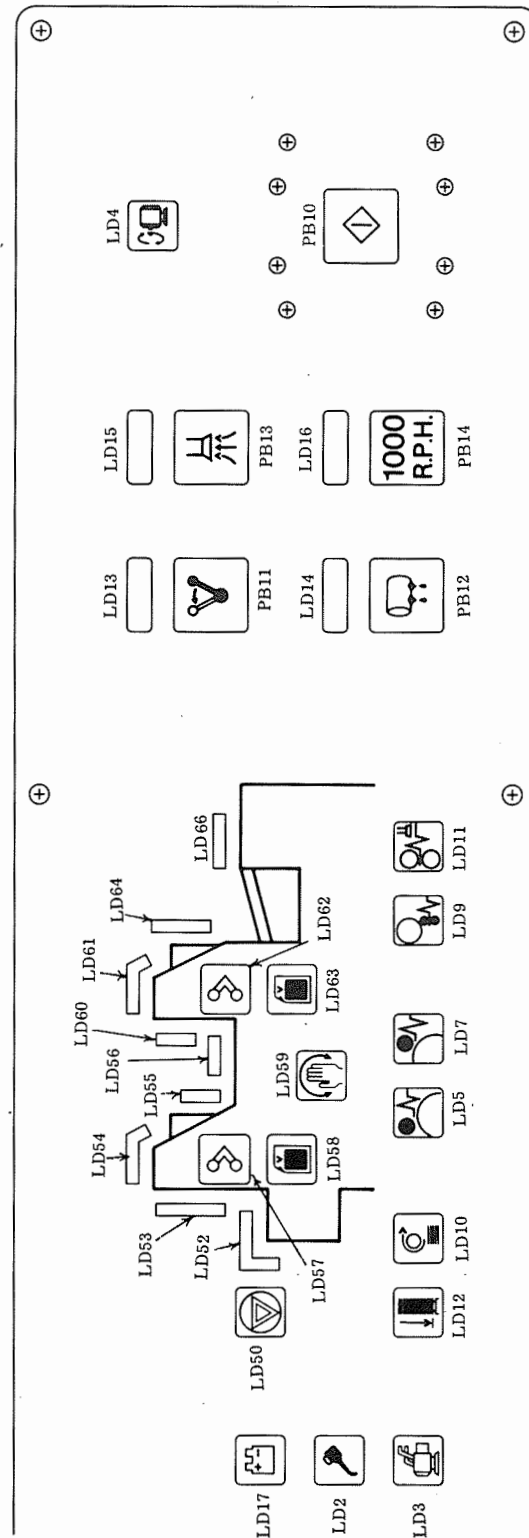
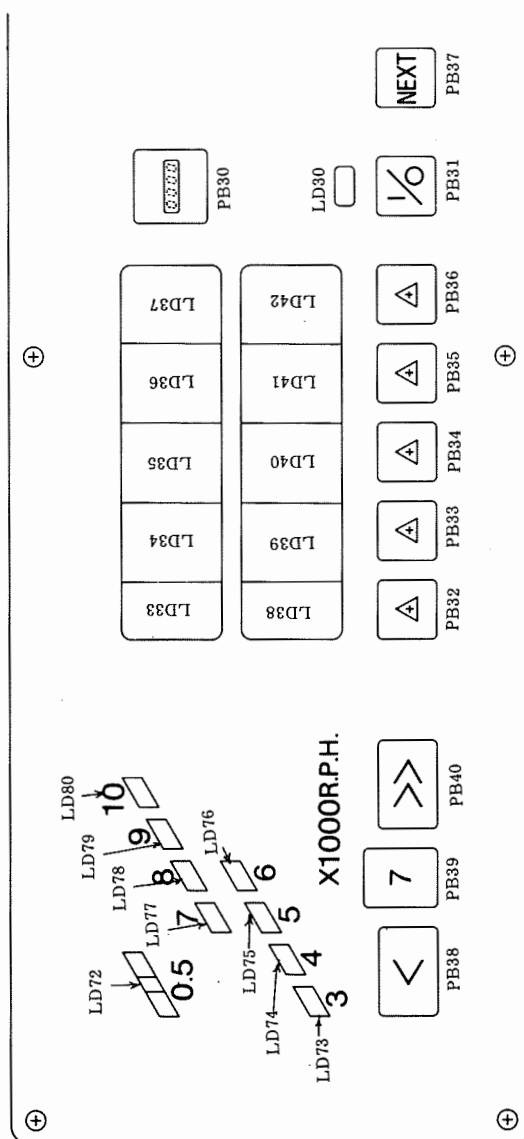
The TR26 (Wire No. 352) is connected to the LD34 and the LD42 on the main control panel. When the TR26 is ON, at the same time the LD34 and the LD42 data is sent from the TR9 through the TR24 (Wire No. 360 ~ 377). At this moment, only the LD34 and the LD42 light up.

The TR27 through the TR32 function the same way. Therefore, when the dynamic lighting circuit on the display control circuit board is damaged, all of the LEDs that are connected to that data or line will be affected. If all of the LEDs connected to the data and/or line do not light, replace the display control circuit board.



## 12. Main control panel circuit board

The main control panel circuit board is connected to the connector board and the CPU board. For more details, please refer to the connector board input circuit diagram (page 135) and the display control circuit output section diagram (page 145).



### 13. Output checking program

This machine has output checking programs. It is used to check the circuits, for example the solenoid and the motor. The output checking program on this machine is divided into 8 groups, the group 1 through group 8. So each section listed below can be checked individually.

Group 1 ~ 4 ... Used for checking each indication on the main control panel.

Group 5 ..... Used for checking the solenoids, the pump motor, and the spray device on the operation side.

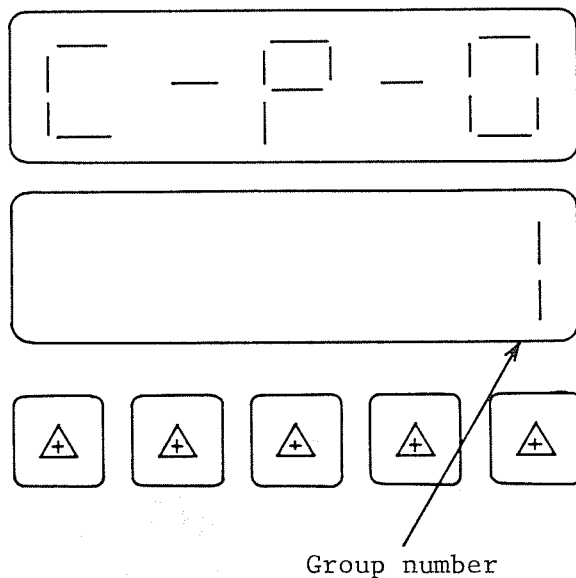
Group 6 ..... Used for checking the solenoids on the non operation side.

Group 7 ..... Used for checking the inverter control circuit board.

Group 8 ..... Used for checking the input matrix select lines and the tape inserter.

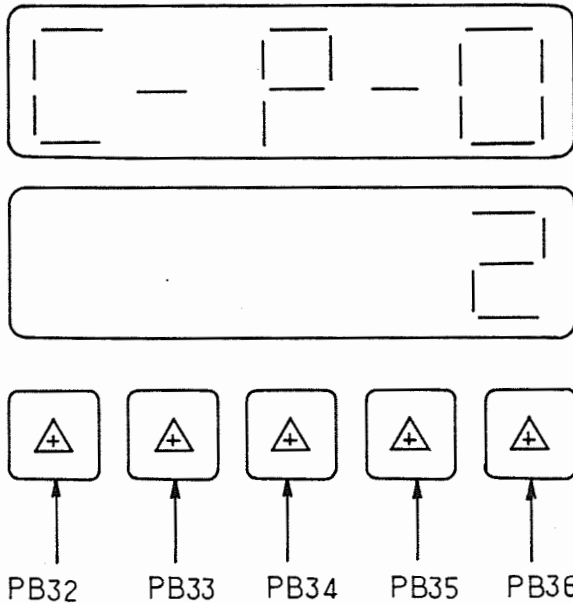
#### (1) Output checking program procedures

##### a) When inputting the output checking program



To enter the output checking program, keep pushing the second unit reverse inching button and turn on the main power and the C-P-O (Check Program for Output) will appear on the sheet counter upper display and the group number will be shown on the sheet counter lower display. With the power ON, the group number 1 is indicated and the group 1 output checking will be done.

## b) To change the group number



When pushing any one of the set buttons (PB32 ~ PB36) on the sheet counter, the group number for the output checking program will be advanced. However depending on the timing when pushing any one of the PB32 through PB36, the group number may not change at first, therefore keep pushing the button until the group number changes.

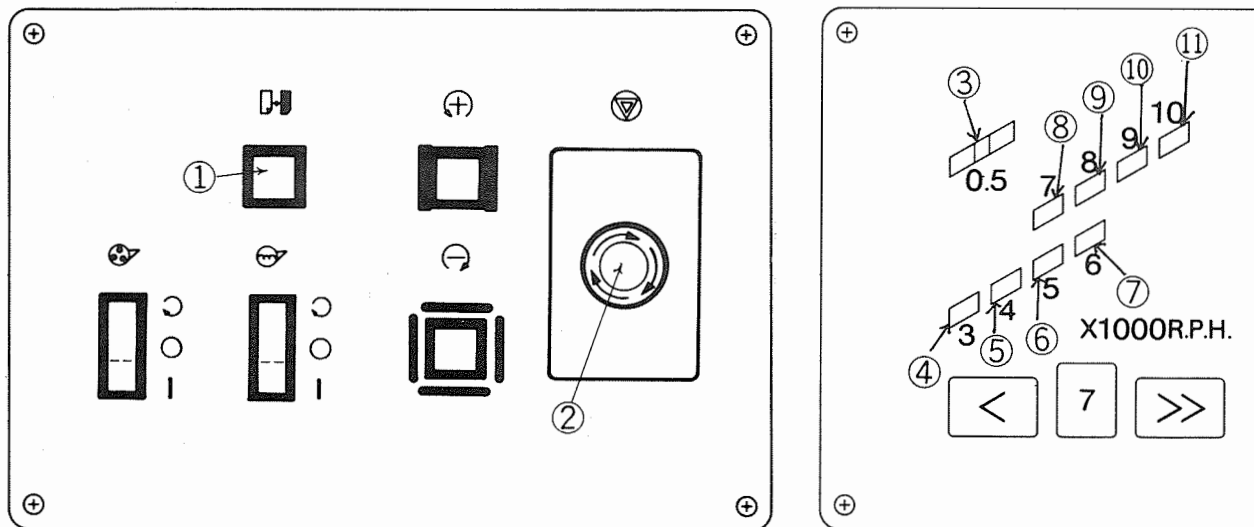
## c) Output checking procedure

First select the solenoid or LED group number that needs to be checked. The output checking program will be on the LED or the solenoid and check each one in order. If the LED or the solenoid do not go on, check the circuit by using the output circuit diagram.

## d) When finishing the output checking program

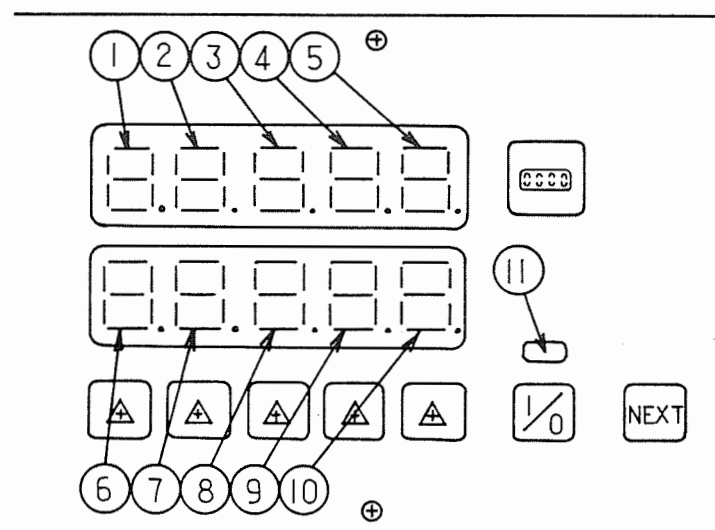
When finishing the output checking program, turn the main power switch OFF.

## (2) Group 1



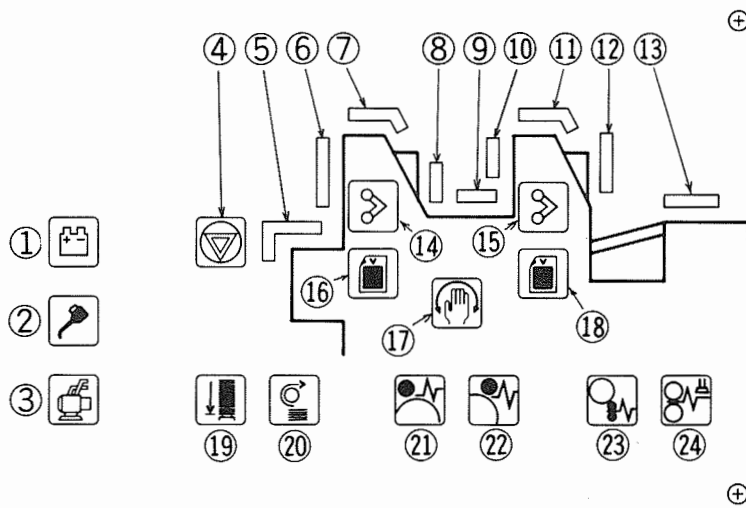
The second unit inching control panel and the speed indicator section on the main control panel light up one at a time.

## (3) Group 2



The sheet counter section on the main control panel lights up in order shown in the illustration on the left.

## (4) Group 3

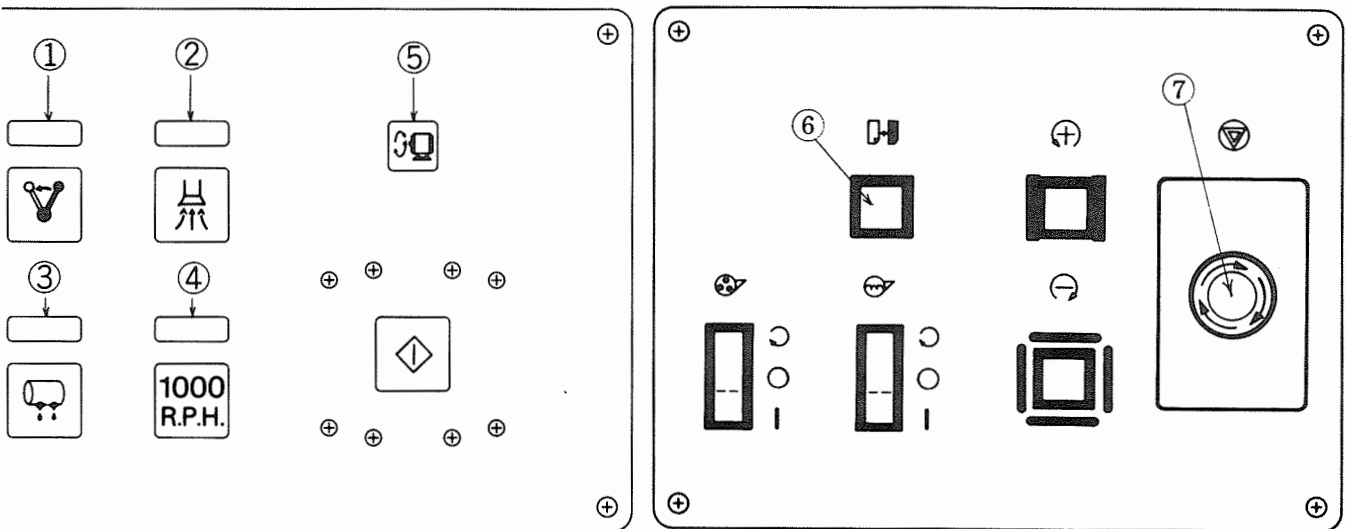


The OK monitor section on the main control panel lights up in order shown in the illustration on the left.

(Note)

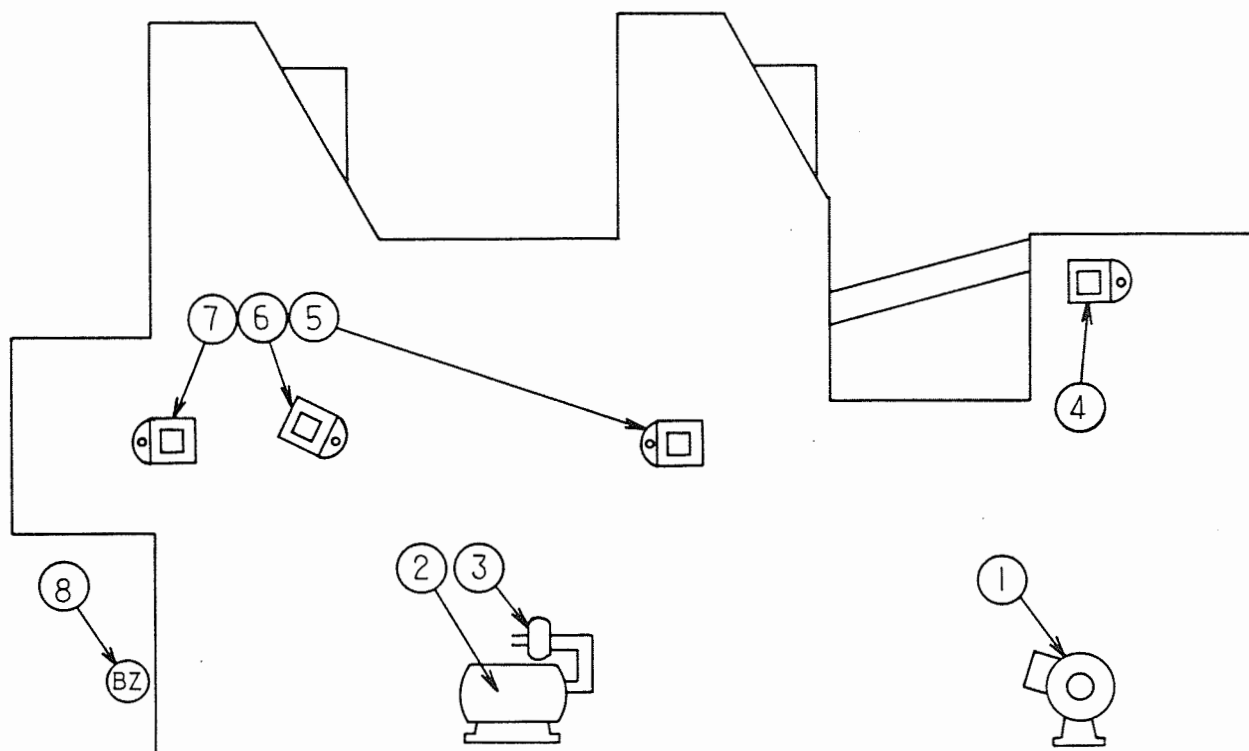
Each reset button lamp on the sub control panel lights up at the same time when (2) and (3) above are checked.

## (5) Group 4



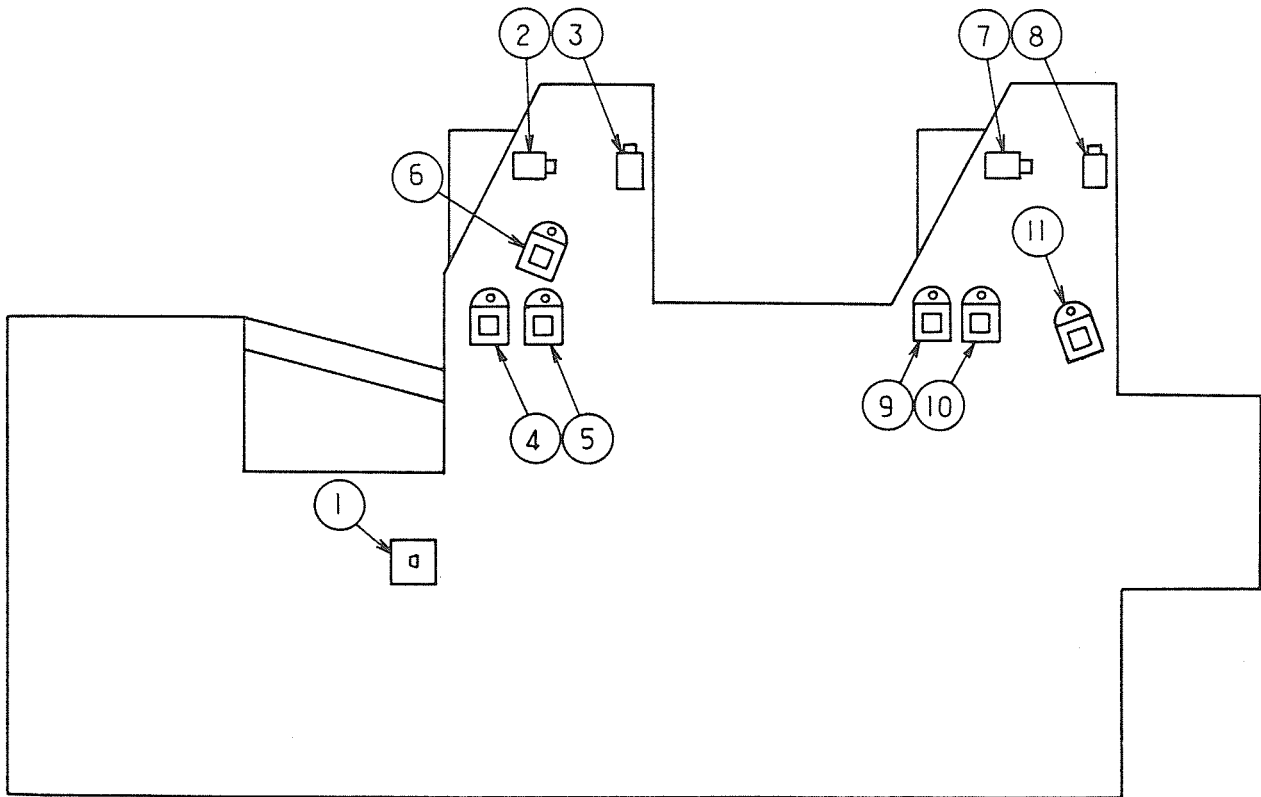
The upper indication section on the main control panel and the indication section on the first unit inching control panel light up one at a time.

## (6) Group 5



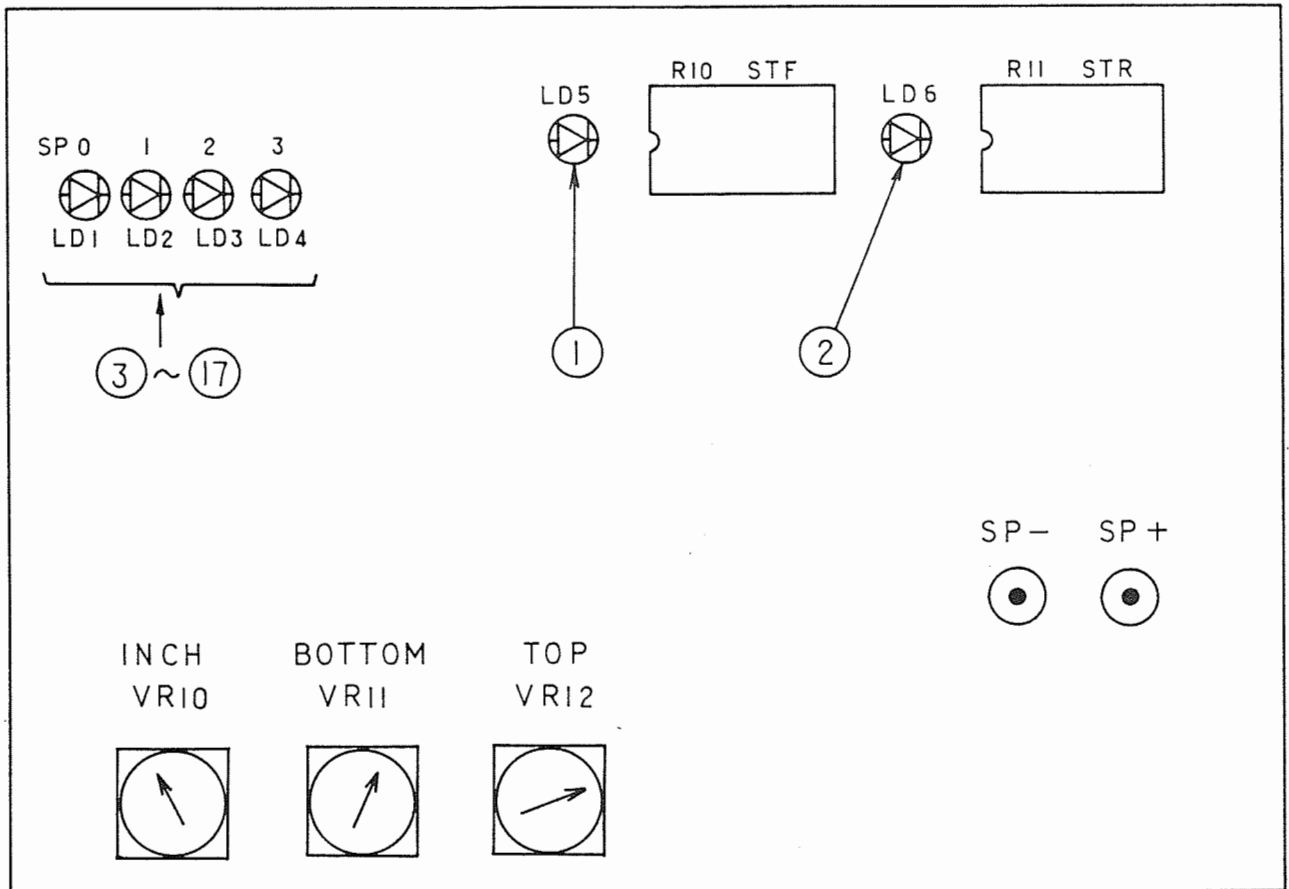
- 1) The pump motor will turn ON.
- 2) The spray device motor will turn ON.
- 3) The spray valve will turn ON.
- 4) The feed OFF solenoid will turn ON.
- 5) The first unit cylinder ON solenoid will turn ON.
- 6) The second unit cylinder ON solenoid will turn ON.
- 7) The delivery table dolly lowering solenoid will turn ON.
- 8) The paper jam buzzer will sound.

(7) Group 6



The solenoids on the non operation side will turn ON in order shown in the illustration above.

## (8) Group 7 (Inverter control circuit)

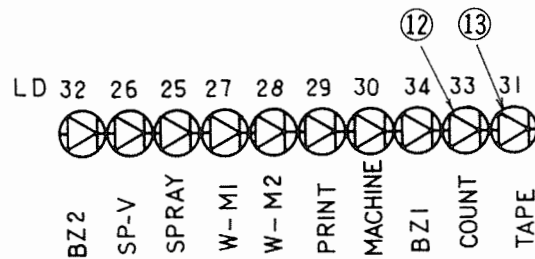
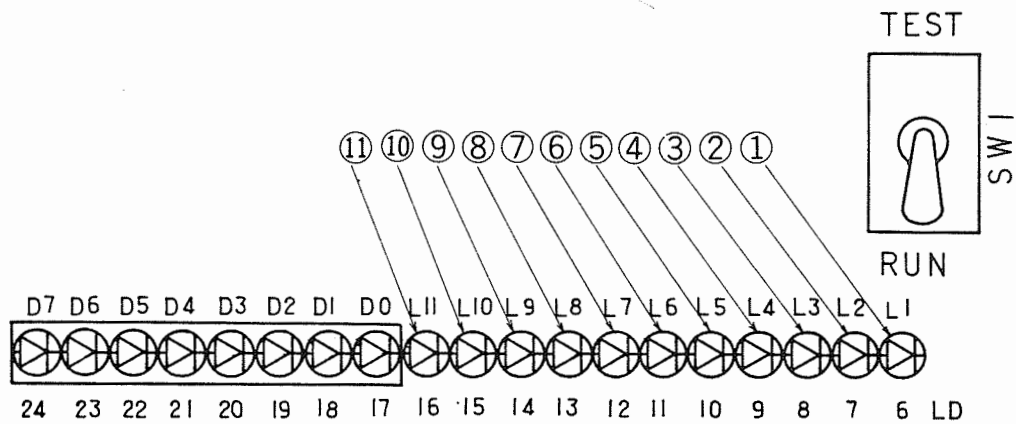


- 1) The R10 (STF) will turn ON for a moment. The drive motor will not rotate because the time that it is ON is too short.
- 2) The R11 (STR) will turn ON for a moment. The drive motor will not rotate because the time that it is ON is too short.
- 3) ~ 17)

The 3,000rph through the 10,000rph speed setting increases gradually. For the speed setting signal checking procedures, see 6. The inverter control board, (3) The speed setting circuit checking procedure (page 37).



## (9) Group 8



1) ~ 11)

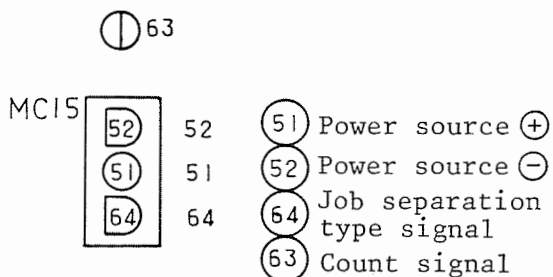
Each input matrix select line from L1 to L11 go on one at a time. At this time, the data line checking LED D0 through D7 corresponds with the select line.

12) The output of the tape inserter count signal.

13) The output of the output signal to the tape inserter.

## 14. The terminals for optional accessories and DS2

## (1) Tape inserter



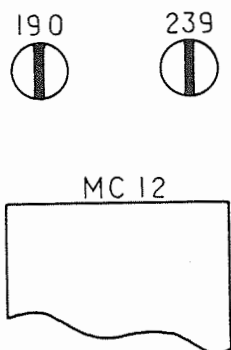
## a) The job separation type

Connect the connector from the tape inserter to the MC15 connector only.

## b) The preset number of copies type

Connect the connector from the tape inserter to the MC15 connector and connect the line (63) to the count signal terminal.

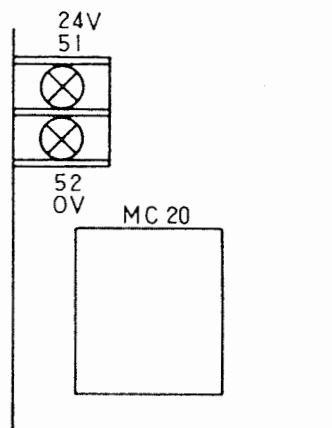
## (2) Feeder safety cover



For the machines that the safety cover is mounted on the feeder section, do not connect anything to the wire no.190 and no.239 tabs.

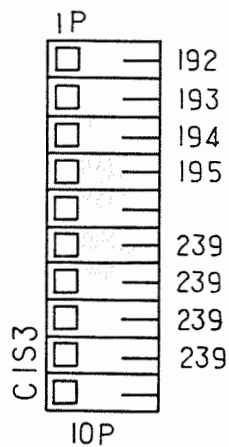
For the machines that the safety cover is not mounted on the feeder section, the wire no.190 and no.239 tabs are connected by a jumper wire to each other. If there is not a jumper line, the machine cannot be rotated.

## (3) 24V terminal base



The output of this terminal base is DC24V. When needing a DC24V power source, use it. But do not use it over the maximum electric current of 1A.

## (4) CIS3



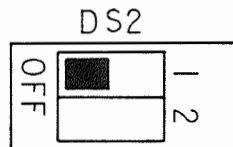
The CIS3 is an extra input terminal.

When connecting the switch point of contact between the wires no.192 through no.195 and the wire no.239, they are inputted to each L9, D2 through D5.

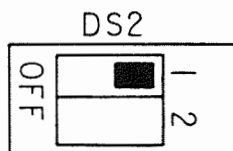
However, there is no program for these input now. If the specifications change and increase the input points, these will be used.

## (5) DS2

When the blanket cleaning device is not mounted



When the blanket cleaning device is mounted



## a) DS2-1

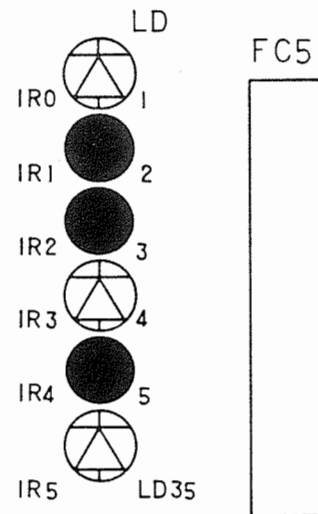
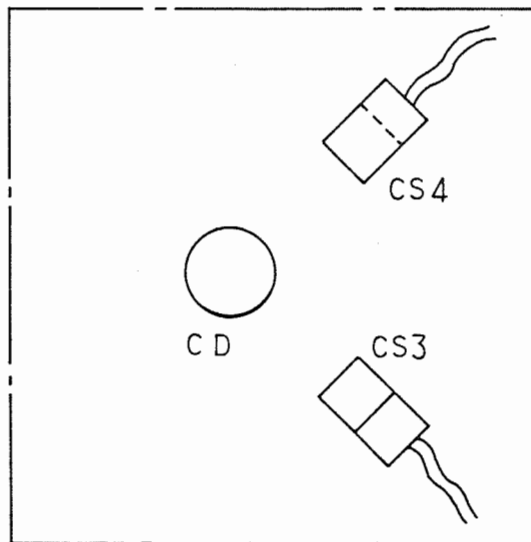
This is the switch for the blanket cleaning device (option) input if it is mounted. If there is no blanket cleaning device on the machine, turn the DS2-1 OFF. And if there is a blanket cleaning device on the machine, turn the DS2-1 ON. Therefore if the blanket cleaning device is mounted later, turn this DS2-1 ON.

## b) DS2-2

This switch is an extra one. Although it does not have any effect when moving it to either side.

### 15. The CS3 and CS4 timing switches

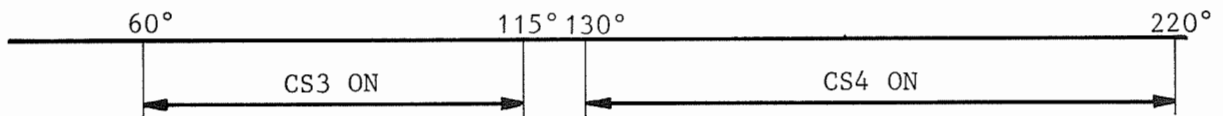
#### (1) The CS3 and CS4 setting procedures



The CS3 and CS4 actuation confirmation is checked by the LD2, LD3, and the LD5 on the connector board.

- ° With the CS3 ON ..... LD2 is OFF
- ° With the CS4 ON ..... LD3 is OFF
- ... LD5 is ON

The timing on the timing plate that turns the CS3 and CS4 ON/OFF is as shown below.



- ° CS3 ..... ON in the 60° to 115° section
- ° CS4 ..... ON in the 130° to 220° section

The timing that turns the CS3 and the CS4 ON/OFF has to be adjusted at only one point, then the other 3 points will be set automatically. Therefore when adjusting, adjust the timing so that the CS3 turns ON on 60°.

(2) Paper feed delayed timing detection

The paper feed delayed timing detection is done by using the timing switch (CS3) and the photo sensor (PH1) on the feeder board. When the sheet of paper reaches the PH1, if the CS3 is OFF, it will be judged that the paper feed timing is delayed. Therefore, the sheet of paper has to reach the PH1 between 60° and 115° on the timing plate.

(Reference) If you think that the paper feed timing is not delayed, the reaching timing should be 68°.

(3) Sheet count

The sheet count is done by the timing switch CS3 and the photo sensor (PH1) on the feeder board. When the CS3 turns OFF (115°), the sheet counter adds one if the PH1 detects the sheet of paper and outputs the count signal (For the tape inserter).

(4) Feed jam

The feed jam detection is done by the timing switches CS3, CS4, the photo sensor (PH1) on the feeder board and the paper feed drum photo sensor (PH4). When the CS3 turns OFF (115°), there is a sheet of paper over the PH1, and when the CS4 turns ON after one rotation (130°) and the sheet of paper has not reached the PH4, this will be detected as a feed jam.

(5) The first unit cylinder ON

The first unit cylinder ON detection is done by the timing switch CS4 and the paper feed drum photo sensor (PH4). When the CS4 turns ON (130°), it judges whether there is a sheet of paper over the PH4. Then turns the first unit cylinder ON solenoid ON or OFF.

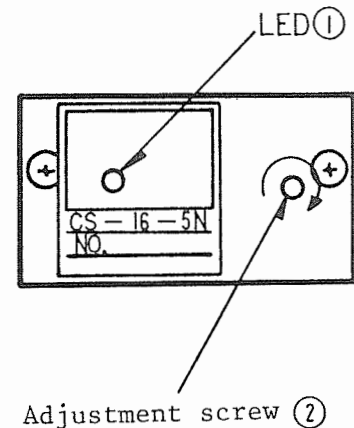
(6) The second unit cylinder ON

The second unit cylinder ON detection is done by the timing switch CS4 and the paper feed drum photo sensor (PH4). When the CS4 turns ON (130°), it judges whether there is a sheet of paper over the PH4. Then turns the second unit cylinder ON solenoid ON or OFF when the CS4 turns OFF (220°).

## 16. Lowering the delivery table dolly

This machine uses an capacitance sensor to lower the delivery table dolly. The sensitivity should be adjusted in the following procedure:

- a) With no paper piled on the delivery table dolly, turn the adjustment screw (2) in the clockwise direction until the LED (1) just lights up.
- b) Turn the adjustment screw (2) in the counterclockwise direction by approximately 90 degrees from the position where the LED (1) just lights up.



This is merely a basic adjustment. Be sure to check the following after the sensitivity adjustment is finished.

(Checking) Run the machine and feed sheets of paper. Then check that the capacitance sensor detects a sheet of paper consistantly and the delivery table dolly lowers.

If the delivery table dolly does not lower, turn the adjustment screw (2) in the clockwise direction to increase the sensitivity. If the delivery table lowers irrespective of the paper feed or delivery, turn the adjustment screw (2) in the counterclockwise direction to reduce the sensitivity.

(Note) If the surface of the delivery table dolly lowering switch is dirty with foreign particles (spray powder and paper dust), the switch may malfunction. Be sure to always clean the surface of the switch.

## 17. Flow charts

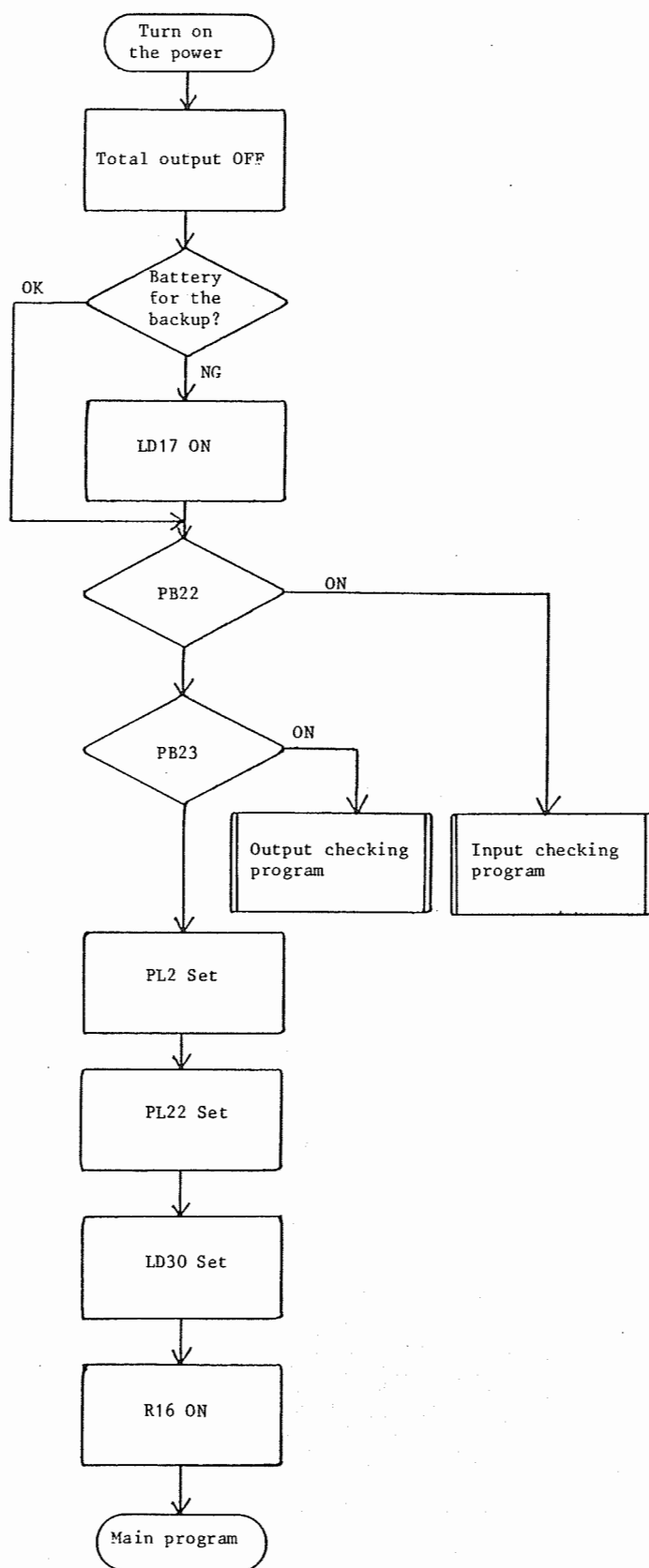
The flow charts explain this machines control program, and explain every function sequence of the machine at each stage. Use these to learn the basic functioning and sequencing of the machine operation and to check the input and the output for after sales service. On the right side of the flow chart the explanation of the parts is given.

	[Page]
(1) Turn on the power .....	71
(2) Green lamp .....	72
(3) Drive motor operation .....	73
(4) Drive motor stop .....	74
(5) The first unit inching .....	75
(6) The second unit inching .....	76
(7) Plate clamp positioning .....	77
(8) Speed .....	78
(9) Pump motor .....	79
(10) Feed ON .....	80
(11) Feed OFF .....	81
(12) Starting the end cycle .....	82
(13) Operating lever return to position III .....	83
(14) Automatic blanket cleaning .....	84
(15) Operating lever return to position I .....	85
(16) Pushing the button to start blanket cleaning .....	86
(17) The blanket cleaning .....	87
(18) Lever synchronizing .....	88
(19) No. 1 ink ductor .....	89
(20) No. 2 ink ductor .....	90
(21) No. 1 water ductor .....	91
(22) No. 2 water ductor .....	92
(23) Spray device .....	93
(24) Lowering the delivery table dolly .....	94
(25) The first unit cylinder ON .....	95
(26) The second unit cylinder ON .....	96
(27) Sheet counter adding .....	97
(28) Lubrication warning .....	98

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(29) Pump filter cleaning warning .....	99
(30) Paper feed delayed timing detector .....	100
(31) Feed jam .....	101
(32) The first unit blanket jam .....	102
(33) The second unit blanket jam .....	103



## (1) Turn on the power



This is the program used only when turning on the main power.

Sign	LD17	Name	Battery warning lamp
Remarks	When the battery on the CPU board is weak, the LD17 will light.		

Sign	PB22	Name	The second unit normal rotation inching button
Check line	L6	Check data	D1
Remarks			

Sign	PB23	Name	The second unit reverse rotation inching button
Check line	L6	Check data	D2
Remarks			

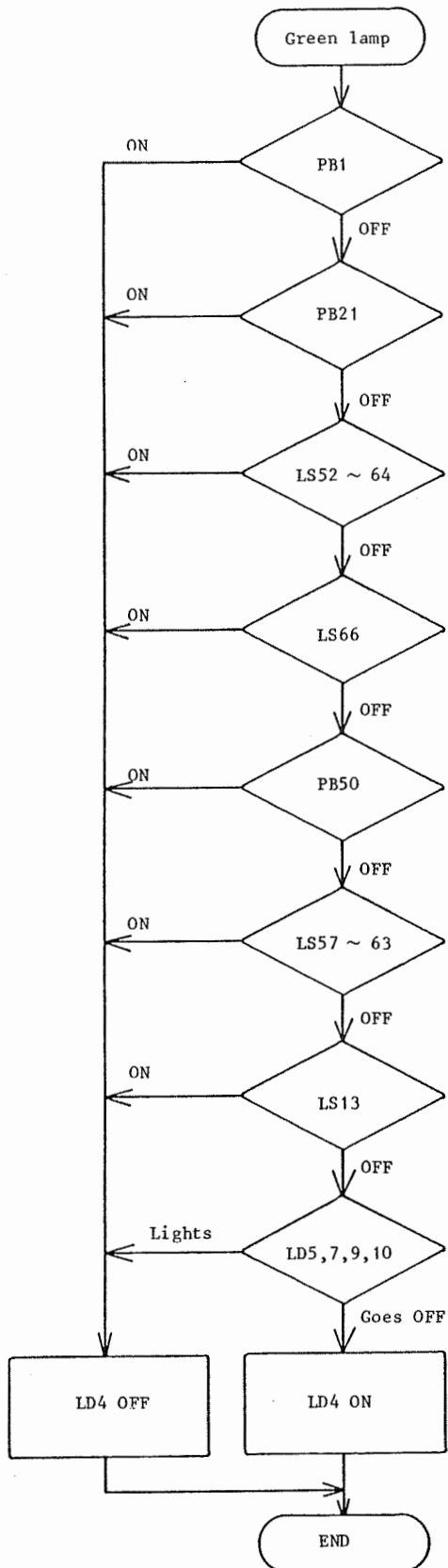
Sign	PL2	Name	The first unit ON/OFF lamp
Memorizes the power OFF condition and indicates that condition.			

Sign	PL22	Name	The second unit ON/OFF lamp
Memorizes the power OFF condition and indicates that condition.			

Sign	LD30	Name	Count ON/OFF lamp
Memorizes the power OFF condition and indicates that condition.			

Sign	R16	Name	Feed OFF relay
Remarks			

## (2) Green lamp



This is the program that lights the ON or OFF green lamp.

Sign	PB1	Name	The first unit emergency stop button	
Check line	L5		Check data	D0
Remarks				

Sign	PB21	Name	The second unit emergency stop button	
Check line	L6	Check data	D0	
Remarks				

Sign	LS52~64	Name	Safety cover switch	
Check line	L10	Check data	D0 ~ D7	
Sign	LS66	Name	Safety cover switch(Optional)	
Check line	L9	Check data	D0	
Remarks	The cover switches are all N.C. Therefore the checking LEDs usually light and when the cover is opened, the light goes off.			

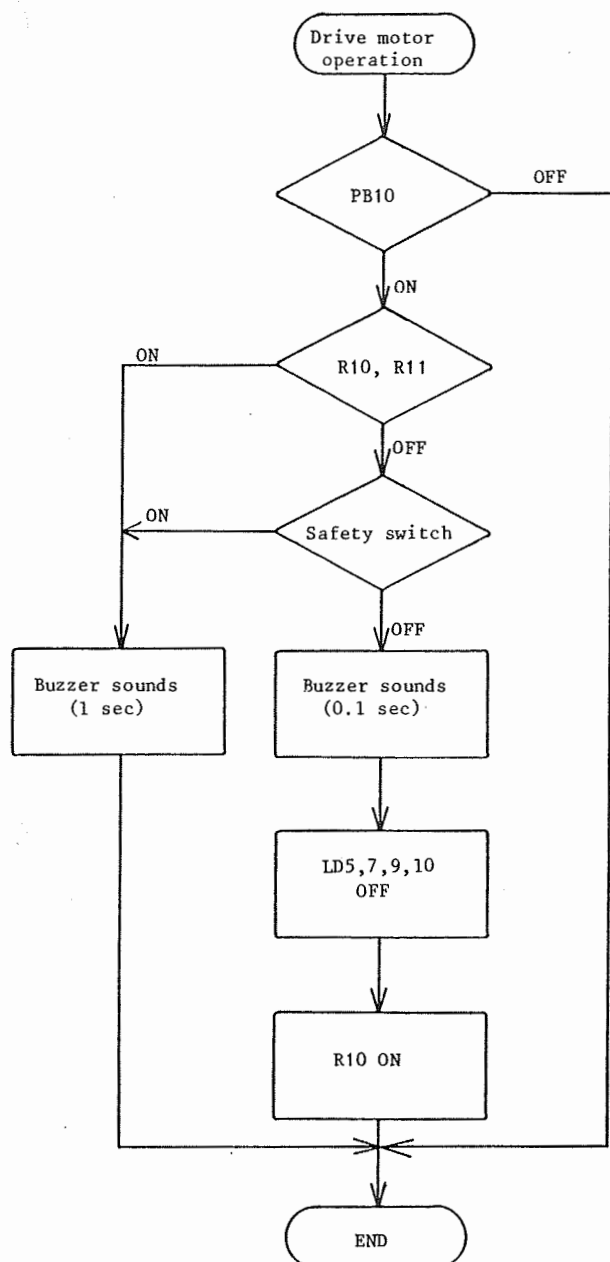
Sign	PB50	Name	Delivery section emergency stop button	
Check line	L11	Check data	D0	
Sign	LS57~63	Name	Safety switch	
Check line	L11	Check data	D2 ~ D6	
Remarks	The emergency stop button and the safety switches are all N.C. Therefore the checking LEDs usually light and when the switch operates, the light goes off.			

Sign	LS13	Name	Delivery jam switch	
Check line	L2	Check data	D7	
Remarks				

Sign	LD5	Name	The second unit blanket jam lamp	
Sign	LD7	Name	The first unit blanket jam lamp	
Sign	LD9	Name	Feed jam lamp	
Sign	LD10	Name	Delivery jam lamp	

Sign	LD4	Name	Green lamp
Remarks			

## (3) Drive motor operation



Sign	PB10	Name	Start Button
Check line	L8	Check data	D3
Remarks			

Sign	R10	Name	Motor normal rotation relay
Sign	R11	Name	Motor reverse rotation relay
Remarks			

Sign		Name	Safety switch
Remarks	If even one safety switch actuates, the machine will stop.		

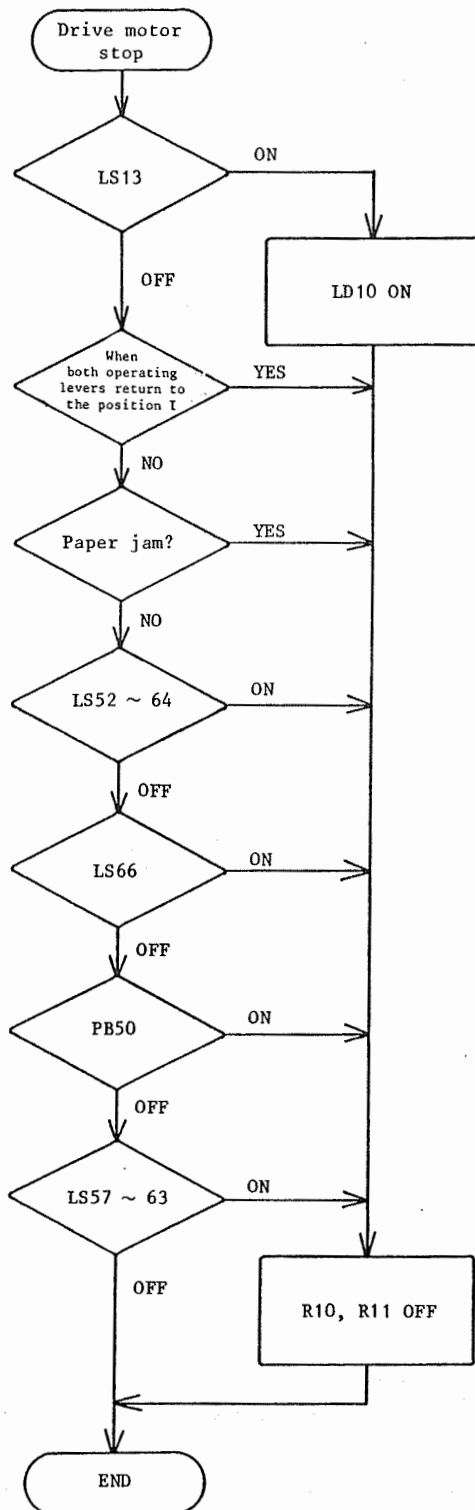
Sign	LD5	Name	The second unit blanket jam lamp
Sign	LD7	Name	The first unit blanket jam lamp
Sign	LD9	Name	Feed jam lamp
Sign	LD10	Name	Delivery jam lamp
Remarks			

Sign	R10	Name	Motor normal rotation relay
Remarks			

For the safety switches shown below if even only one actuates, the machine will stop.

Sign	Name	Sign	Name
PB1	The first unit emergency stop button	LS60	The first unit back safety cover switch
PB21	The second unit emergency stop button	LS61	The first unit top safety cover switch
LS13	Delivery unit jam switch	LS64	The first unit front safety cover switch
LS66	Feeder safety cover switch (Option)	PB50	Delivery section emergency stop button
LS52	Delivery section safety cover switch	LS57	The second unit safety bar switch
LS53	The second unit back safety cover switch	LS58	The second unit vertical image adjustment safety switch
LS54	The second unit top safety cover switch	LS59	Handwheel safety switch
LS55	The second unit front safety cover switch	LS62	The first unit safety bar switch
LS56	Impression cylinder safety cover switch	LS63	The first unit vertical image adjustment safety switch

## (4) Drive motor stop



Sign	LS13	Name	Delivery jam switch
Check line	L2	Check data	D7
Remarks			

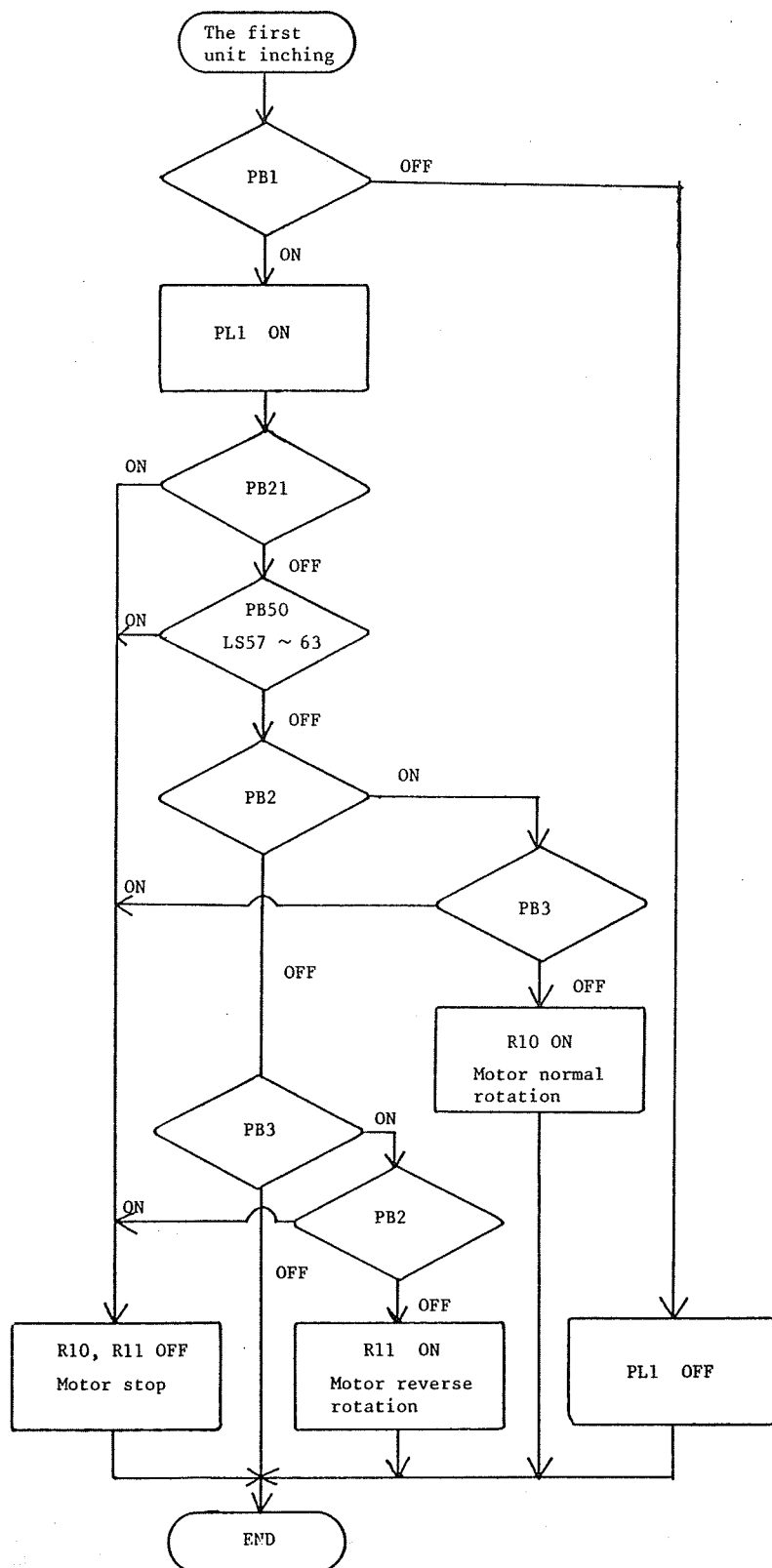
Sign	LD10	Name	Delivery jam lamp
Remarks			

Sign	LS52~64	Name	Safety cover switch
Check line	L10	Check data	D0 ~ D7
Sign	LS66	Name	Safety cover switch (Option)
Check line	L9	Check data	D0
Remarks			

Sign	PB50	Name	Delivery section emergency stop button
Check line	L11	Check data	D0
Sign	LS57~63	Name	Safety switch
Check line	L11	Check data	D2~D6
Remarks			

Sign	R10	Name	Motor normal rotation relay
Sign	R11	Name	Motor reverse rotation relay
Remarks			

## (5) The first unit inching



Sign	PB1	Name	The first unit emergency stop button
Check line	L5	Data line	D0
Remarks			

Sign	PL1	Name	The first unit emergency stop lamp
Remarks			

Sign	PB21	Name	The second unit emergency stop button
Check line	L6	Data line	D0
Remarks			

Sign	PB50	Name	Delivery section emergency stop button
Check line	L11	Data line	D0
Sign	LS57~63	Name	Safety switch
Check line	L11	Data line	D2~D6
Remarks			

Sign	PB2	Name	The first unit normal rotation inching button
Check line	L5	Data line	D1
Remarks			

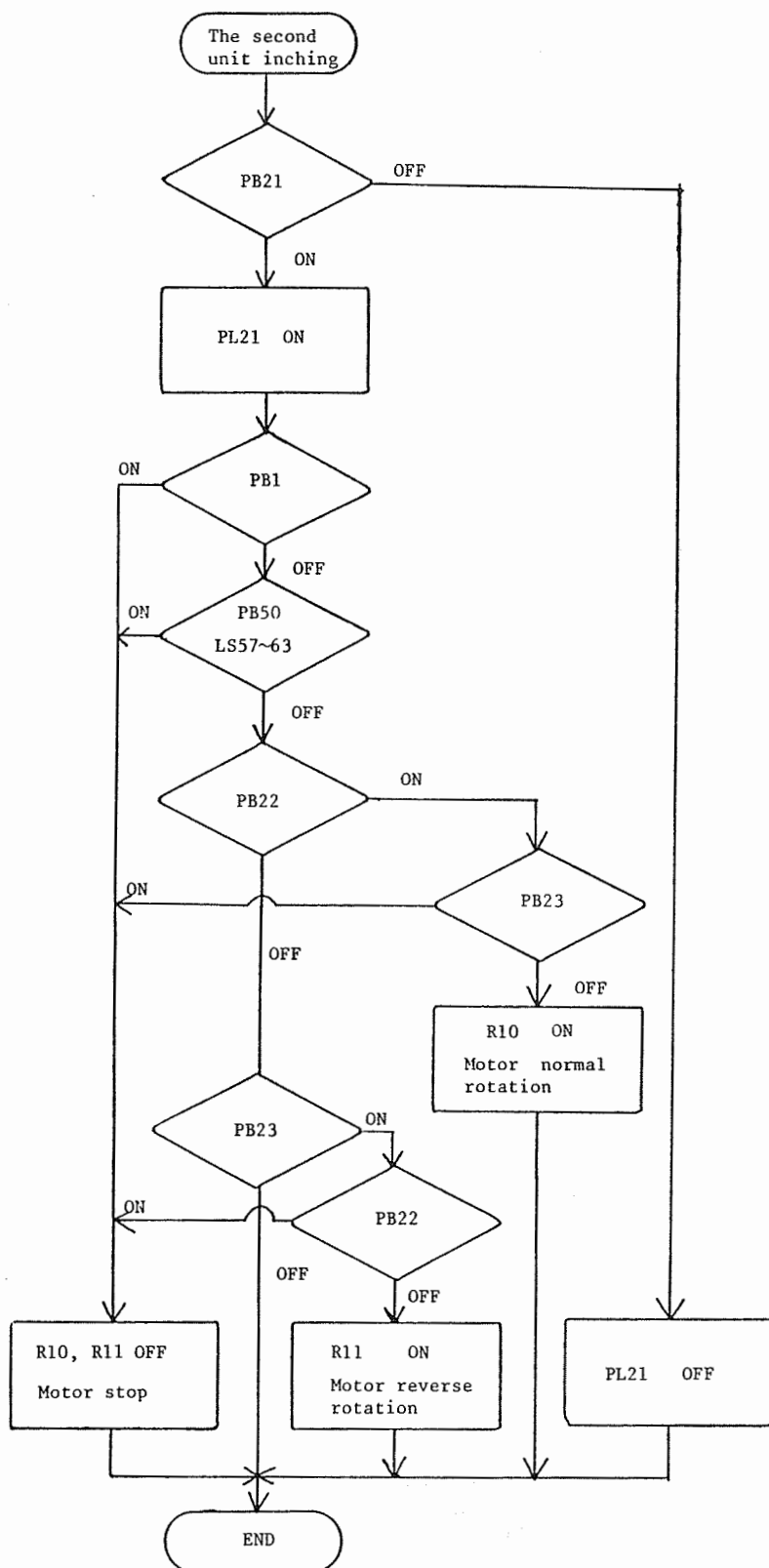
Sign	PB3	Name	The second unit reverse rotation inching button
Check line	L5	Data line	D2
Remarks			

Sign	R10	Name	Motor normal rotation relay
Sign	R11	Name	Motor reverse rotation relay
Remarks			

(Note)

The inching movement time period from start to stop has been set to 0.6 seconds on the software.

## (6) The second unit inching



Sign	PB21	Name	The second unit emergency stop button
Check line	L6	Data line	D0
Remarks			

Sign	PL21	Name	The second unit emergency stop lamp
Remarks			

Sign	PB1	Name	The first unit emergency stop button
Check line	L5	Data line	D0
Remarks			

Sign	PB50	Name	Delivery section emergency stop button
Check line	L11	Data line	D0
Sign	LS57~63	Name	Safety switch
Check line	L11	Data line	D2 ~ D6
Remarks			
Sign	PB22	Name	The second unit normal rotation inching button
Check line	L6	Data line	D1
Remarks			

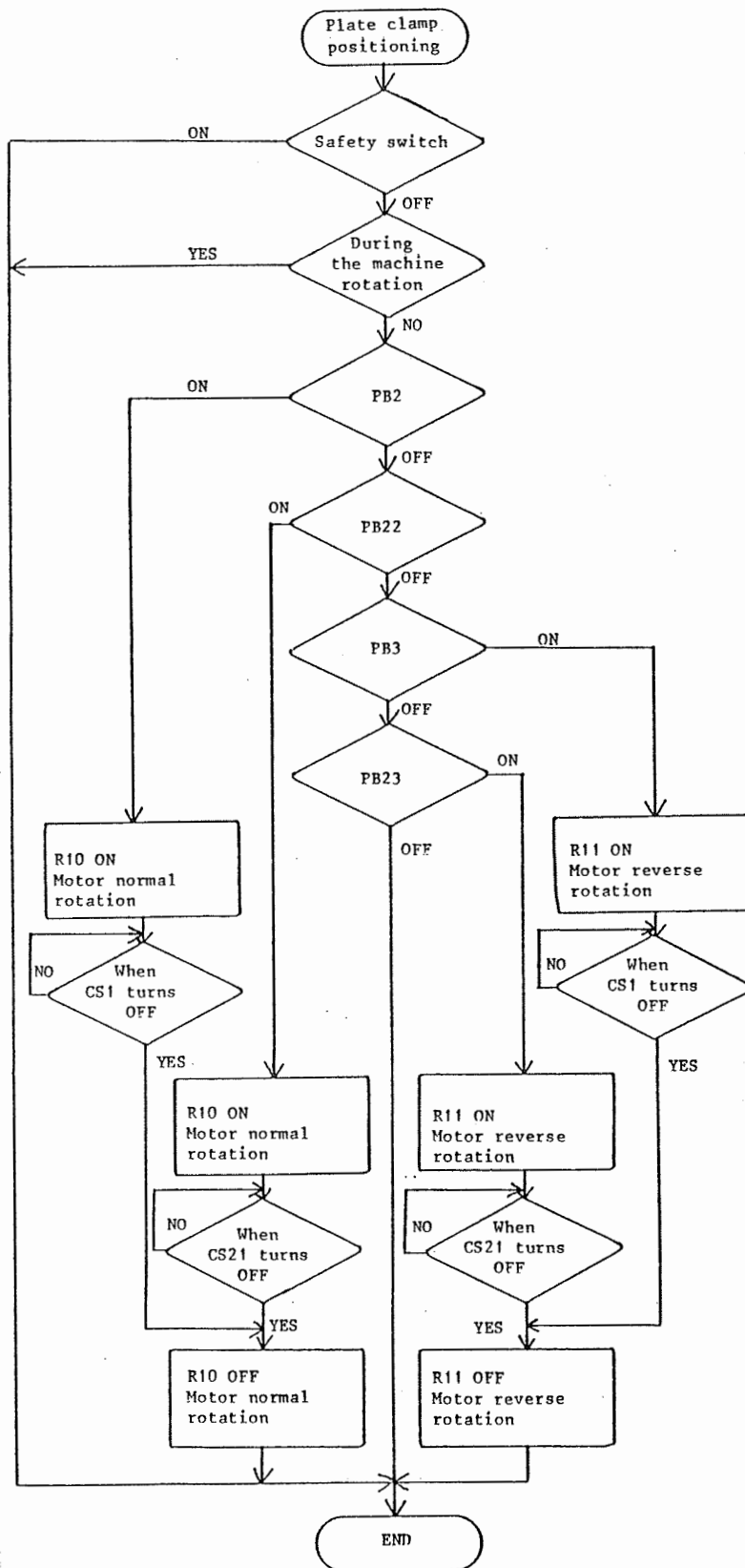
Sign	PB23	Name	The second unit reverse rotation inching button
Check line	L6	Data line	D2
Remarks			

Sign	R10	Name	Motor normal rotation relay
Sign	R11	Name	Motor reverse rotation relay
Remarks			

(Note)

The inching movement time period from start to stop has been set to 0.6 seconds on the software.

## (7) Plate clamp positioning



Sign		Name	Safety switch
Remarks	See (3) Drive motor operation (Page 73).		

Sign	PB2	Name	The first unit normal rotation inching button
Check line	L5	Check data	D1
Remarks			

Sign	PB22	Name	The second unit normal rotation inching button
Check line	L6	Check data	D1
Remarks			

Sign	PB3	Name	The first unit reverse rotation inching button
Check line	L5	Check data	D2
Remarks			

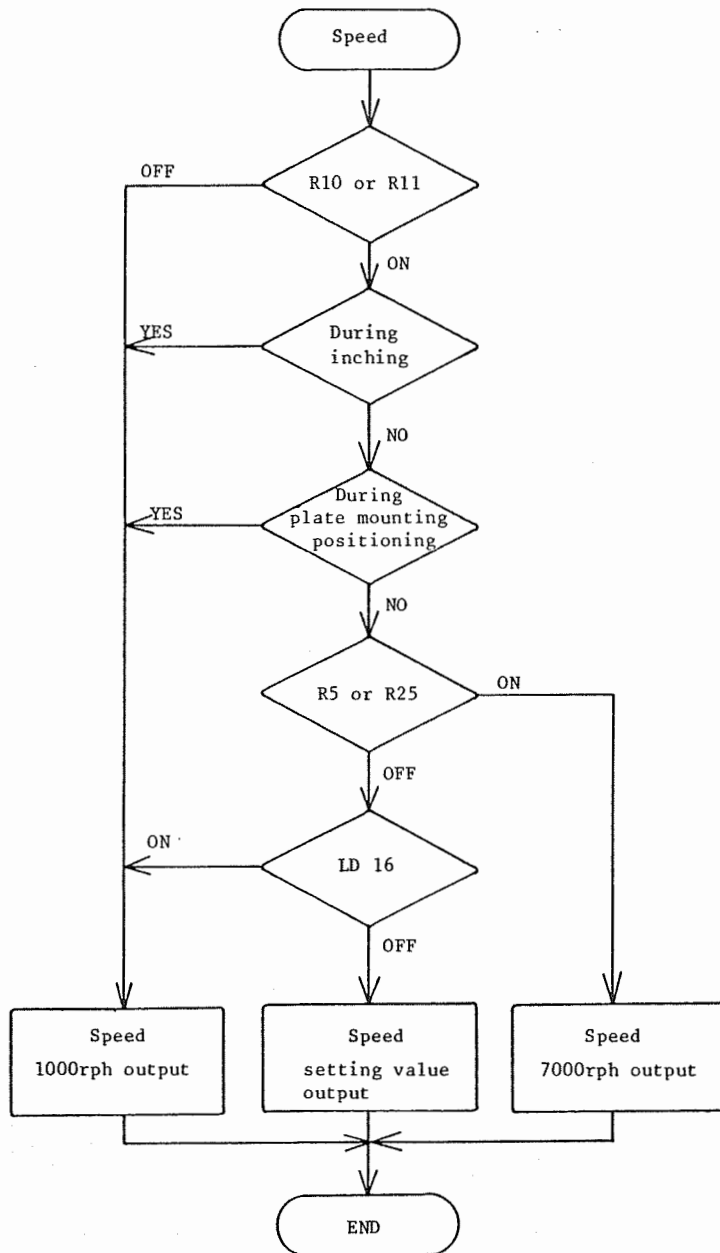
Sign	PB23	Name	The second unit reverse rotation inching button
Check line	L6	Check data	D2
Remarks			

Sign	CS1	Name	The first unit plate mounting position
Check line	L1	Check data	D5
Remarks			

Sign	R10	Name	Motor normal rotation relay
Sign	R11	Name	Motor reverse rotation relay
Remarks			

Sign	CS21	Name	The second unit plate mounting position
Check line	L2	Check data	D5
Remarks			

## (8) Speed



This is the program that sends the speed setting digital signal to the inverter control circuit.

Sign	R10	Name	Motor normal rotation relay
Sign	R11	Name	Motor reverse rotation relay
Remarks			

During the plate mounting means during the rotation to set the plate cylinder at the plate mounting position.

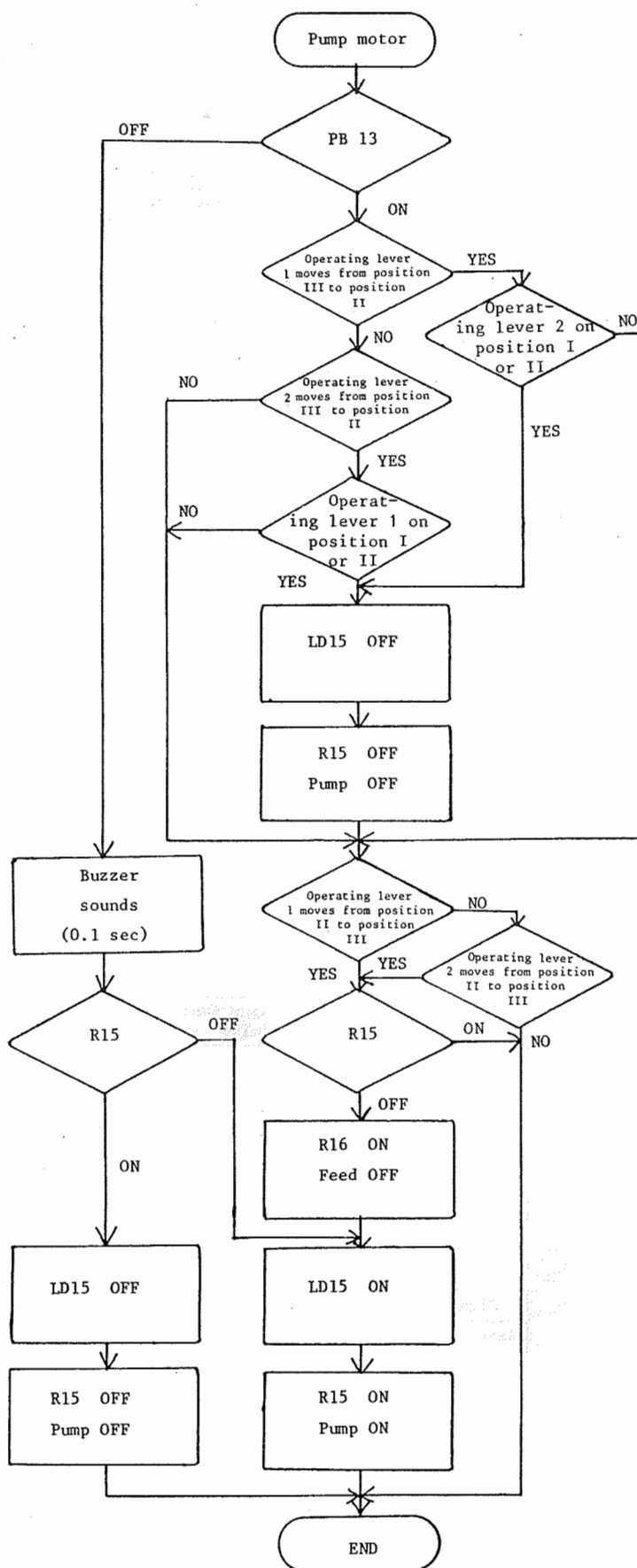
Sign	R5	Name	The first unit blanket cleaning relay
Sign	R25	Name	The second unit blanket cleaning relay
Remarks			

Sign	LD16	Name	1000rph button
Remarks			

The speed setting value is the speed that is set by using the PB38 through PB40.



## (9) Pump motor



Sign	PB13	Name	Pump button
Check line	L8	Check data	D4
Remarks			

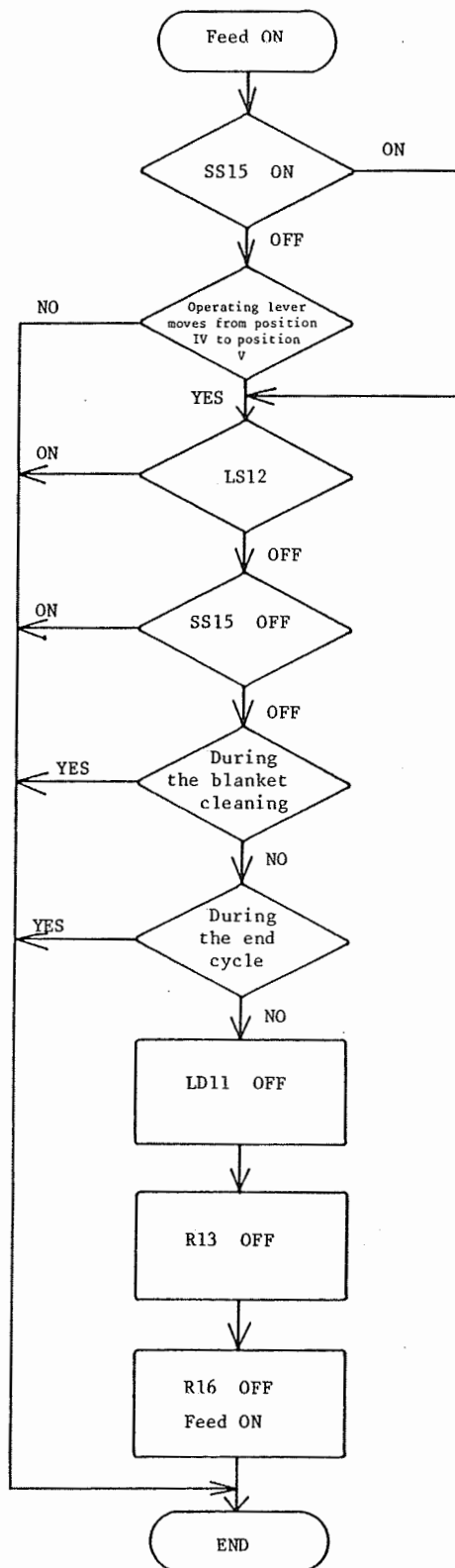
Sign	LS2, 3	Name	Operating lever 1
Check line	L1	Check data	D1, D2
Sign	LS21, 22	Name	Operating lever 2
Check line	L2	Check data	D0, D1
Sign	LS22, 23	Name	Operating lever 2
Check line	L2	Check data	D1, D2
Sign	LS1, 2	Name	Operating lever 1
Check line	L1	Check data	D0, D1
Remarks			

Sign	LD15	Name	Pump lamp
Remarks			

Sign	R15	Name	Pump relay
Remarks			

Sign	R16	Name	Feed OFF relay
Remarks			

## (10) Feed ON



Sign	SS15 ON	Name	Feed ON switch
Check line	L1	Check data	D6
Remarks			

Sign	LS4, 5	Name	Operating lever 1
Check line	L1	Check data	D3, D4
Sign	LS24, 25	Name	Operating lever 2
Check line	L2	Check data	D3, D4
Remarks			

Sign	LS12	Name	Delivery table dolly lower limit switch
Check line	L2	Check data	D6
Remarks			

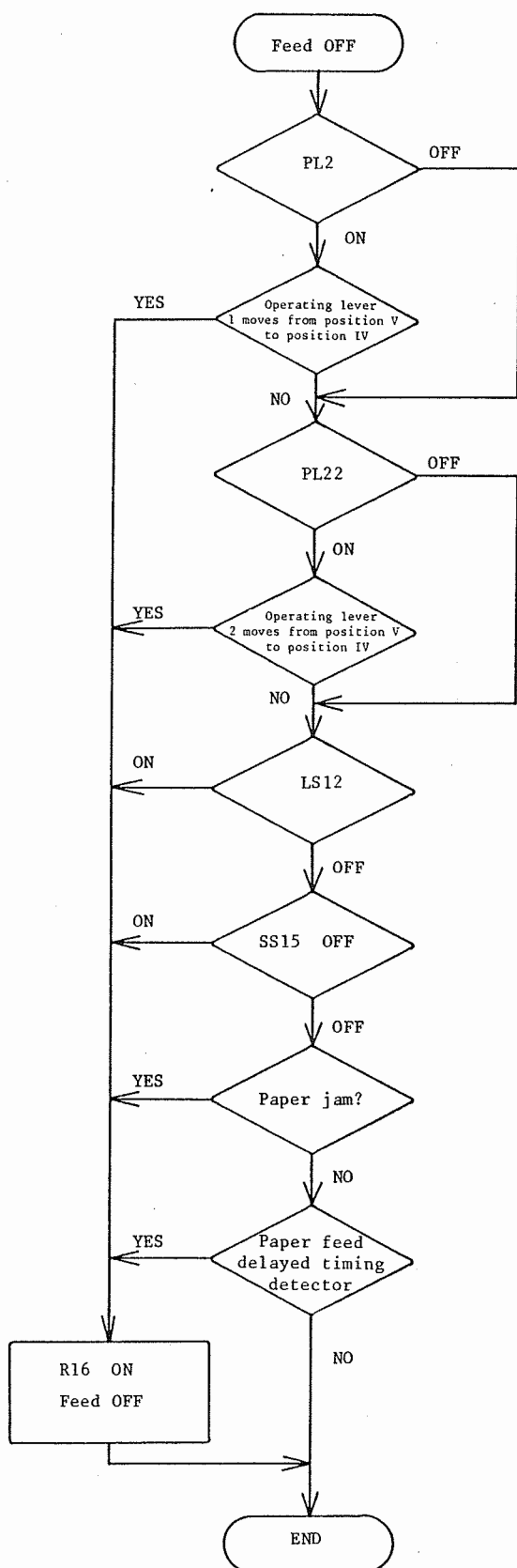
Sign	SS15 OFF	Name	Feed OFF switch
Check line	L1	Check data	D7
Remarks			

Sign	LD11	Name	Paper feed delayed timing lamp
Remarks			

Sign	R13	Name	Paper feed delayed timing relay
Remarks			

Sign	R16	Name	Feed OFF relay
Remarks			

## (11) Feed OFF



Sign	PL2	Name	The first unit ON/OFF lamp
Remarks			

Sign	LS4, 5	Name	Operating lever 1
Check line	L1	Check data	D3, D4
Remarks			

Sign	PL22	Name	The second unit ON/OFF lamp
Remarks			

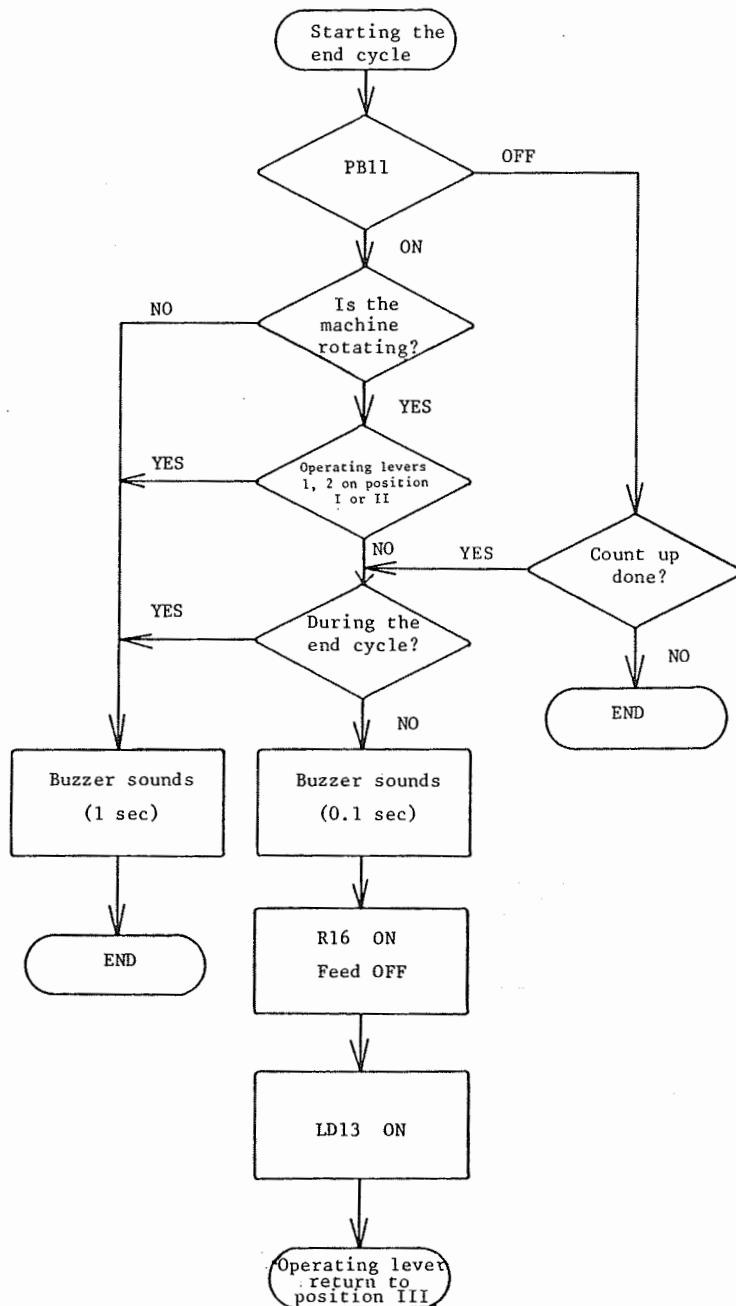
Sign	LS24, 25	Name	Operating lever 2
Check line	L2	Check data	D3, D4
Remarks			

Sign	LS12	Name	Delivery table dolly lower limit switch
Check line	L2	Check data	D6
Remarks			

Sign	SS15 OFF	Name	Feed OFF switch
Check line	L1	Check data	D7
Remarks			

Sign	R16	Name	Feed OFF relay
Remarks			

## (12) Starting the end cycle



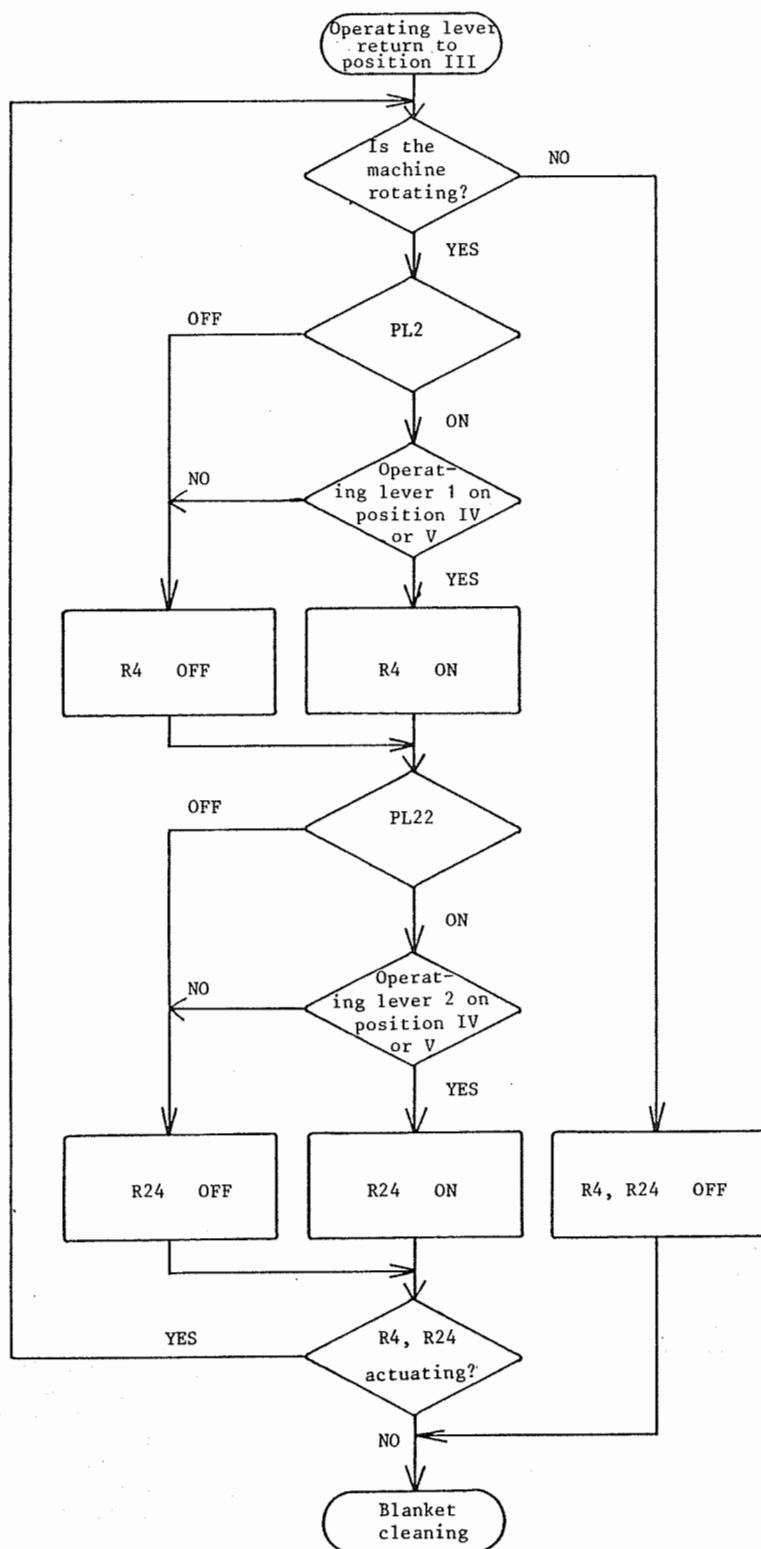
Sign	PB11	Name	End cycle button
Check line	L8	Check data	D0
Remarks			

Sign	LS1, 2	Name	Operating lever 1
Check line	L1	Check data	D0, D1
Sign	LS21, 22	Name	Operating lever 2
Check line	L2	Check data	D0, D1
Remarks			

Sign	R16	Name	Feed OFF relay
Remarks			

Sign	LD13	Name	End cycle lamp
Remarks			

## (13) Operating lever return to position III



This is the program that returns the operating lever to position III during the end cycle.

Sign	PL2	Name	The first unit ON/OFF lamp
Remarks			

Sign	LS4, 5	Name	Operating lever 1
Check line	L1	Check data	D3, D4
Remarks			

Sign	R4	Name	Operating lever 1 return relay
Remarks			

Sign	PL22	Name	The second unit ON/OFF lamp
Remarks			

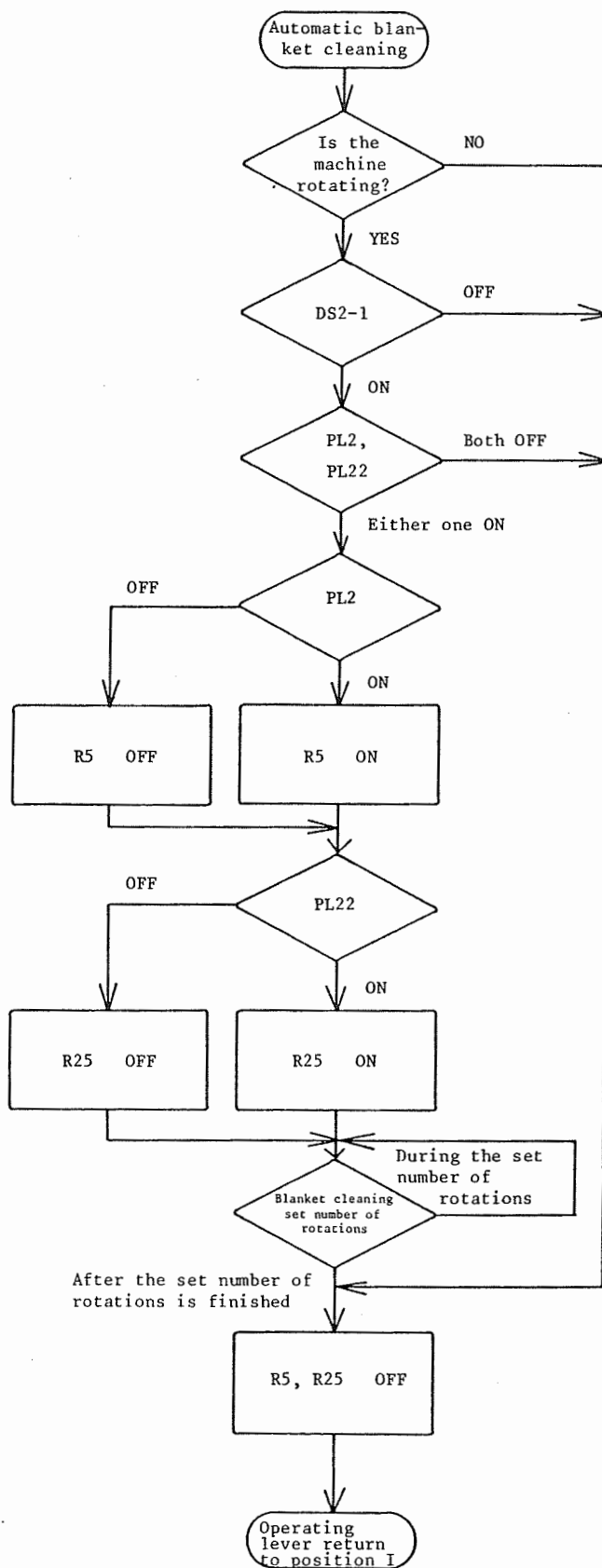
Sign	LS24, 25	Name	Operating lever 2
Check line	L2	Check data	D3, D4
Remarks			

Sign	R24	Name	Operating lever 2 return relay
Remarks			

(Note)

The R4 and the R24 keep actuating until the operating levers return to the position III.

## (14) Automatic blanket cleaning



This is the blanket cleaning program during the end cycle.

Sign	DS2-1	Name	Blanket cleaning ON/OFF switch
Check line	L9	Check data	D6
Remarks			

Sign	PL2	Name	The first unit ON/OFF lamp
Remarks			

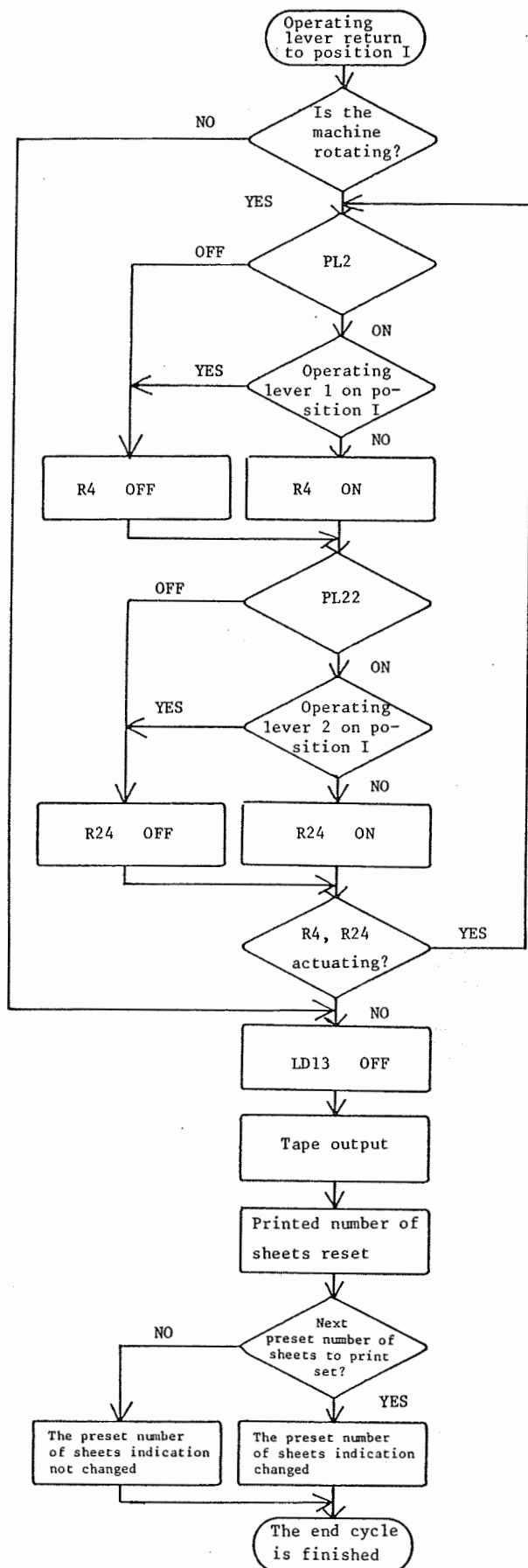
Sign	R5	Name	The first unit blanket cleaning relay
Remarks			

Sign	PL22	Name	The second unit ON/OFF lamp
Remarks			

Sign	R25	Name	The second unit blanket cleaning relay
Remarks			

Sign	CS4 OFF	Name	Timing switch
Check line	IR2	Check data	
Sign	DS1	Name	Blanket cleaning rotation number preset switch
Check line	L3	Check data	D0 ~ D3
Remarks	One rotation is counted when the CS4 timing switch turns OFF. When the total number of rotations equals the preset number of rotations, the blanket cleaning cycle is finished. The number of blanket cleaning cycle rotations = (DS1) x 4 + 20 times.		

## (15) Operating lever return to position I



This is the program that returns the operating lever from position III to position I during the end cycle.

Sign	PL2	Name	The first unit ON/OFF lamp
Remarks			

Sign	LS1	Name	Operating lever 1
Check line	L1	Check data	D0
Remarks			

Sign	R4	Name	Operating lever 1 return relay
Remarks			

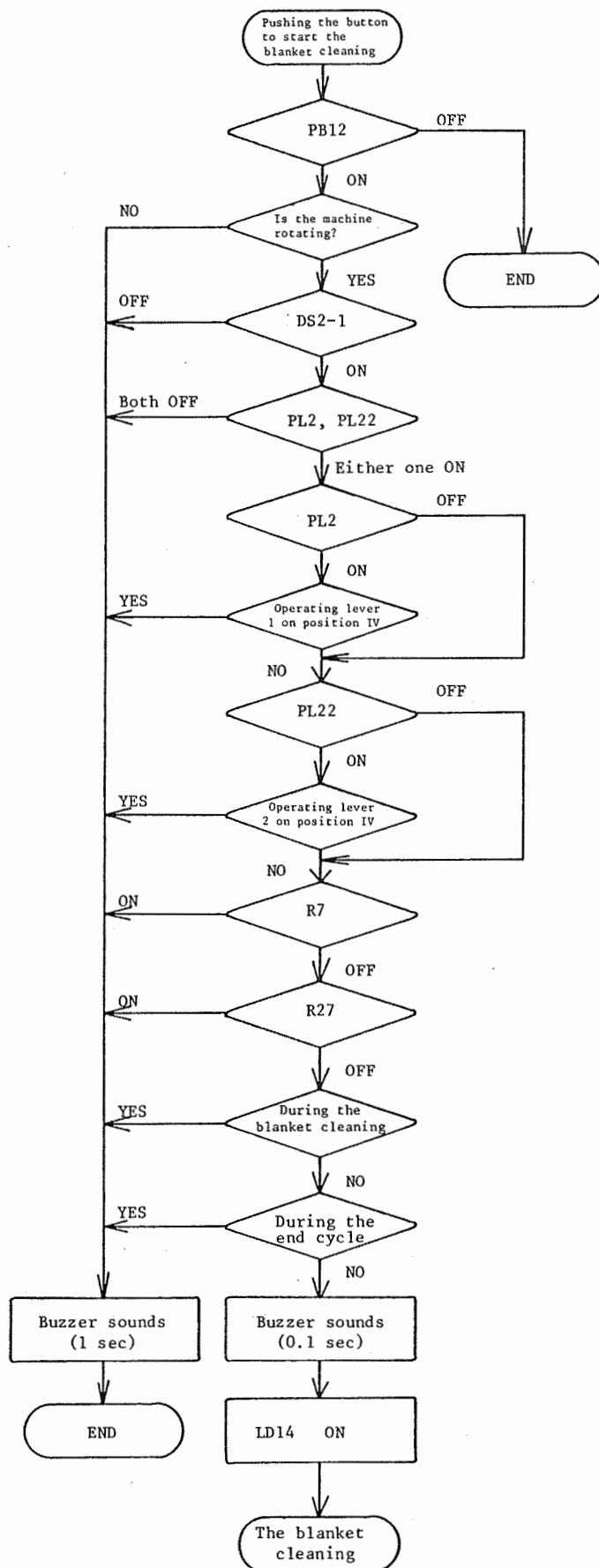
Sign	PL22	Name	The second unit ON/OFF lamp
Remarks			

Sign	LS21	Name	Operating lever 2
Check line	L2	Check data	D0
Remarks			

Sign	R24	Name	Operating lever 2 return relay
Remarks			

Sign	LD13	Name	End cycle lamp
Remarks			

## (16) Pushing the button to start blanket cleaning



This is the program started when pushing the blanket cleaning button.

Sign	PB12	Name	Blanket cleaning button
Remarks			

Sign	DS2-1	Name	Blanket cleaning ON/OFF switch
Check line	L9	Check data	D6
Remarks			

Sign	PL2	Name	The first unit ON/OFF lamp
Remarks			

Sign	LS4	Name	Operating lever 1
Check line	L1	Check data	D3
Remarks			

Sign	PL22	Name	The second unit ON/OFF lamp
Remarks			

Sign	LS24	Name	Operating lever 2
Check line	L2	Check data	D3
Remarks			

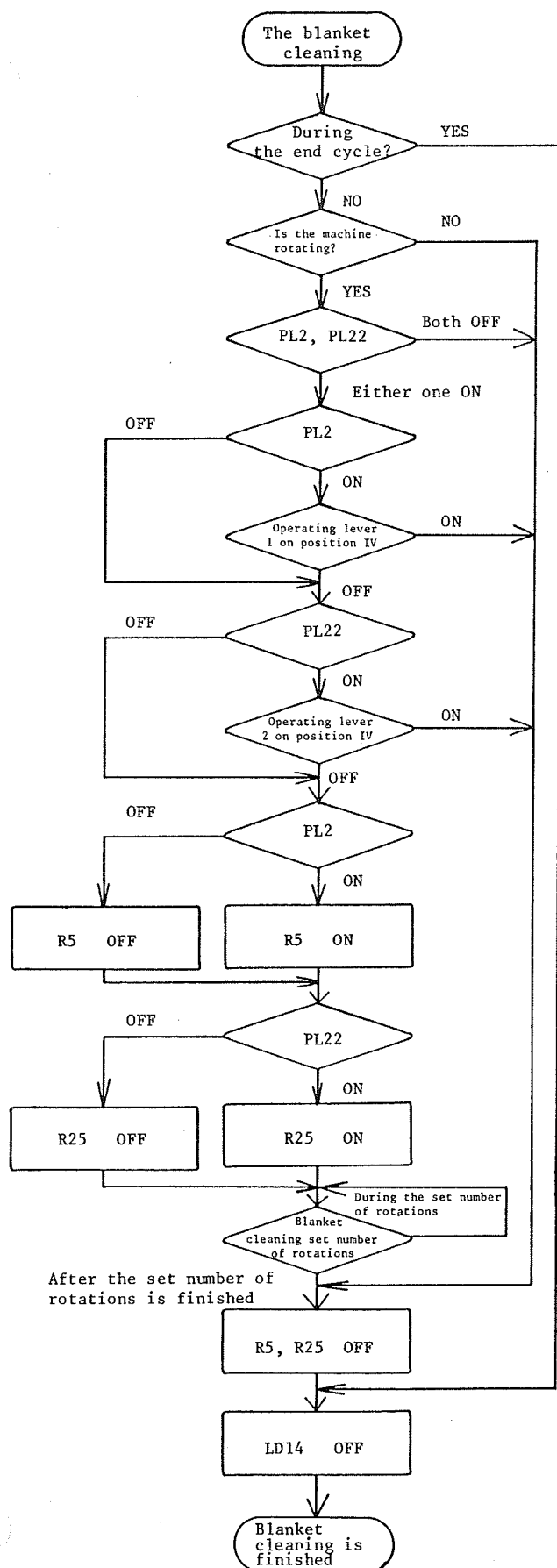
Sign	R7	Name	The first unit cylinder ON relay
Remarks			

Sign	R27	Name	The second unit cylinder ON relay
Remarks			

Sign	LD14	Name	Blanket cleaning lamp
Remarks			



## (17) The blanket cleaning



This is the blanket cleaning program when pushing the blanket cleaning button.

Sign	PL2	Name	The first unit ON/OFF lamp
Remarks			

Sign	LS4	Name	Operating lever 1
Check line	L1	Check data	D3
Remarks			

Sign	PL22	Name	The second unit ON/OFF lamp
Remarks			

Sign	LS24	Name	Operating lever 2
Check line	L2	Check data	D3
Remarks			

Sign	R5	Name	The first unit blanket cleaning relay
Remarks			

Sign	R25	Name	The second unit blanket cleaning relay
Remarks			

Sign	CS4 OFF	Name	Timing switch
Check line	IR2	Check data	

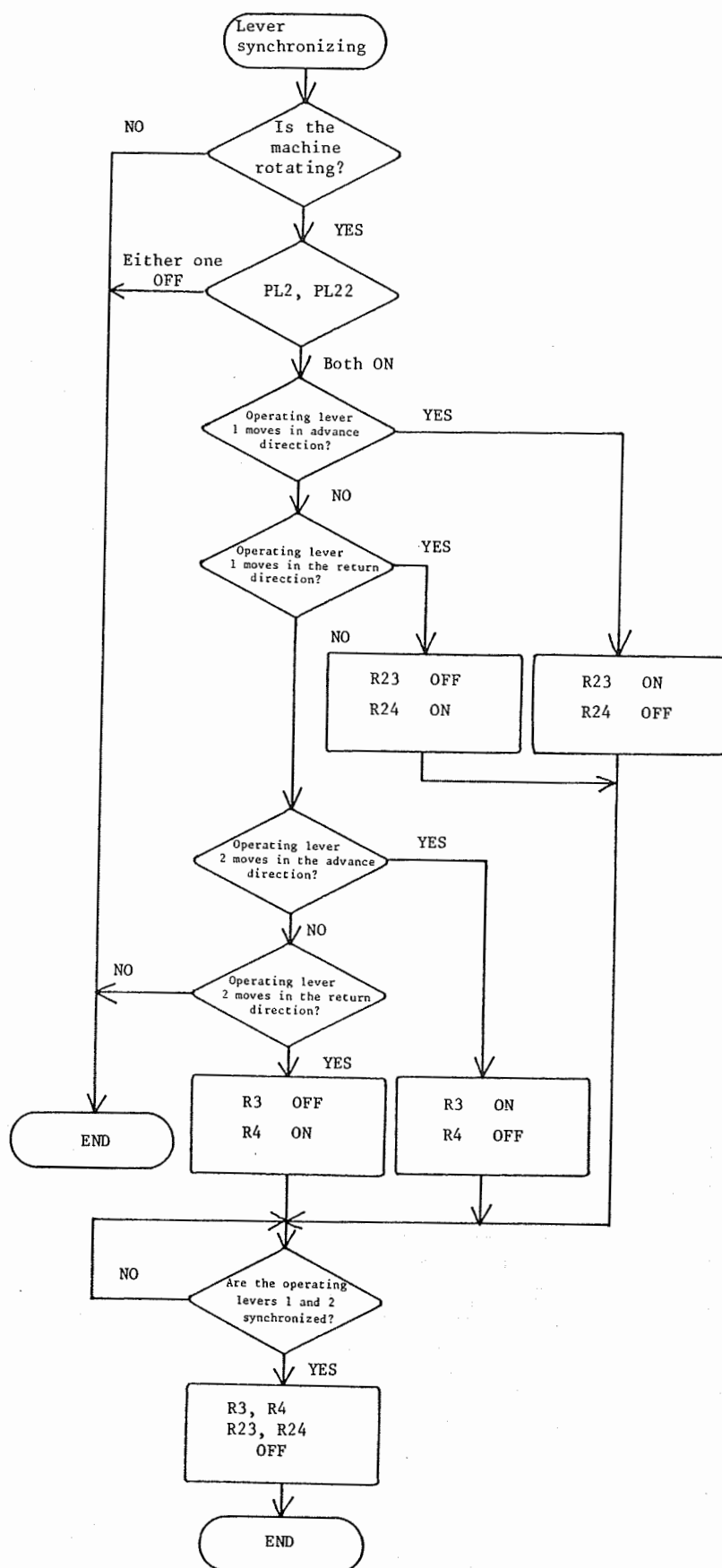
Sign	DS1	Name	Blanket cleaning rotation number preset switch
Check line	L3	Check data	D0 ~ D3

Remarks	One rotation is counted when the CS4 timing switch turns OFF. When the total number of rotations equals the preset number of rotations, the blanket cleaning cycle is finished. The number of blanket cleaning cycle rotations = (DS1) x 4 + 20 times.		
---------	---	--	--

Sign	LD14	Name	Blanket cleaning lamp
Remarks			

## (18) Lever synchronizing

This is the program for synchronizing both units operating levers.



Sign	PL2	Name	The first unit ON/OFF lamp
Sign	PL22	Name	The second unit ON/OFF lamp
Remarks			

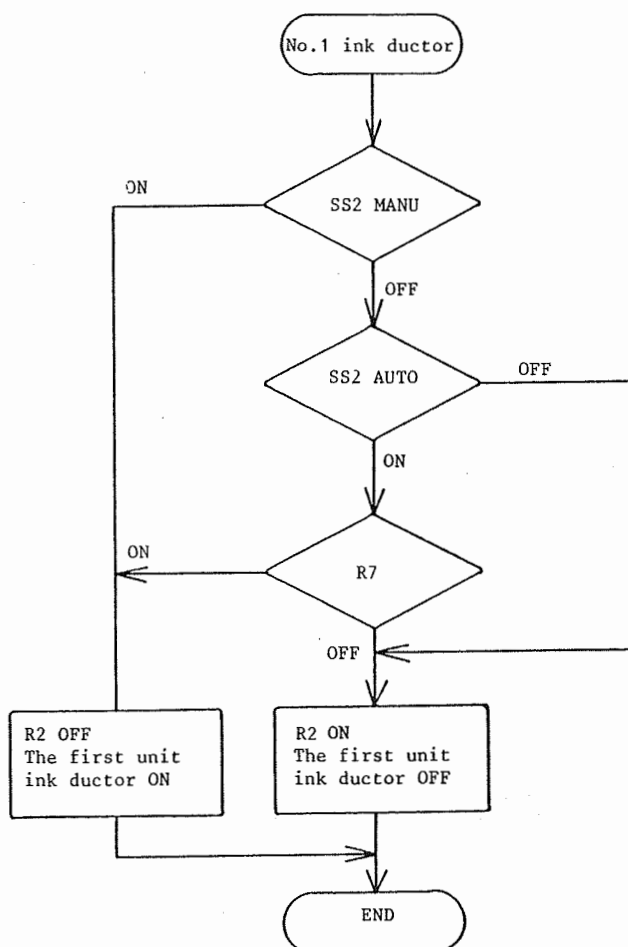
Sign	LS1~5	Name	Operating lever 1
Check line	L1	Check data	D0 ~ D4
Remarks	For the operating lever advance direction movement, the operating lever moves in the position I to the position V direction, and for the return direction movement, the operating lever moves in the position V to the position I direction.		

Sign	R23	Name	Operating lever 2 advance relay
Sign	R24	Name	Operating lever 2 return relay
Remarks			

Sign	LS21 ~ 25	Name	Operating lever 2
Check line	L2	Check data	D0 ~ D4
Remarks	For the operating lever advance direction movement, the operating lever moves in the position I to the position V direction, and for the return direction movement, the operating lever moves in the position V to the position I direction.		

Sign	R3	Name	Operating lever 1 advance relay
Sign	R4	Name	Operating lever 1 return relay
Remarks			

## (19) No. 1 ink ductor



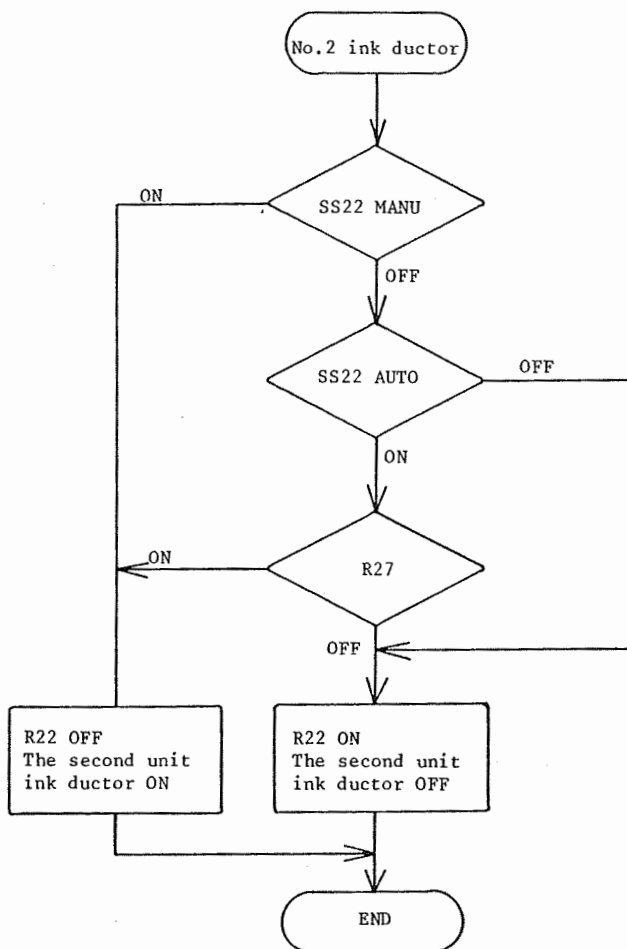
Sign	SS2 MANU	Name	The first unit ink ductor manual switch
Check line	L5	Check data	D6
Remarks			

Sign	SS2 AUTO	Name	The first unit ink ductor automatic switch
Check line	L5	Check data	D7
Remarks			

Sign	R7	Name	The first unit cylinder ON relay
Remarks			

Sign	R2	Name	The first unit ink ductor stop relay
Remarks			

## (20) No. 2 ink ductor



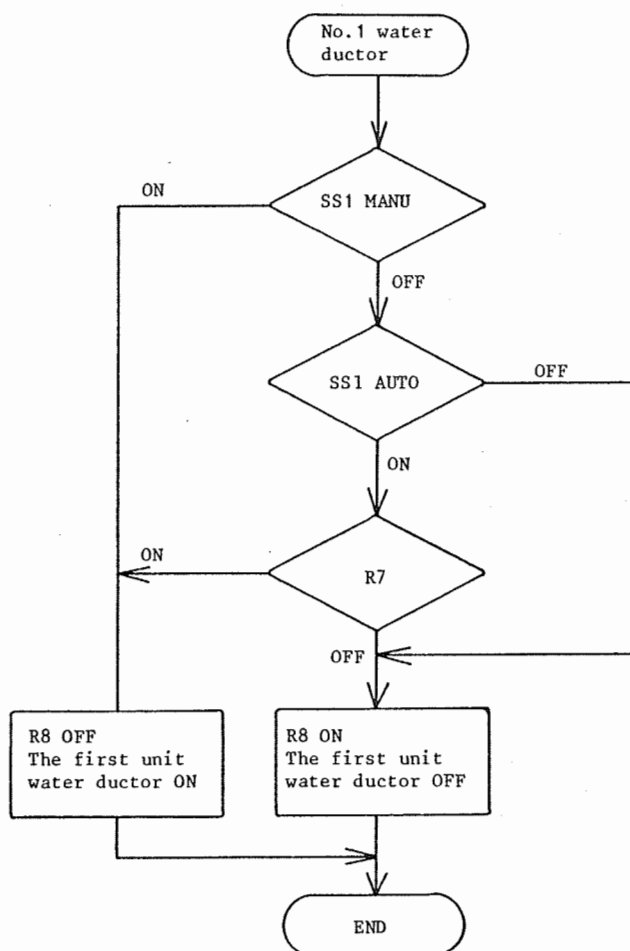
Sign	SS22 MANU	Name	The second unit ink ductor manual switch
Check line	L6	Check data	D6
Remarks			

Sign	SS22 AUTO	Name	The second unit ink ductor automatic switch
Check line	L6	Check data	D7
Remarks			

Sign	R27	Name	The second unit cylinder ON relay
Remarks			

Sign	R22	Name	The second unit ink ductor stop relay
Remarks			

## (21) No. 1 water ductor



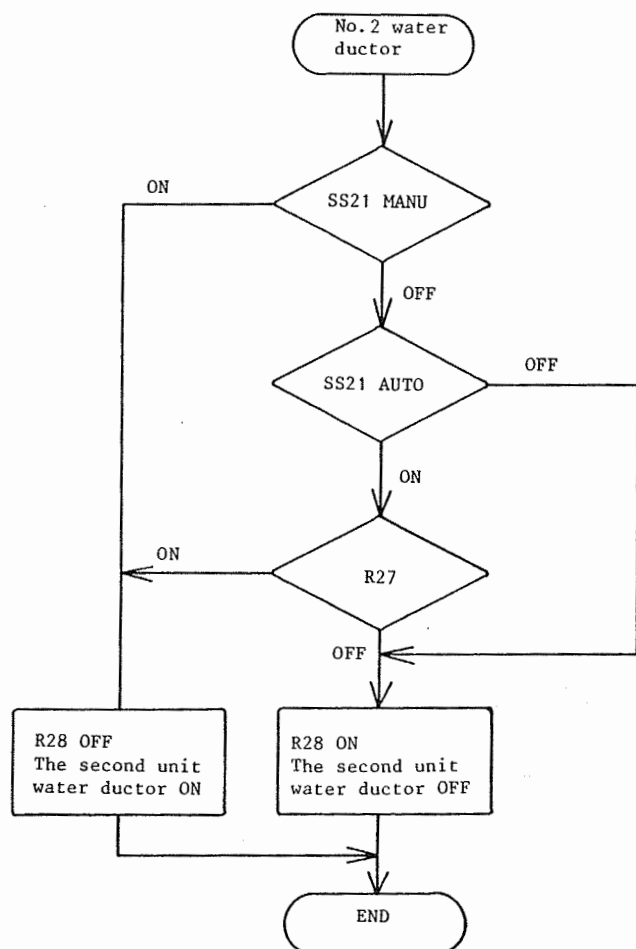
Sign	SS1 MANU	Name	The first unit water ductor manual switch
Check line	L5	Check data	D4
Remarks			

Sign	SS1 AUTO	Name	The first unit water ductor automatic switch
Check line	L5	Check data	D5
Remarks			

Sign	R7	Name	The first unit cylinder ON relay
Remarks			

Sign	R8	Name	The first unit water ductor stop relay
Remarks			

## (22) No. 2 water ductor



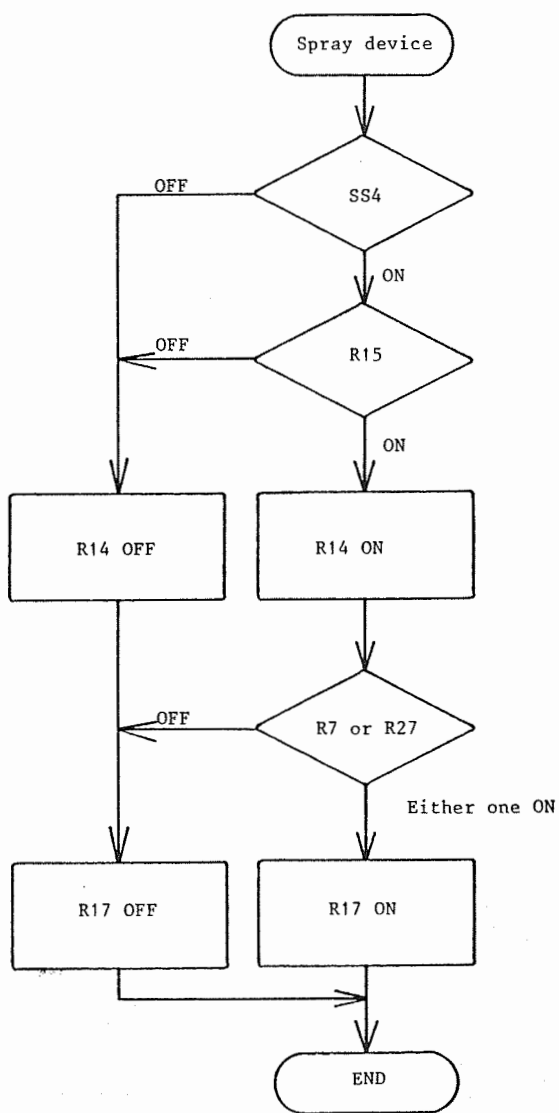
Sign	SS21 MANU	Name	The second unit water ductor manual switch	
Check line	L6	Check data	D4	
Remarks				

Sign	SS21 AUTO	Name	The second unit water ductor automatic switch	
Check line	L6	Check data	D5	
Remarks				

Sign	R27	Name	The second unit cylinder ON relay
Remarks			

Sign	R28	Name	The second unit water ductor stop relay
Remarks			

## (23) Spray device



Sign	SS4	Name	Spray switch
Check line	L4	Check data	D3
Remarks			

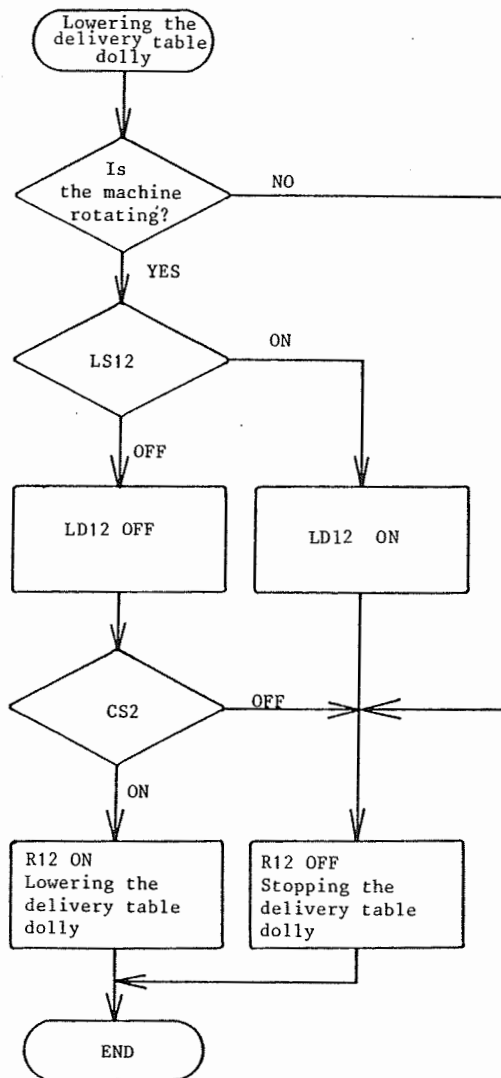
Sign	R15	Name	Pump motor relay
Remarks			

Sign	R14	Name	Spray pump relay
Remarks			

Sign	R7	Name	The first unit cylinder ON relay
Sign	R27	Name	The second unit cylinder ON relay
Remarks			

Sign	R17	Name	Spray valve relay
Remarks			

## (24) Lowering the delivery table dolly



Sign	LS12	Name	Delivery table dolly lower limit switch
Check line	L2	Check data	D6
Remarks			

Sign	LD12	Name	Delivery table dolly lower limit lamp
Remarks			

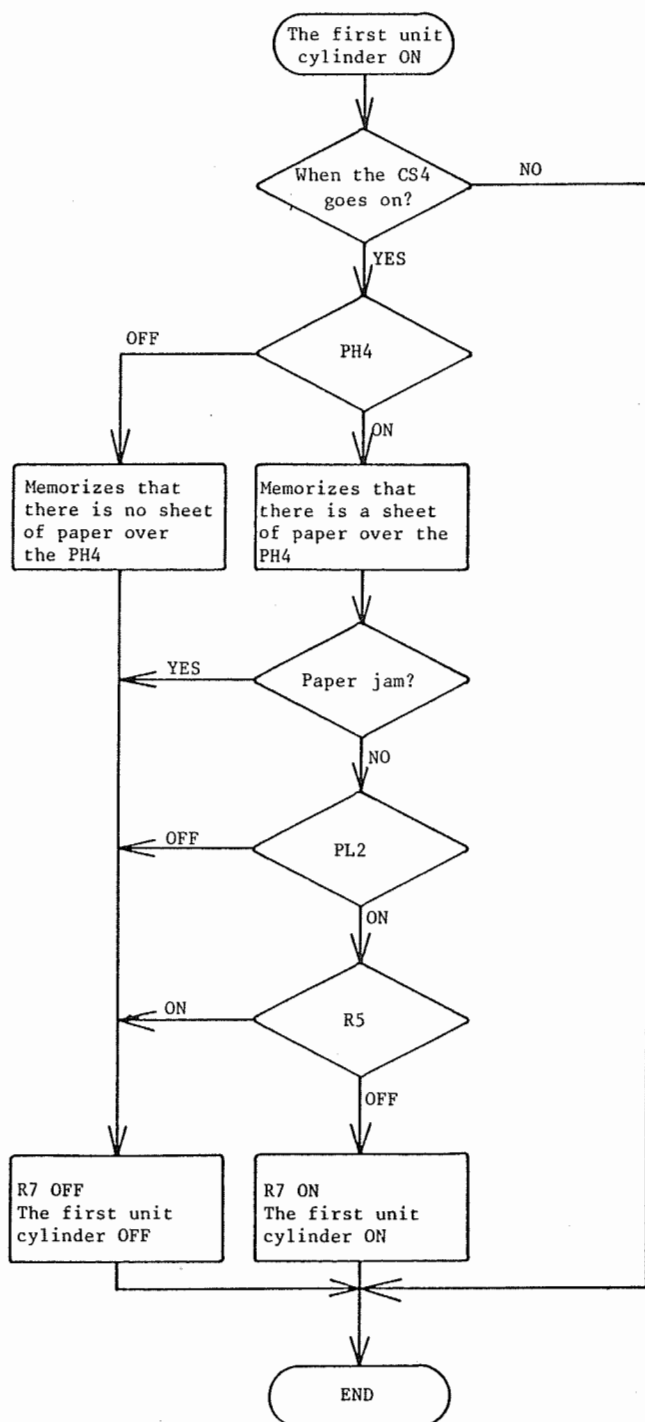
Sign	CS2	Name	Delivery table dolly lowering sensor
Check line	L4	Check data	D6
Remarks			

Sign	R12	Name	Delivery table dolly lowering relay
Remarks			

When the CS2 delivery table dolly lowering sensor actuates ON once, the delivery table dolly lowering relay R12 will turn ON and stay ON for about 3 seconds as written in the software.



## (25) The first unit cylinder ON



Sign	CS4	Name	Timing switch
Check line	IR4	Check data	
Remarks			

Sign	PH4	Name	Impression control sensor
Check line	L4	Check data	E2
Remarks			

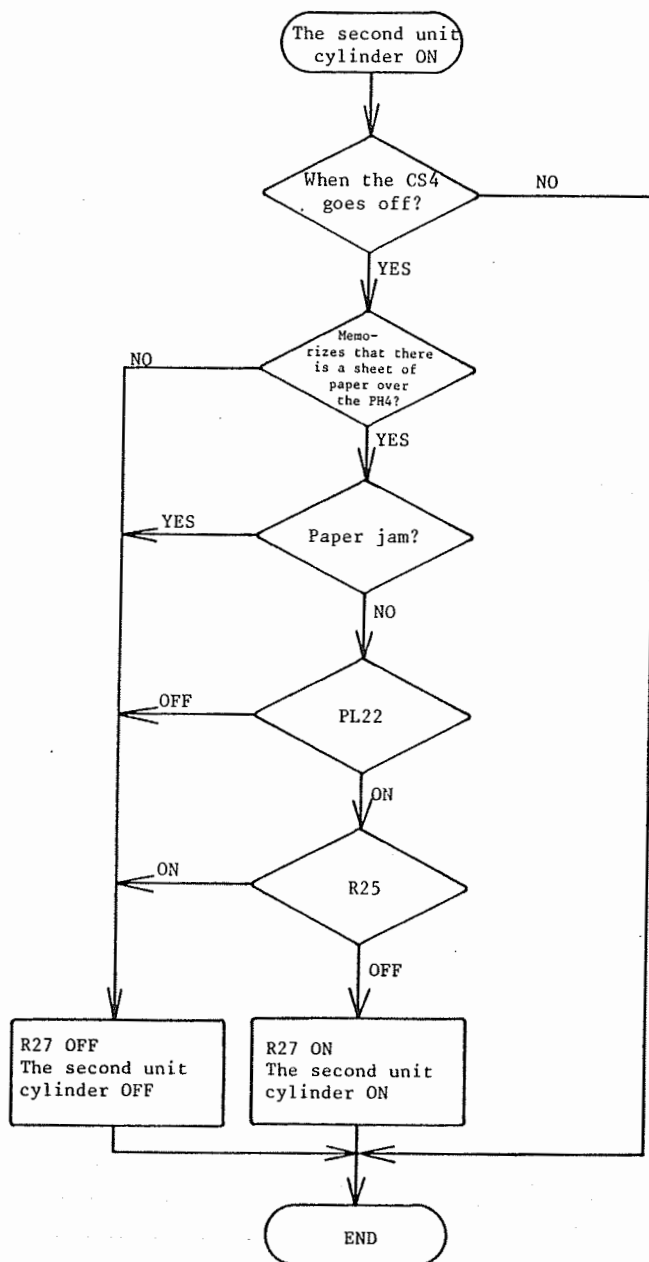
Memorizes whether there is a sheet of paper over the PH4 to judge when turning the second unit cylinder ON or OFF. See (26) The second unit cylinder ON (page 96).

Sign	PL2	Name	The first unit ON/OFF lamp
Remarks			

Sign	R5	Name	The first unit blanket cleaning relay
Remarks			

Sign	R7	Name	The first unit cylinder ON relay
Remarks			

## (26) The second unit cylinder ON



Sign	CS4	Name	Timing switch
Check line	IR2	Check data	
Remarks			

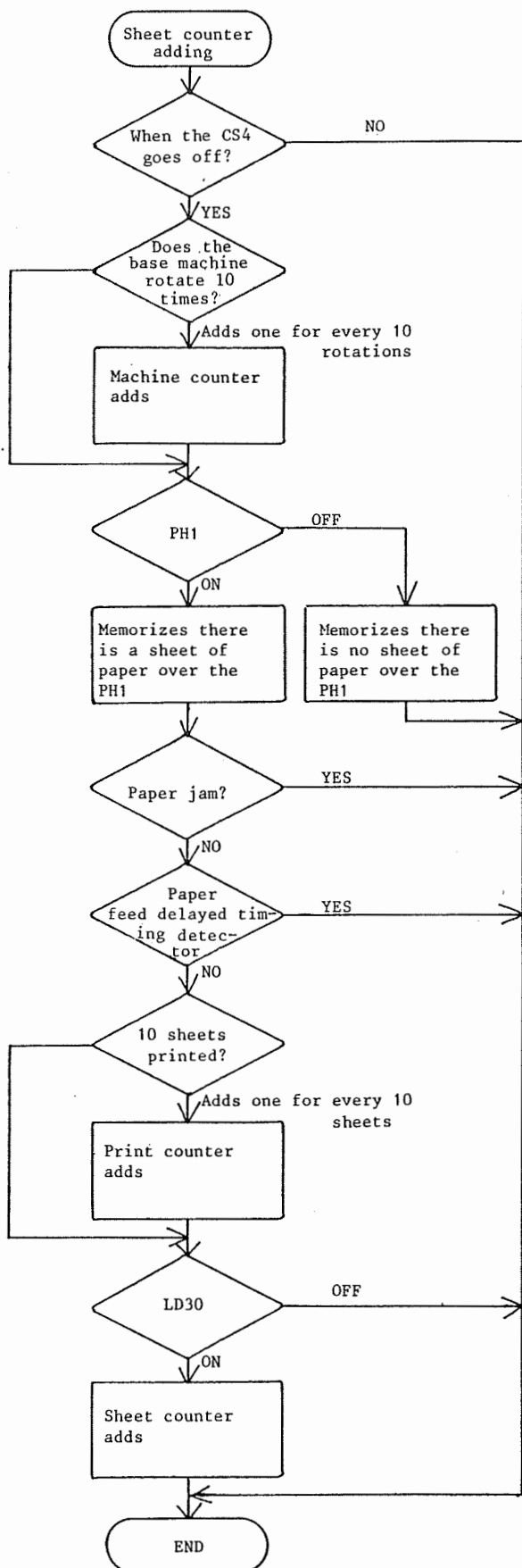
Judges based on the memory whether there is a sheet of paper over the PH4 that is explained on (25) The first unit cylinder ON flow chart (page 95).

Sign	PL22	Name	The second unit ON/OFF lamp
Remarks			

Sign	R25	Name	The second unit blanket cleaning relay
Remarks			

Sign	R27	Name	The second unit cylinder ON relay
Remarks			

## (27) Sheet counter adding



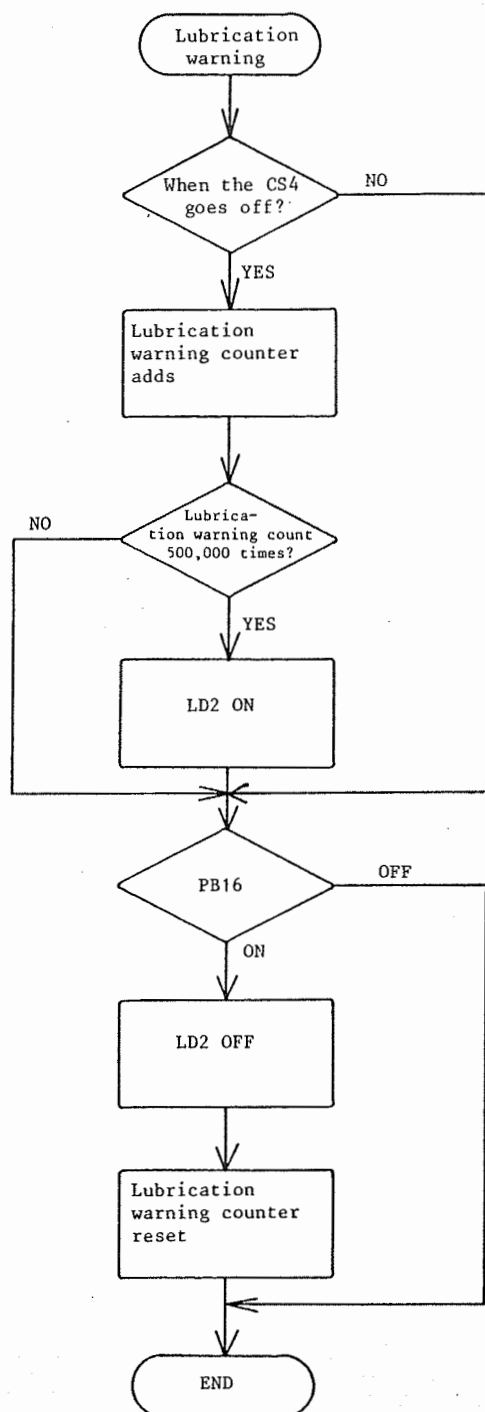
Sign	CS3	Name	Timing switch
Check line	IR1	Check data	
Remarks	When the CS3 turns OFF, each counter adds one.		

Sign	PH1	Name	Feeder photo sensor
Check line	L4	Check data	D0
Remarks			

Memorizes whether there is a sheet of paper over the PH1 to judge for the feeder jam detector.

Sign	LD30	Name	Count ON/OFF lamp
Remarks			

## (28) Lubrication warning



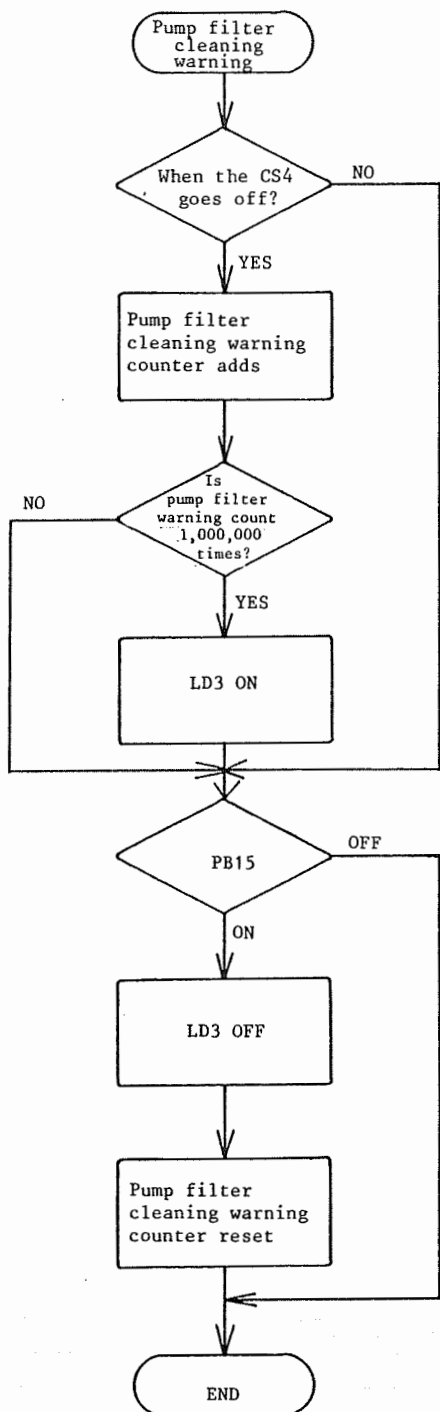
Sign	CS4	Name	Timing switch
Check line	IR2	Check data	
Remarks			

When the CS4 timing switch turns OFF, the counter adds one. When the total number of rotations is over 500,000 rotations, the LD2 lubrication warning lamp lights to signal it is time to lubricate the machine.

Sign	LD2	Name	Lubrication warning lamp
Remarks			

Sign	PB16	Name	Lubrication warning reset button
Check line	L4	Check data	D5
Remarks	When pushing the PB16, the LD2 goes off and the counter is reset.		

## (29) Pump filter cleaning warning



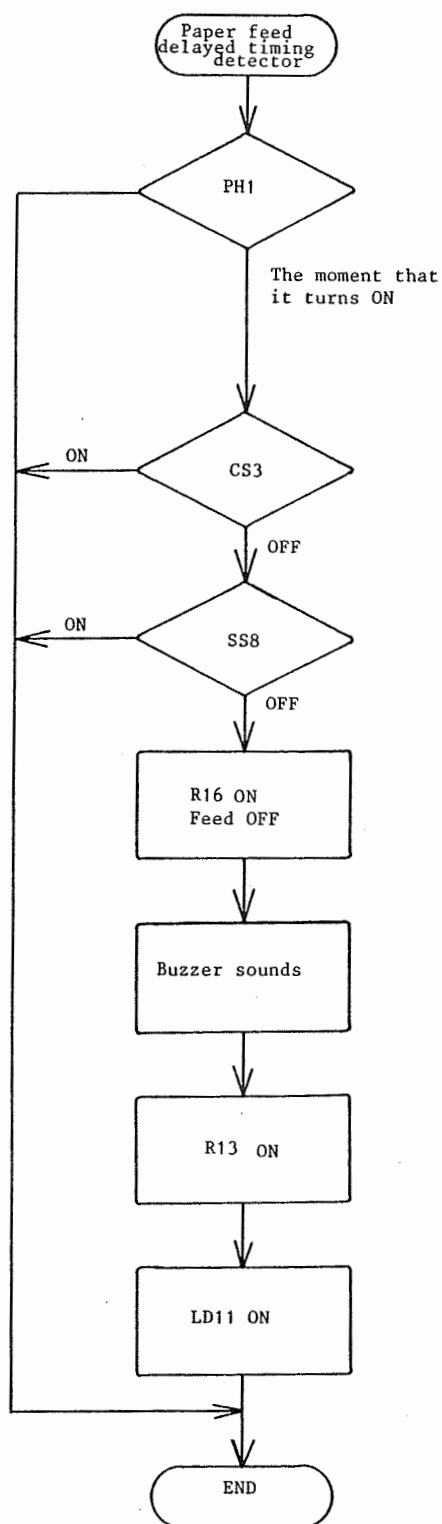
Sign	CS4	Name	Timing switch
Check line	IR2	Check data	
Remarks			

When the CS4 timing switch turns OFF, the counter adds one. When the total number of rotations is over 1,000,000 rotations, the LD3 pump filter cleaning warning lamp lights to signal it is time to clean the pump filter

Sign	LD3	Name	Pump filter cleaning warning lamp
Remarks			

Sign	PB15	Name	Pump filter cleaning warning reset button
Check line	L4	Check data	D4
Remarks	When pushing the PB15, the LD3 goes off and the count is reset.		

## (30) Paper feed delayed timing detector



Sign	PH1	Name	Feeder photo sensor
Check line	L4	Check data	D0
Remarks	The paper feed delayed timing detector detects the moment that the PH1 turns ON.		

Sign	CS3	Name	Timing switch
Check line	L4	Check data	D7
Remarks			

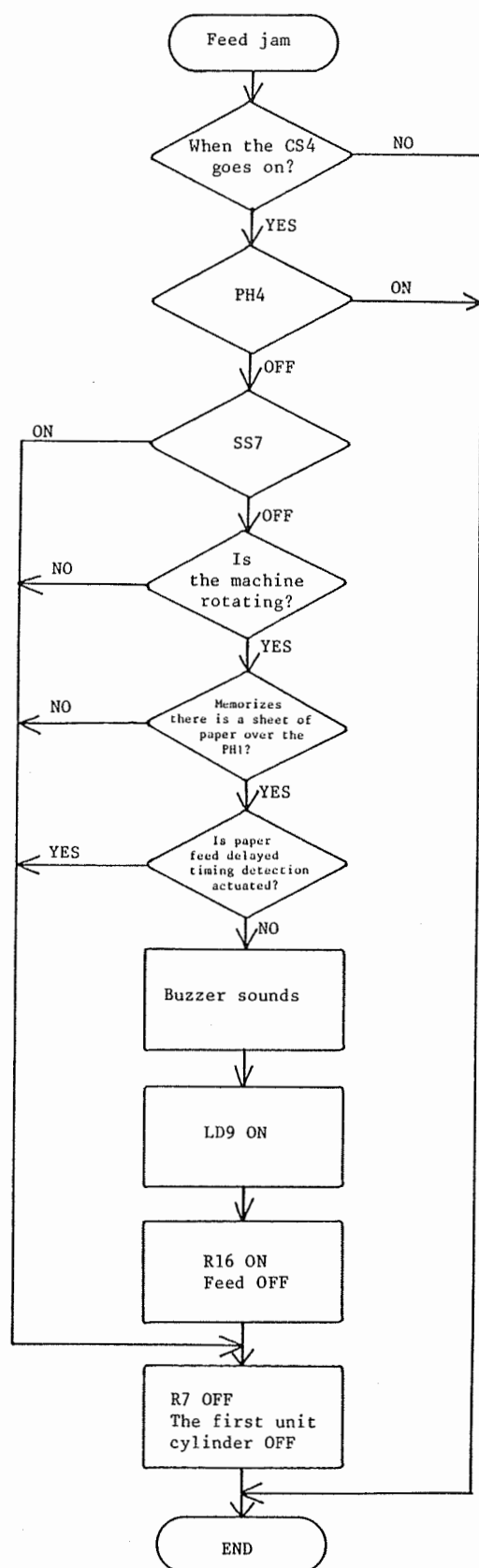
Sign	SS8	Name	Delayed paper OFF switch
Check line	L3	Check data	D7
Remarks			

Sign	R16	Name	Feed OFF relay
Remarks			

Sign	R13	Name	Delayed paper relay
Remarks			

Sign	LD11	Name	Delayed paper lamp
Remarks			

## (31) Feed jam



Sign	CS4	Name	Timing switch
Check line	IR4	Check data	
Remarks			

Sign	PH4	Name	Impression control sensor
Check line	L4	Check data	D2
Remarks	When a sheet of paper is detected, it turns ON.		

Sign	SS7	Name	Feed jam detector OFF switch
Check line	L3	Check data	D6
Remarks			

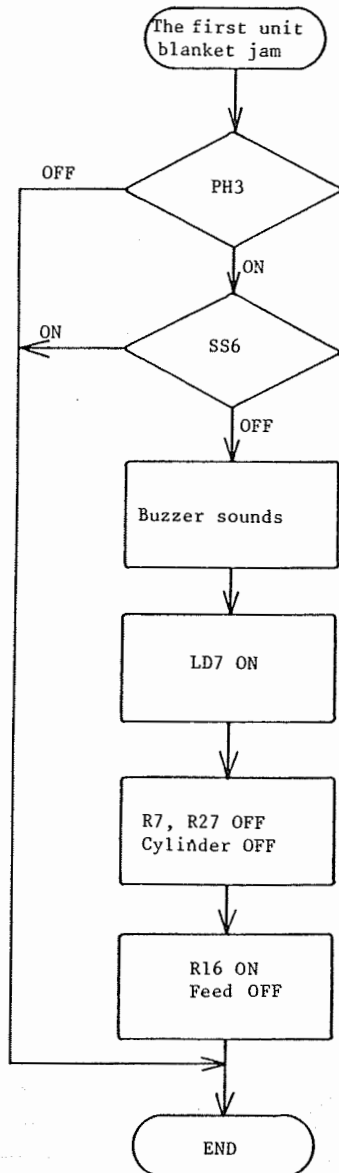
Judges based on the memory whether there is a sheet of paper over the PH1 that is explained on (27) sheet counter adding flow chart (page 97).

Sign	LD9	Name	Feed jam lamp
Remarks			

Sign	R16	Name	Feed OFF relay
Remarks			

Sign	R7	Name	The first unit cylinder ON relay
Remarks			

## (32) The first unit blanket jam



Sign	PH3	Name	The first unit blanket photo sensor	
Check line	IR1	Check data		
Remarks				

Sign	SS6	Name	The first unit blanket jam detector OFF switch	
Check line	L3	Check data	D5	
Remarks				

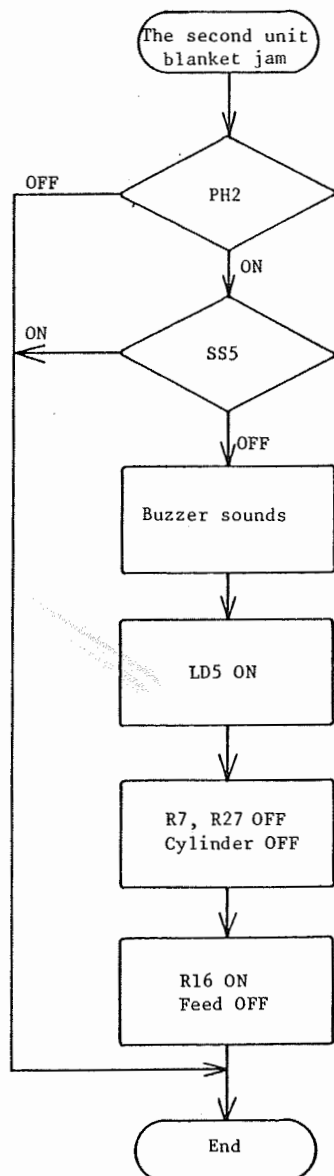
Sign	LD7	Name	The first unit blanket jam lamp
Remarks			

Sign	R7	Name	The first unit cylinder ON relay
Sign	R27	Name	The second unit cylinder ON relay
Remarks			

Sign	R16	Name	Feed OFF relay
Remarks			



## (33) The second unit blanket jam



Sign	PH2	Name	The second unit blanket photo sensor	
Check line	IR5		Check data	
Remarks				

Sign	SS5	Name	The second unit blanket jam detector OFF switch	
Check line	L3	Check data	D4	
Remarks				

Sign	LD5	Name	The second unit blanket jam lamp
Remarks			

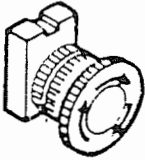
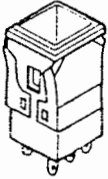
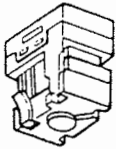
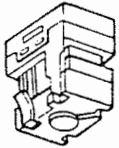
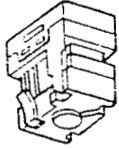
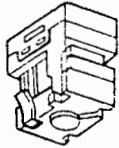
Sign	R7	Name	The first unit cylinder ON relay
Sign	R27	Name	The second unit cylinder ON relay
Remarks			


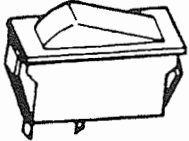
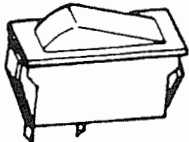
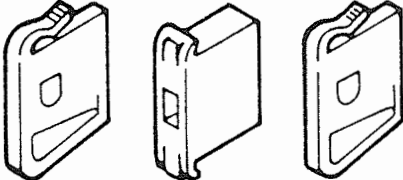
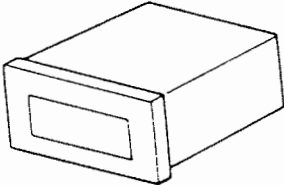

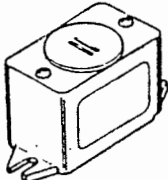
Sign	R16	Name	Feed OFF relay
Remarks			

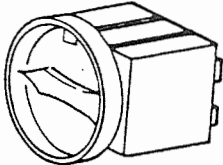
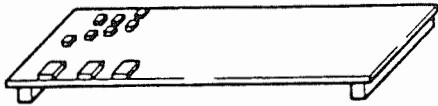
## 18. List of replacement parts

When ordering replacement parts, please use the specified parts number indicated in ( ).

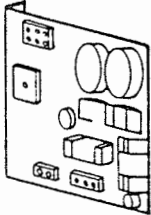
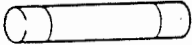
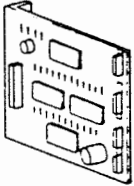
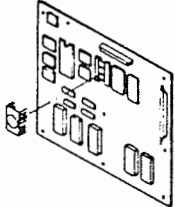
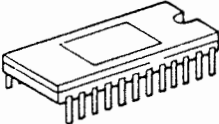
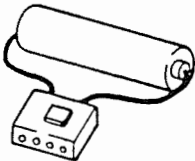
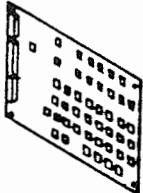
## (1) Operation panel

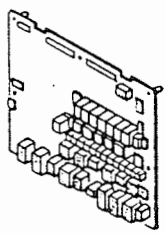
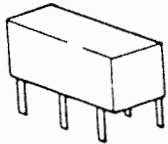
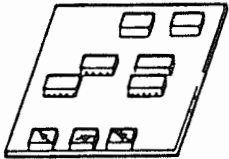
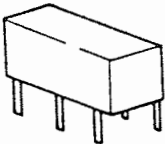
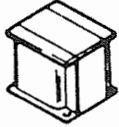
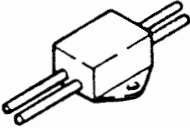
(IZUMI)  LED LSHD-28R (98 930) AVLW322T20D-R(96 606)	PB1, PL1 PB21, PL21
(OMRON)  A3SA-7050-T(96 564)	PB2, PB3, PB4 PB22, PB23, PB24 PB15, PB16
(OMRON)  (96 591) A3SA-5801-N(White)	PB4 PB24 Unit ON-OFF
(OMRON)  (96 592) A3SA-5802-N(Ped)	PB3 PB23 Inching reverse rotation
(OMRON)  (96 593) A3SA-5803-N(Green)	PB2 PB22 Inching normal rotation
(OMRON)  (96 594) A3SA-5805-N(Yellow)	PB15, PB16 Warning lamp reset button

<p>(OMRON)</p>  <p>SLL-24EY(98 926)</p>	<p>PL2, PL22 PL4, PL5</p>
<p>(IZUMI)</p>  <p>C-1420F-B(96 559)</p>	<p>SS1, SS2 SS21, SS22 Ductor control</p>
<p>(IZUMI)</p>  <p>C-1400F-B(96 560)</p>	<p>SS4 Spray switch</p>
<p>(IZUMI)</p>  <p>Switch DGAN-031-B(96 561), End plate DGNW-1-B(96 562)</p>	<p>DS1 Blanket cleaning cycle set</p>
<p>(OMRON)</p>  <p>H7EC-BLM(97 864)</p>	<p>Print counter Machine counter</p>
<p>(NIKKAI)</p>  <p>Switch M-2012J-2G(96 549), Bezel AT-207G(96 550)</p>	<p>SS5, SS6, SS7, SS8 Jam ON-OFF switch</p>
<p>(NATIONAL)</p>  <p>Buzzer E.B 2124</p>	<p>BZ1 Buzzer for jam</p>

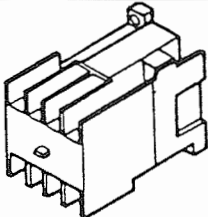
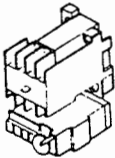
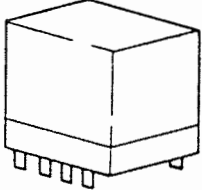

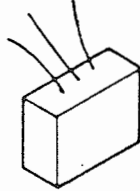
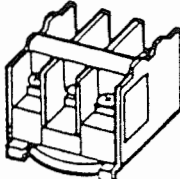
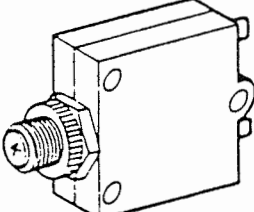
<p>(KLOCKNER-MOELLER)</p>  <p>P1-25/Svb(97 729)</p>	<p>Main switch</p>
 <p>Main operation panel board(5340 61 648)</p>	

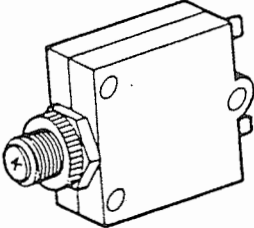

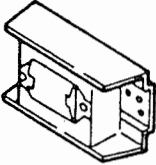
## (2) Control box

	<p>Power source circuit board (5330 61 643-1)</p>
 <p>Fuse 6.4 X 30 10A(97 722)</p>	
 <p>Sensor printed circuit board(5330 61 644-2)</p>	
	<p>CPU board With P-ROM (5340 61 640-2) Without P-ROM (5330 61 641)</p>
	<p>P-ROM (5340 61 801-1)</p>
	<p>Battery ASSY (5330 61 646)</p>
	<p>Display controller (5340 61 645)</p>

 <p>Connector board (5340 61 642-1)</p>	
<p>(NATIONAL)</p>  <p>DSP1-DC24V(97 190)</p>	
 <p>Inverter controller (5340 61 647)</p>	
<p>(OMRON)</p>  <p>G6A-274P-DC24V(97 192)</p>	
 <p>PT-19 (97 976)</p>	
<p>(TDK)</p>  <p>ZGB2203-01(99 779)</p>	

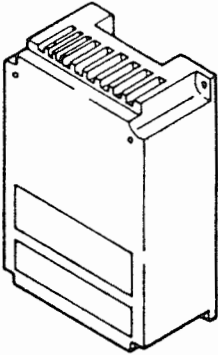
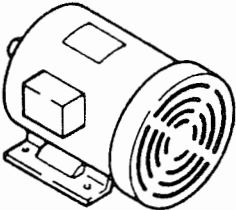

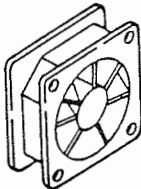
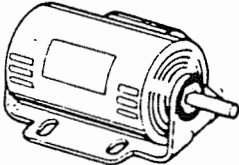
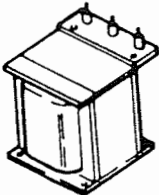
## (3) Sub control box

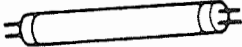
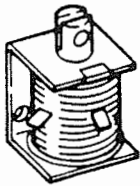
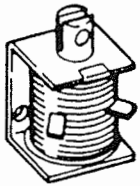
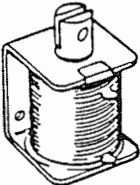
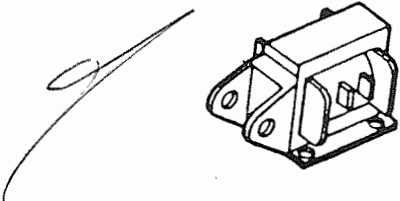
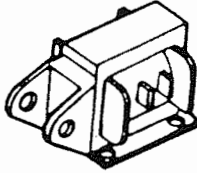
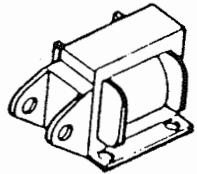
<p>(MITSUBISHI)</p>  <p>S-K11 AC120V (97 165)</p>	Single phase machine
<p>(MITSUBISHI) MSO-K11 (97 166)</p> <p>(OMRON)</p> <p>Contactor LC1-D093A60 (97 201)</p> <p>Thermal LR1-D09 310 (97 202)</p>	 <p>Three phase machine UL machine</p>
<p>(OMRON)</p>  <p>LY-2N DC24V (97 125)</p>	
<p>(MARUKON)</p>  <p>DCR2-20D50 (99 772)</p>	
<p>(MARUKON)</p>  <p>RFM2H664KPD (99 771)</p>	
<p>(IZUMI)</p>  <p>Terminal base BA211T (98 982)</p> <p>Separator BNL5(98 984)</p>	
<p>(AMP)</p>  <p>Circuit protector4A (97 703)</p>	For Europe machine only

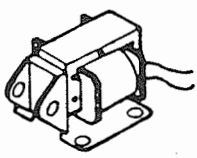
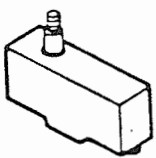
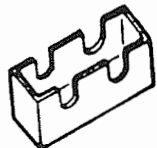
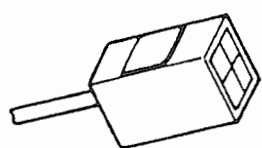
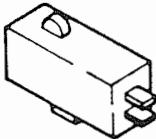
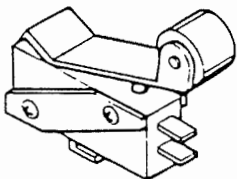
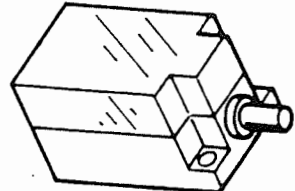
<p>(AMP)</p>  <p>Circuit protector 7A (97 702)</p>	<p>For Europe machine only</p>
<p>(NATIONAL)</p>  <p>Glow lamp FG-1E(99 928)</p>	
<p>(NATIONAL)</p>  <p>Fluorescent lamp stabilizer</p> <p>50Hz ..... FZ15111-349 (99 963) 60Hz ..... FZ15111-249 (99 962) UL type... GX15112MA-svb (955 11 001)</p>	

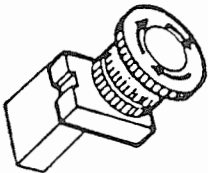
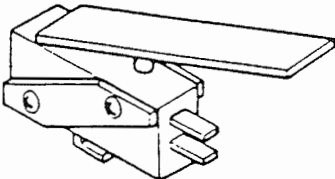
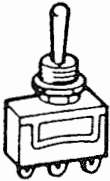
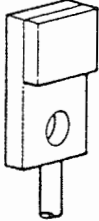
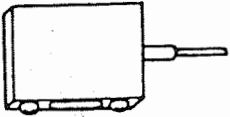
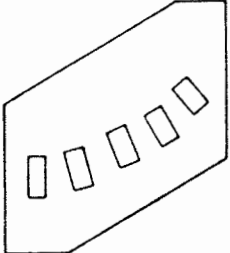
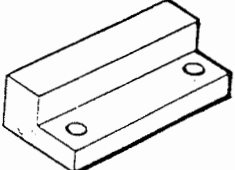


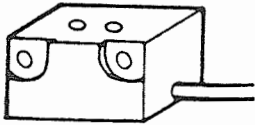
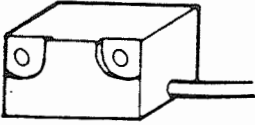
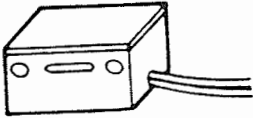
## (4) Parts outside the panel

<p>(MITSUBISHI)</p>  <p>Inverter FRZ120 1.5kW (96 051) UL type (951 03 002)</p>	
<p>(MITSUBISHI)</p>  <p>SB-JR 1.5kW (97 038) UL type (951 01 001)</p>	Drive motor
<p>(MITSUBISHI)</p>  <p>Noise absorber BKO-C1947H01 (99 776)</p>	
<p>(TOUBISHI)</p>  <p>U12CB9(UL)+A-40 (99 953)</p>	
<p>(MITSUBISHI)</p>  <p>Single phase SCL-KR550W 210V (97 054) Three phase SB-JR 0.75kW (97 034)</p>	Pump motor
 <p>Auto-transformer SRB 12UL (97 975) Compound transformer DRB 12UL (97 974)</p>	

	<p>Fluorescent lamp 15W (99 960)</p>
<p>(CKD)</p> 	<p>MS-10J811-145 (97 628)</p> <p>Ink ductor stop</p>
<p>(CKD)</p> 	<p>MS-10J811-111 (97 602)</p> <p>Water ductor stop</p>
<p>(CKD)</p> 	<p>MS-35J803-123 (97 603)</p> <p>Shutter</p>
<p>(CKD)</p> 	<p>AS-03A 721-152 (97 606-1)</p> <p>Lever advance Lever return Delayed paper</p>
<p>(CKD)</p> 	<p>AS-05N 703-188 (97 632)</p> <p>The first unit cylinder ON Lowering the delivery table dolly</p>
<p>(CKD)</p> 	<p>AS-05N 703-177 (97 630)</p> <p>Feed stop The second unit cylinder ON</p>

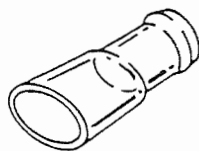
(CKD)		AS-20N 708-015 (97 657)	Blanket cleaning
(OMRON)		Z-15GS-B (95 119)	Double sheet detector
(OMRON)		AP-B (95 117)	
(OMRON)		TL-Q3 (97 812)	Plate cylinder setting position stop
(OMRON)		V-1C2 (97 303)	Safety cover
(OMRON)		V-1C244 (97 313) VAM22 (97 381)	Delivery table dolly lower limit
(FUJI)		WK244XP-2μ (95 338)	Safety bar

(IZUMI)		AVW401-R (96 519)	Emergency stop (Delivery side)
(OMRON)		D2MV-5L111-1C2 (97 332)	Delivery jam
(NATIONAL)		AJ4534 (96 589)	Feed switch
(SUNX)		GXL-12F+MS-GXL-12 (97 837)	Timing switch
(KOYO)		CS-16-5N (96 531)	Delivery table dolly lower switch
		(5330 61 321)	Operation lever switch
(NIPPON AUTOMATION)		RS-9M (97 501)	

(OMRON)		ORE-S5 (97 805) Sensor assy (5340 61 612)	Impression control sensor (PH4)
(OMRON)	 <i>534094823</i>	OAS-61LD-2 (97 823) Sensor assy (5340 61 611)	Feeder board photo sensor (PH1)
		(5330 61 614)	Blanket jam sensor (PH2), (PH3) <i>ord 624830</i>

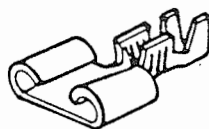
(5) Parts for connecting

(AMP)



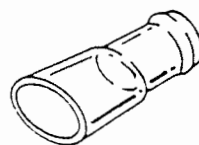
Faston cover 170823-1 (110 series) (98 682)

(AMP)



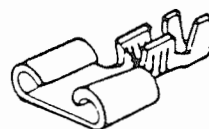
Faston terminal 42470-1 (For 110 series) (98 681)

(AMP)



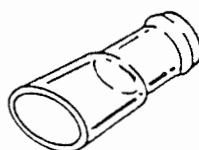
Faston cover 170892-1 (187 series) (98 514)

(AMP)



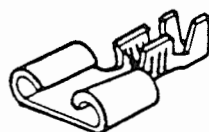
Faston terminal 170038-1 (For 187 series) (98 500)

(AMP)



Faston cover 1-170823-5 (250 series) (98 536)

(AMP)



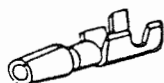
Faston terminal 42731-2 (For 250 series) (98 647)

(AMP)



Share plug (Receptacle) 170021-1 (98 538)

(AMP)



Share plug (Plug) 170020-1 (98 540)

(AMP)



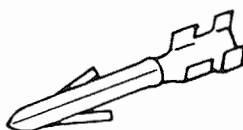
Insulation sleeve (For receptacle) 170889-1 (98 539)

(AMP)



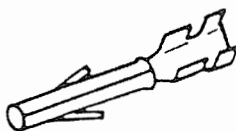
Insulation sleeve (For plug) 170887-1 (98 541)

(AMP)



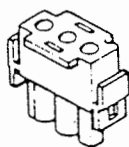
Pin for universal mate-n-lock 350690-3 (98 787)

(AMP)



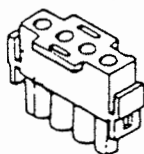
Socket for universal mate-n-lock 350689-3 (98 788)

(AMP)



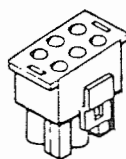
Universal mate-n-lock connector (3P) 1-480700-0 (98 728)

(AMP)



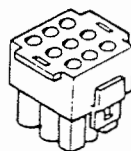
Universal mate-n-lock connector (4P) 1-480702-0 (98 680)

(AMP)



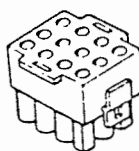
Universal mate-n-lock connector (6P) 1-480704-0 (98 679)

(AMP)



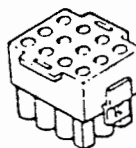
Universal mate-n-lock connector (9P) 1-480706-0 (98 639)

(AMP)



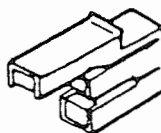
Universal mate-n-lock connector (12P) 1-480708-0 (98 793)

(AMP)



Universal mate-n-lock connector (15P) 1-480710-0 (98 640)

(AMP)



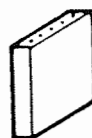
Faston socket 360010-1 (For V-shaped switch) (98 501)

(AMP)



Pin for CIS 163691-1 (98 560)

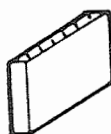
(AMP)



CIS male connector Housing 6P 163690-4 (98 795)

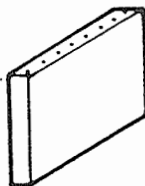


(AMP)



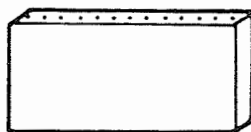
CIS male connector Housing 8P 163690-6 (98 550)

(AMP)



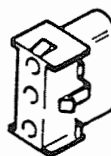
CIS male connector Housing 10P 163690-8 (98 551)

(AMP)



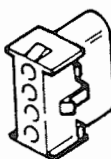
CIS male connector Housing 16P 1-163690-5

(AMP)



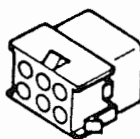
Universal mate-n-lock connector cap 3P 1-480701-0 (98 876)

(AMP)



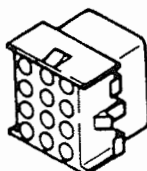
Universal mate-n-lock connector cap 4P 1-480703-0 (98 737)

(AMP)



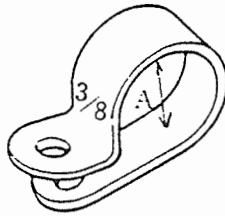
Universal mate-n-lock connector cap 6P 1-480705-0 (98 784)

(AMP)



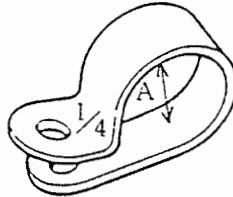
Universal mate-n-lock connector cap 12P 1-480709-0 (98 799)

(HEYCO)

 $A = 9.1\text{mm}$ 

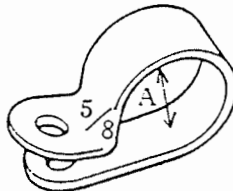
Nylon clamp 3306 (98 806)

(HEYCO)

 $A = 5.9\text{mm}$ 

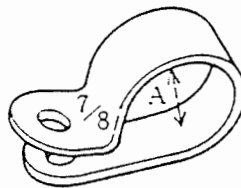
Nylon clamp 3304 (95 150)

(HEYCO)

 $A = 15.9\text{mm}$ 

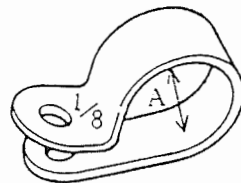
Nylon clamp 3330 (98 809)

(HEYCO)

 $A = 21.9\text{mm}$ 

Nylon clamp 3334 (95 151)

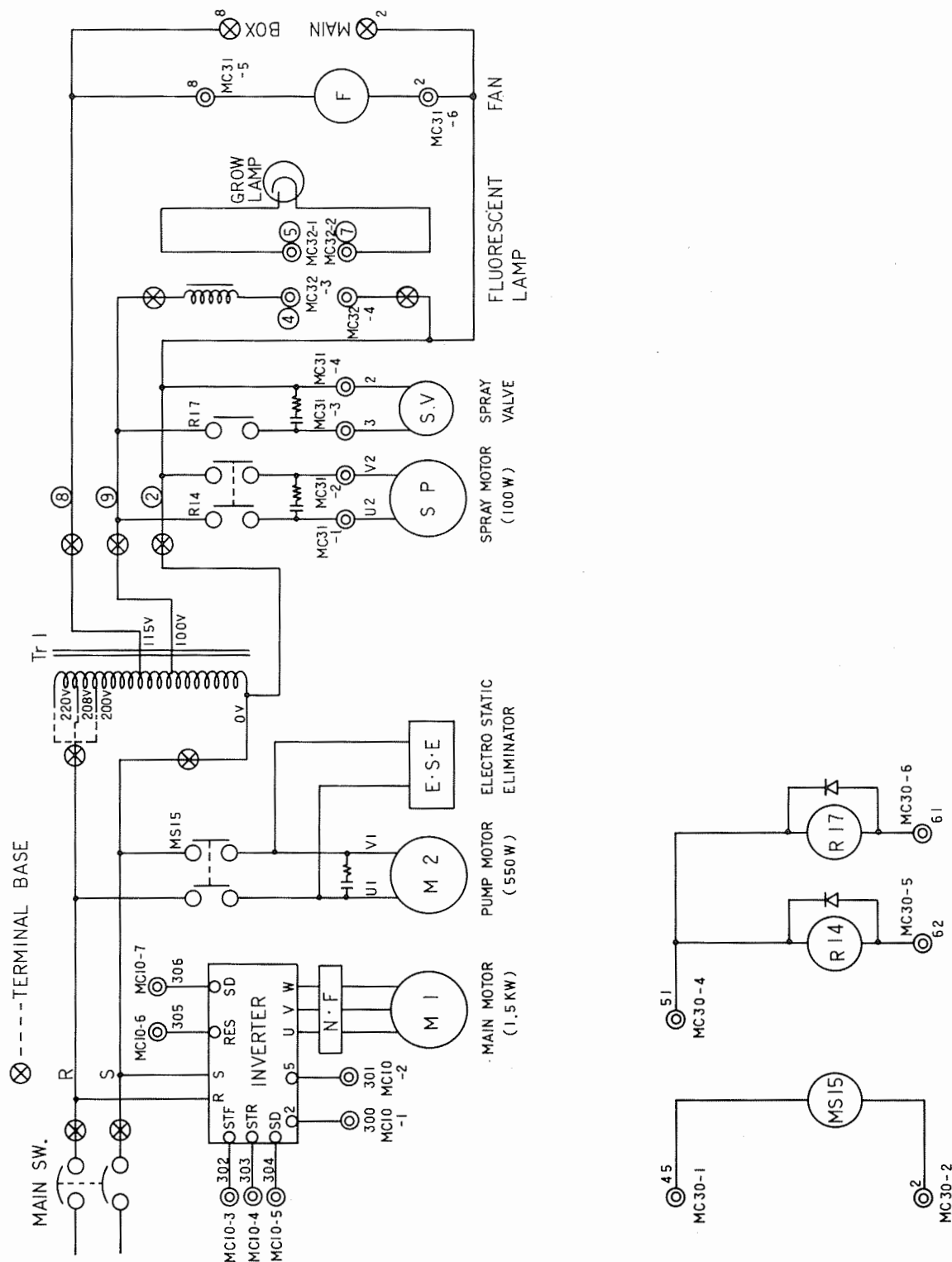
(HEYCO)

 $A = 2.9\text{mm}$ 

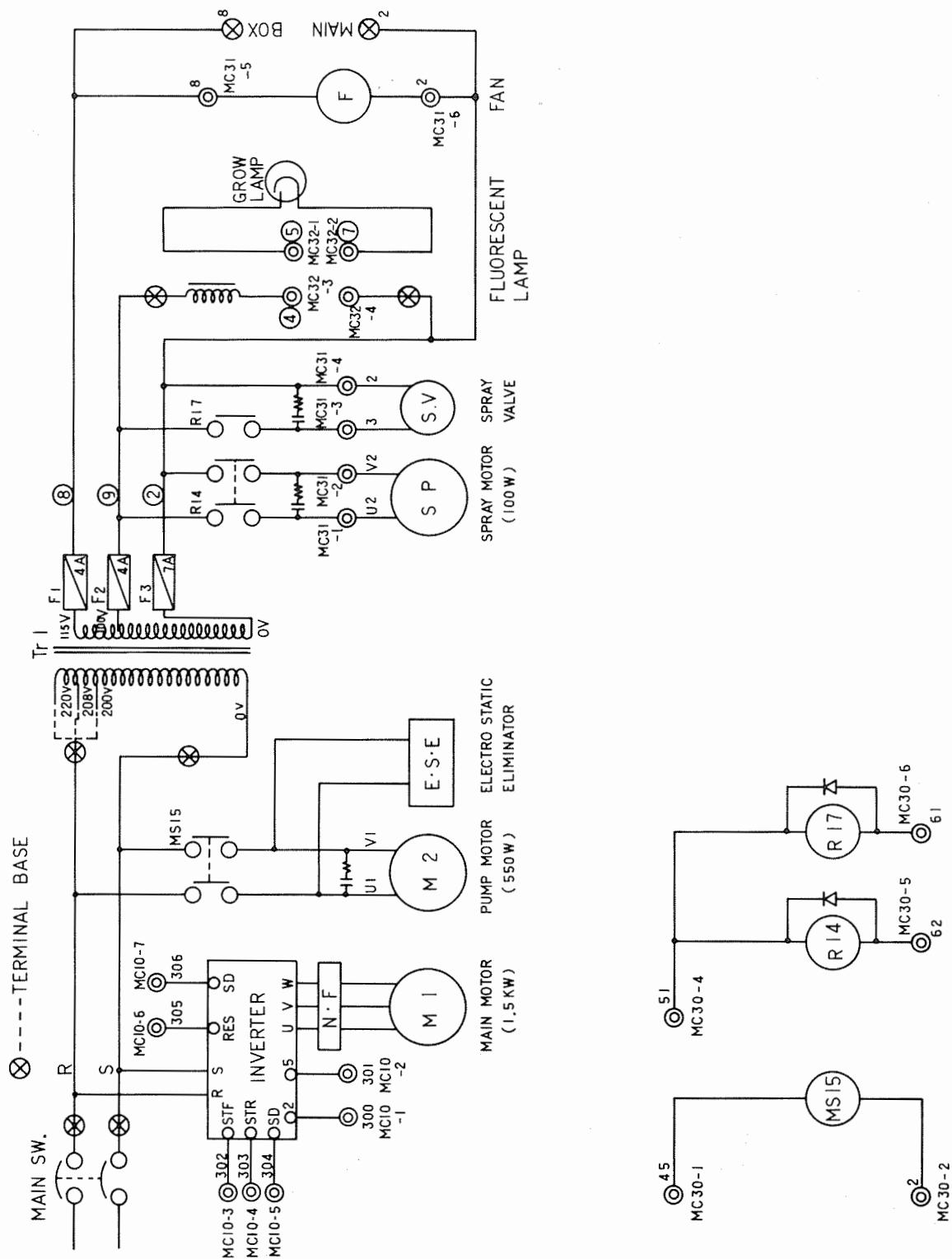
Nylon clamp 3302 (98 805)

## 19. Electrical circuit diagrams

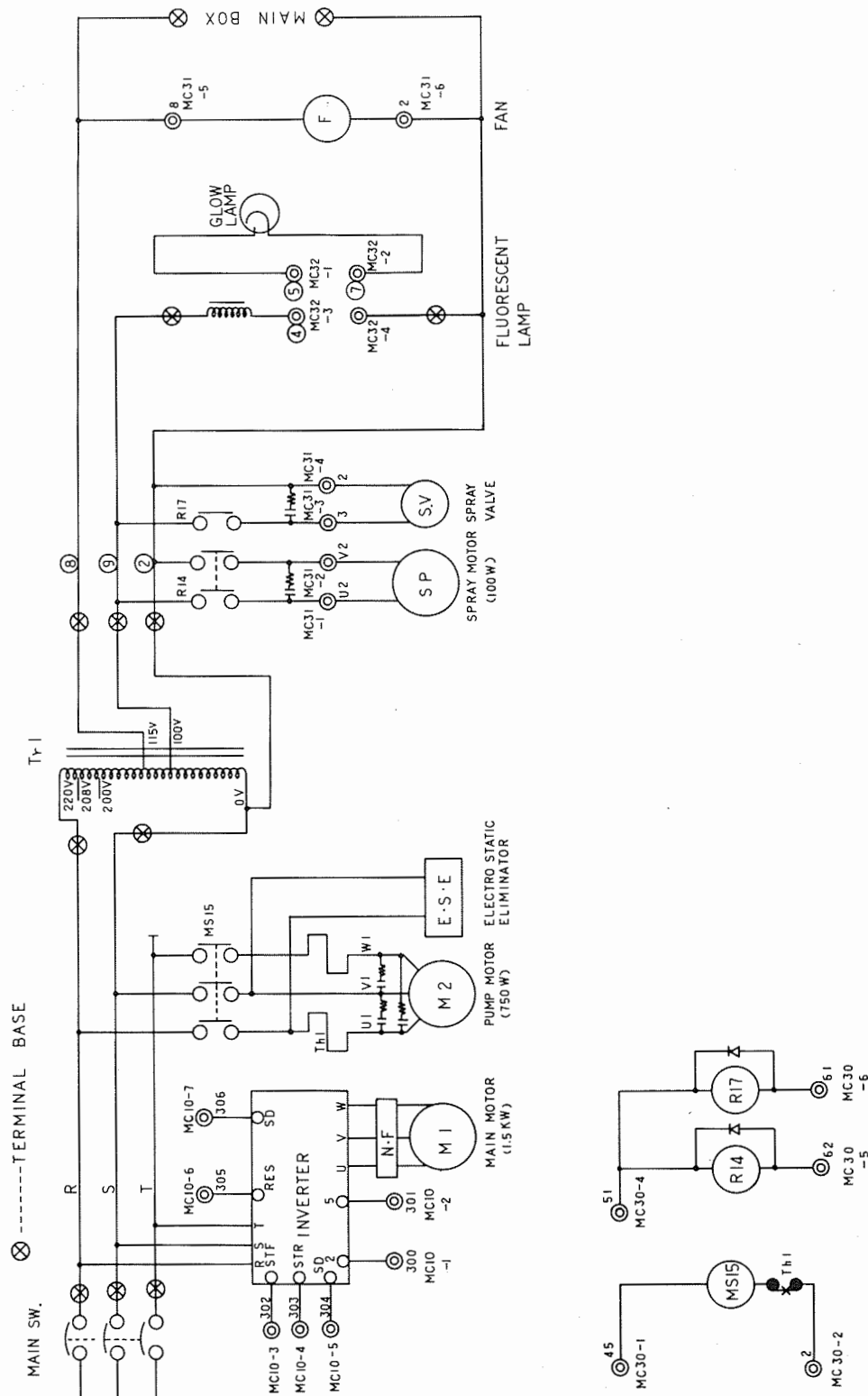
- (1) Sub control box circuit diagram  
 a) Single phase except for Europe



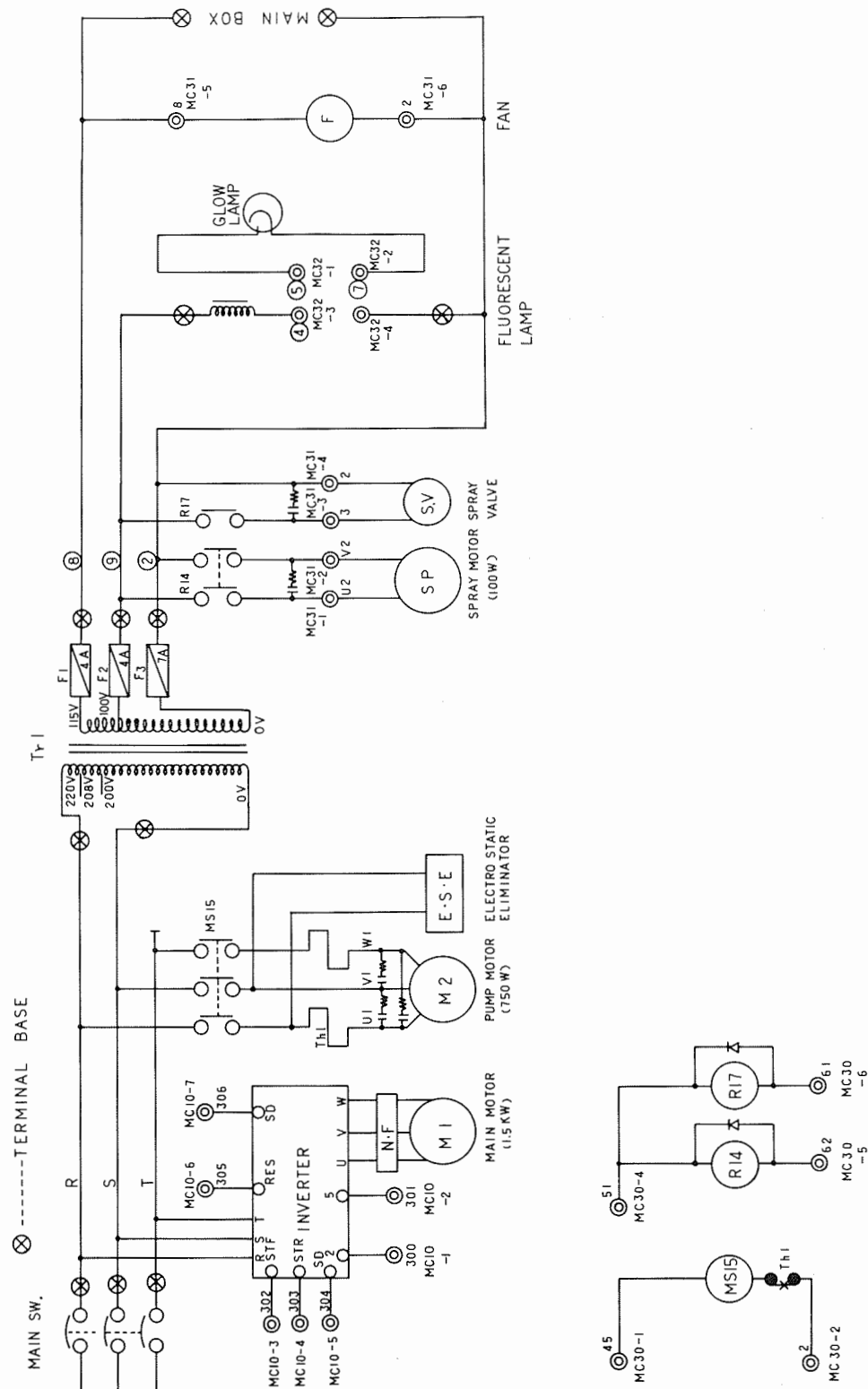
b) Single phase for Europe



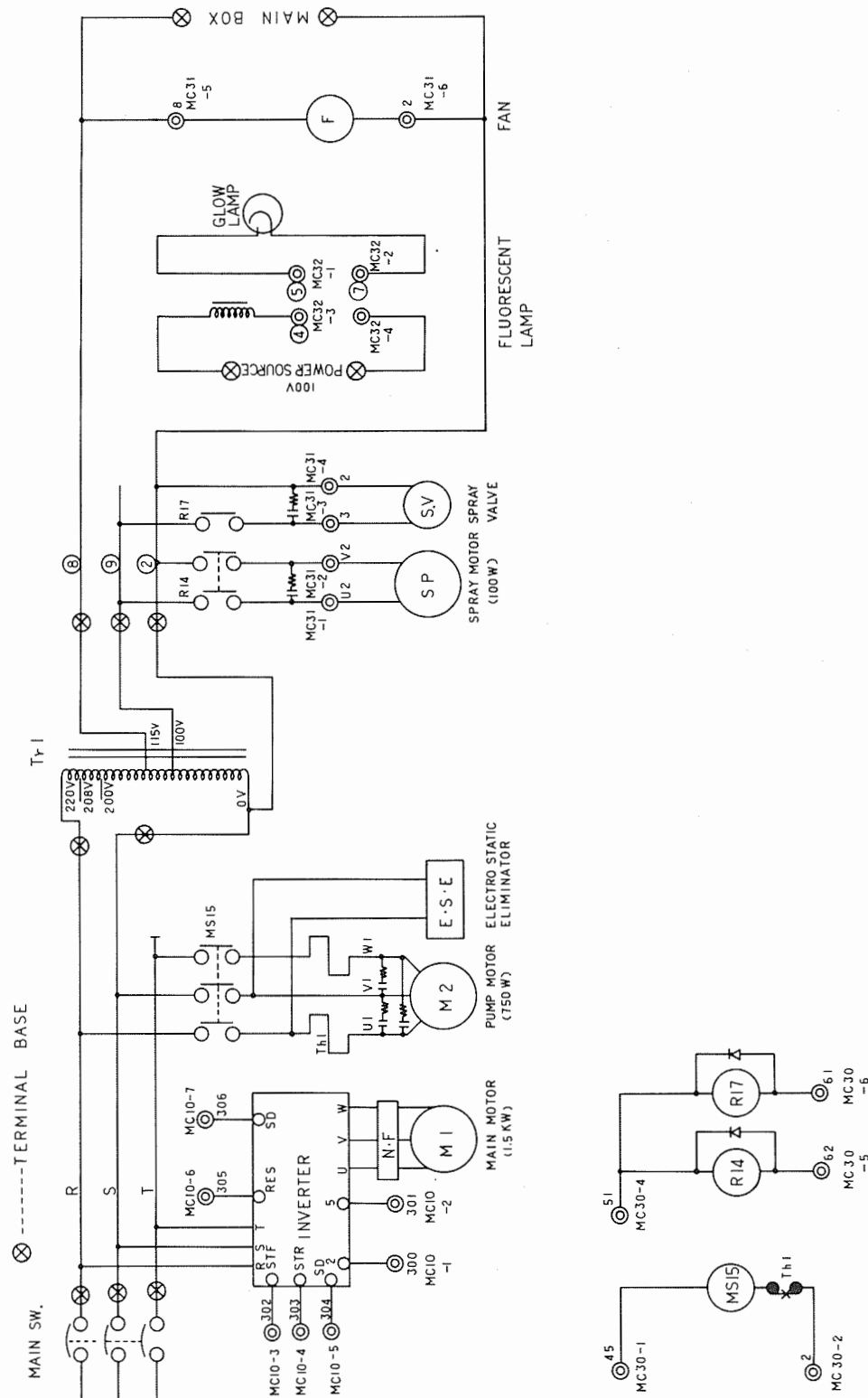
c) Three phase except for Europe



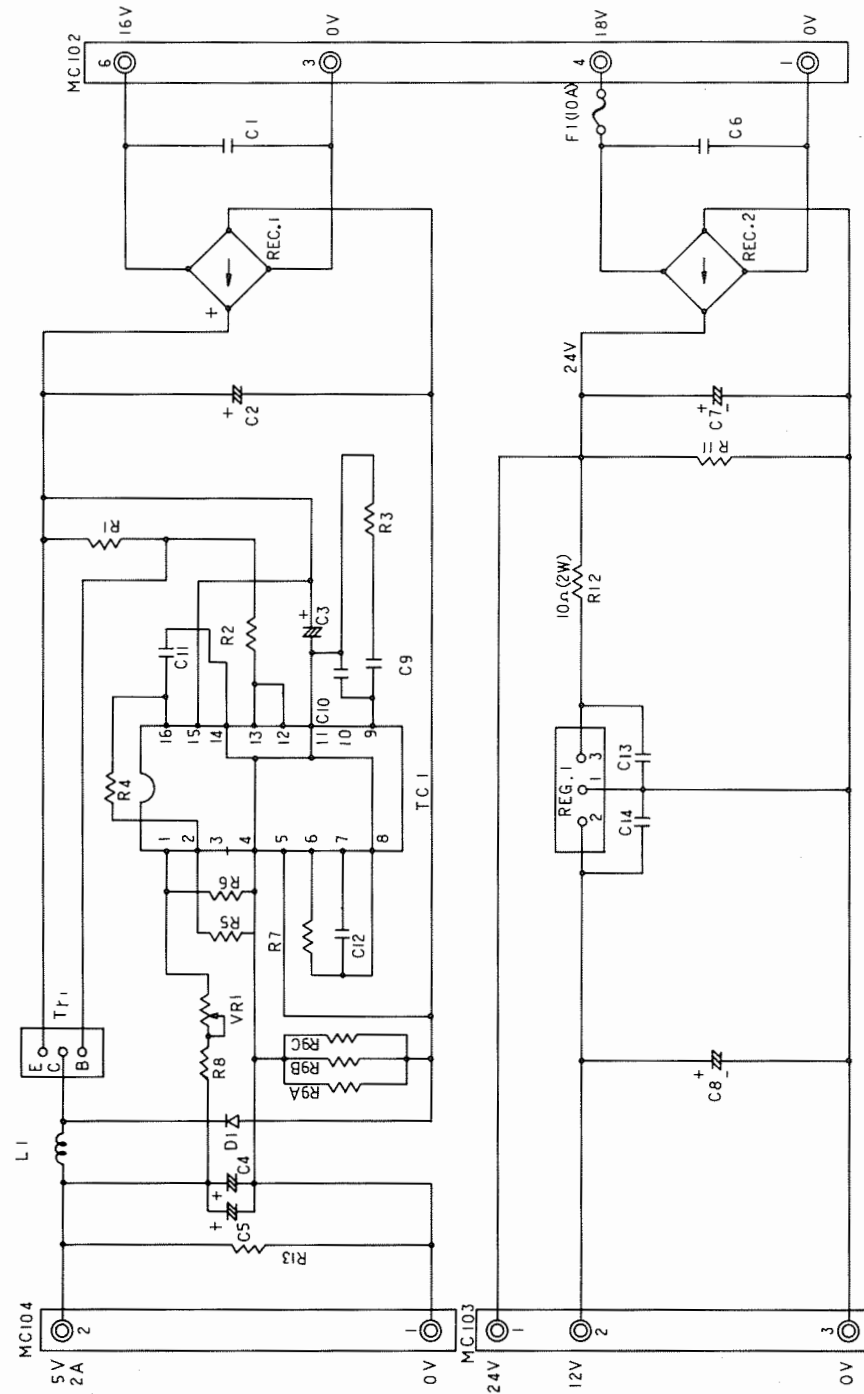
## d) Three phase for Europe



## e) Three phase for the domestic

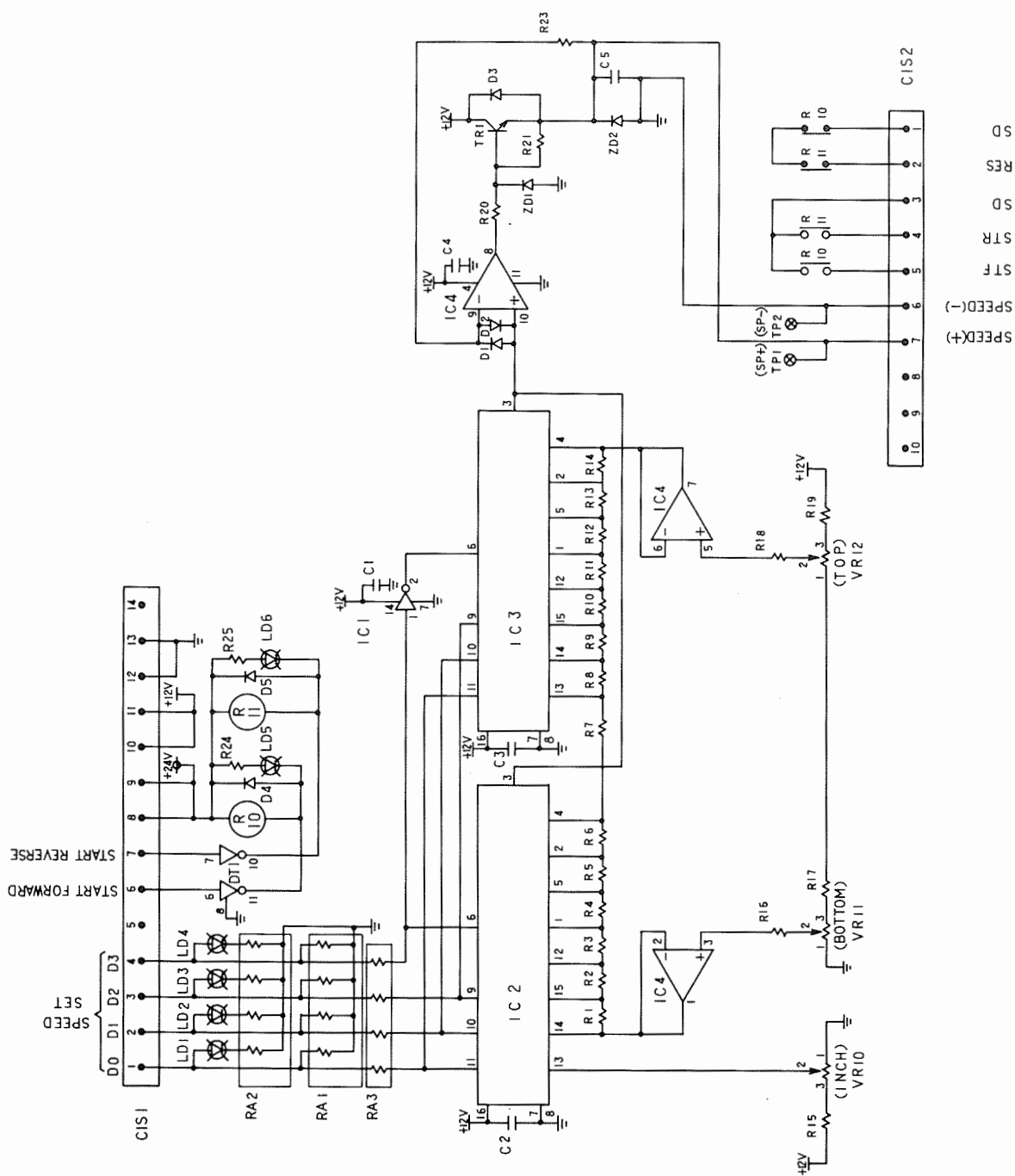


(2) Power source circuit board



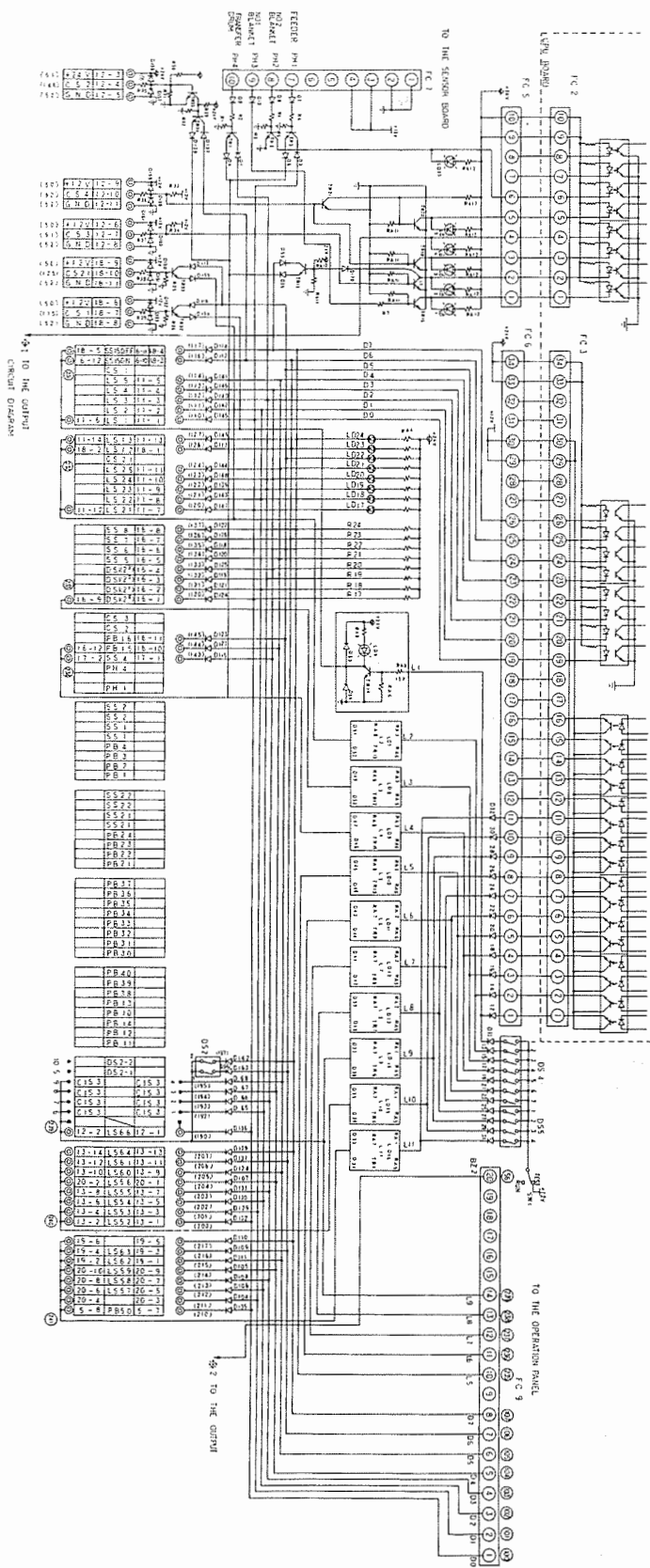


## (3) Inverter control circuit



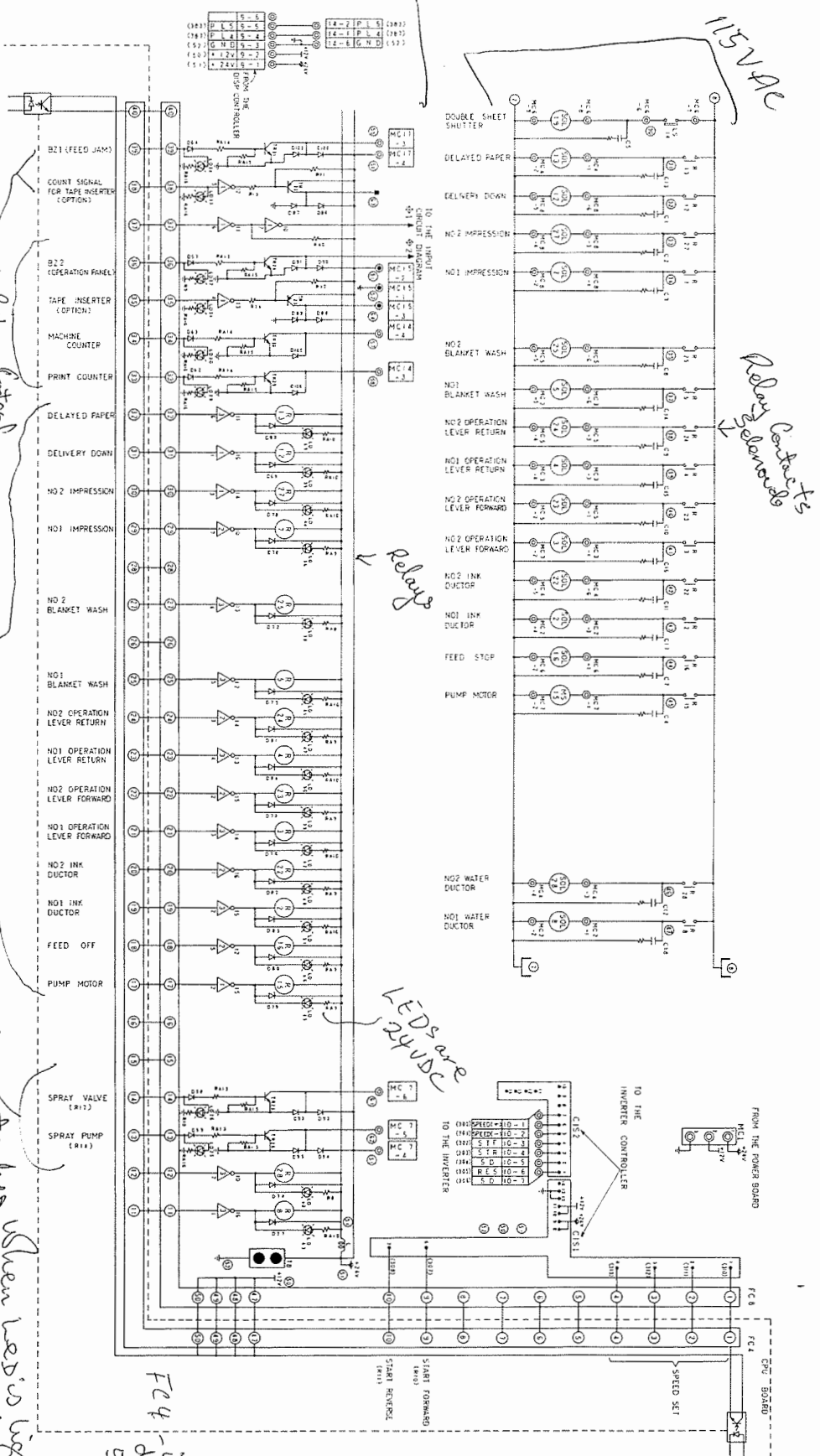


(4) Connector board  
a) Input circuit diagram

[illegible]



b) Output circuit diagram



All relays are the same

Relay contacts

Relays

LEDs are 24 VDC

FC 4 - 10 whole dotted lines 50 pin contact

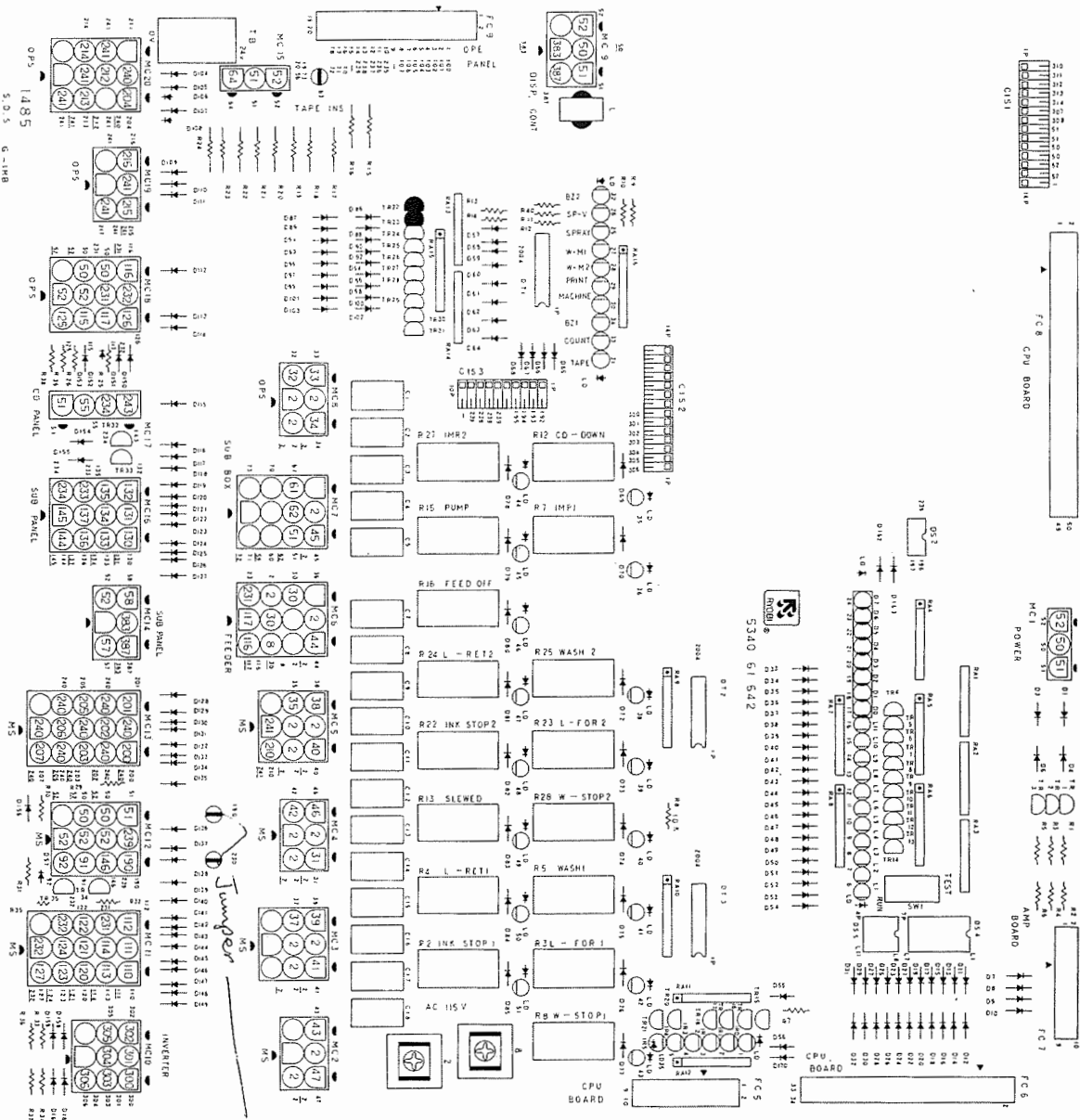
No relay control this circuit transfers

Control by 24 VDC relays

When led is light only means signals are sent dose not mean relay is good.



c) Parts arrangement diagram on the connector board

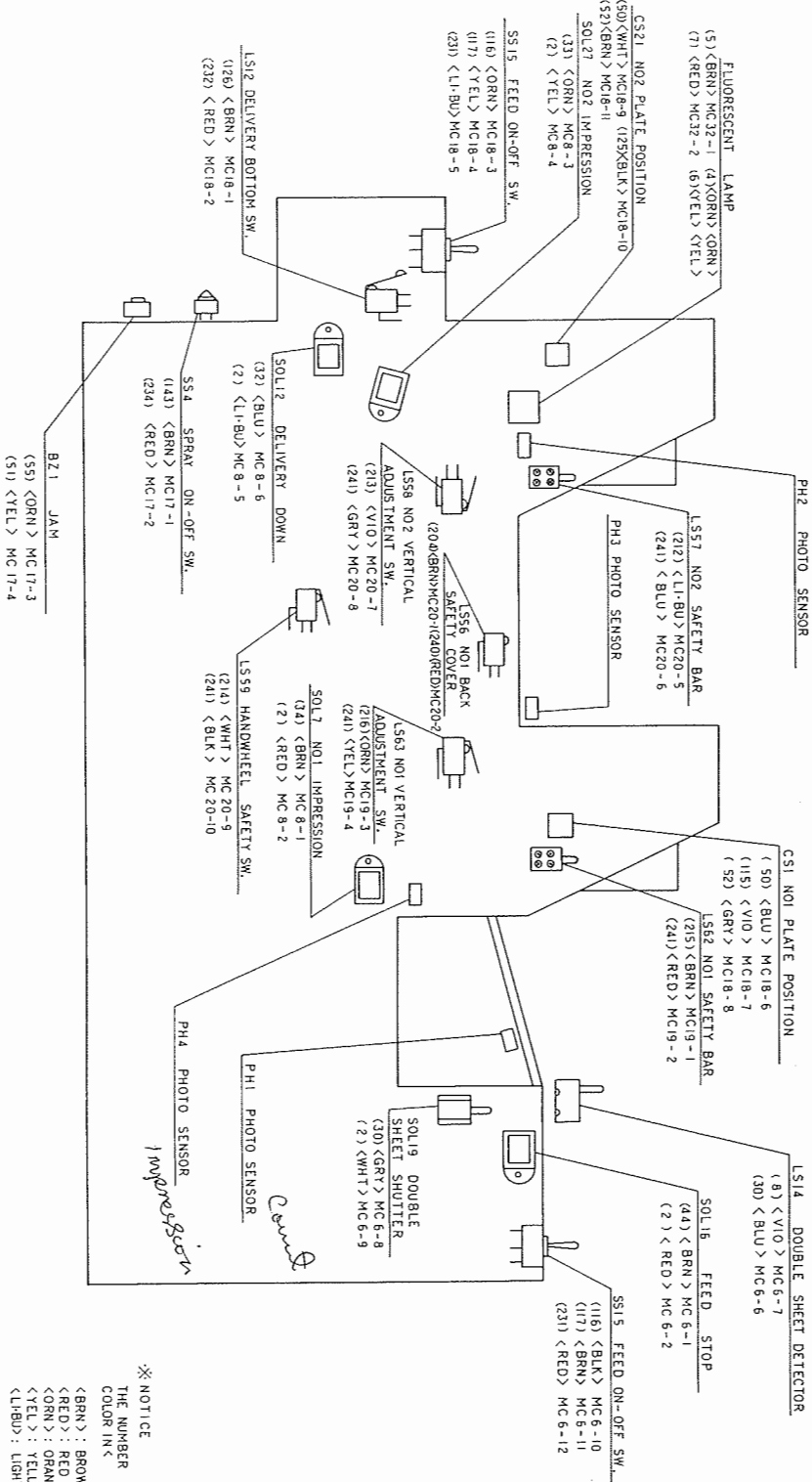


Full out jumper  
Machine went on  
Don't come on





5) Parts arrangement diagram  
a) Operation side



WIRE COLOR OF CONNECTOR

ORANGE	RED	BROWN
3	2	1
BLUE	LIGHT YELLOW	YELLOW
6	5	4
WHITE	GRAY	VIOLET
9	8	7
RED BROWN	BLACK	
12	11	10
LIGHT YELLOW	ORANGE	
15	14	13

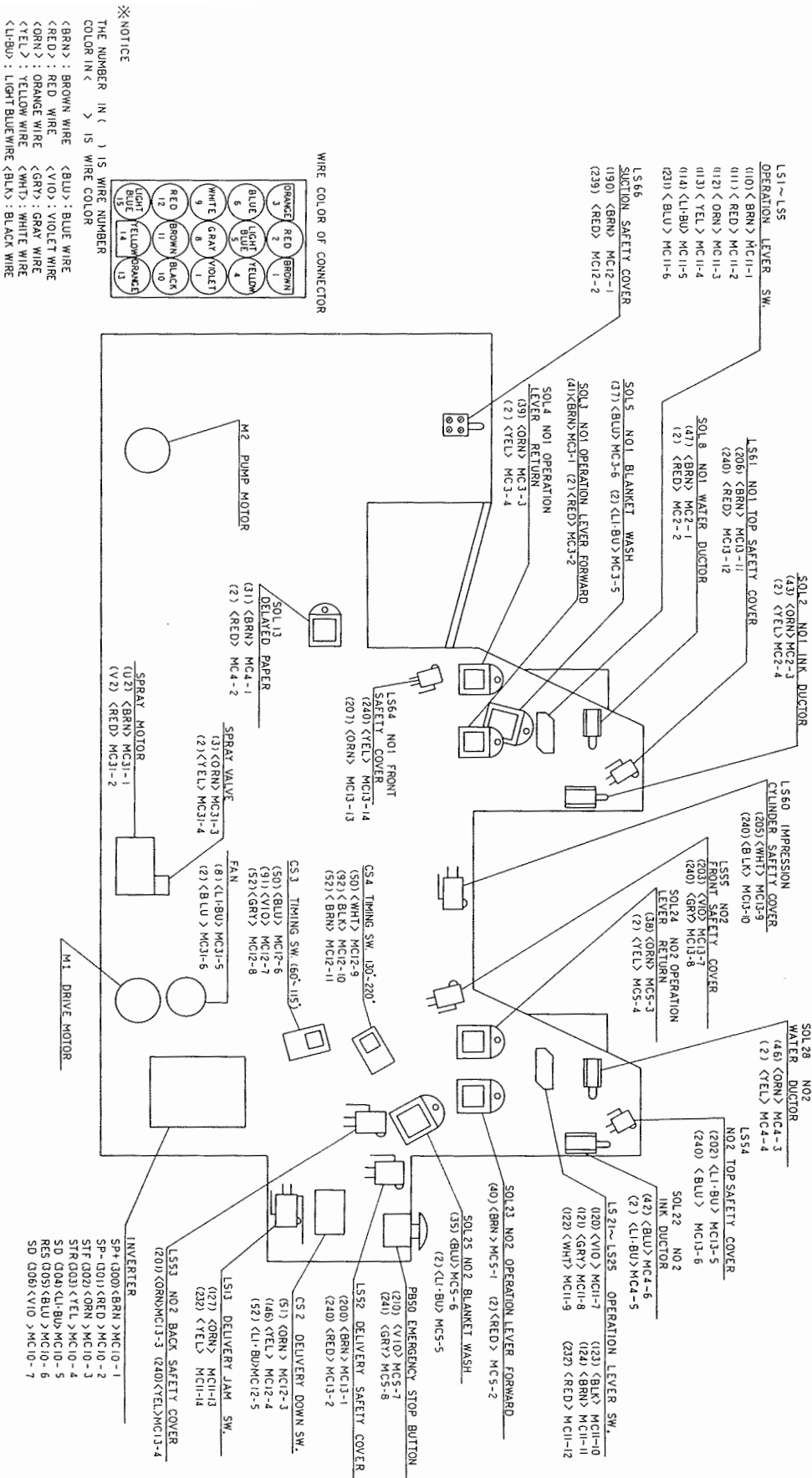
※ NOTICE

THE NUMBER IN ( ) IS WIRE NUMBER  
COLOR IN < > IS WIRE COLOR

<BRN> : BROWN WIRE  
<RED> : RED WIRE  
<VIO> : VIOLET WIRE  
<ORN> : ORANGE WIRE  
<GRY> : GRAY WIRE  
<YEL> : YELLOW WIRE  
<WHT> : WHITE WIRE  
<L-BU> : LIGHT BLUE WIRE  
<BLK> : BLACK WIRE



b) Non operation side





TO THE MAIN PANEL

PIN NO.

LINE NO.

360 (PL1)

381 (PL2)

382 (LD2)

384 (PL21)

385 (PL22)

387 (LD3)

360

361

362

363

364

365

366

367

370

371

372

373

374

375

376

377

351

352

353

354

355

356

357

358

TR1

TR2

TR3

TR4

TR5

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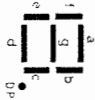
LD405

LD406

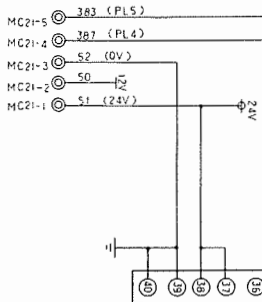
LD407

LD408

MARK	PART NAME
PL1	(N1) EMERGENCY STOP BUTTON
PL2	(N1) ON-OFF BUTTON
LO2	OR MONITOR ON WARNING LAMP
PL5	SUB PANEL OL WARNING LAMP RESET SW
PL21	(N2) EMERGENCY STOP BUTTON
PL22	(N2) ON-OFF BUTTON
LO3	OR MONITOR FLAME WARNING LAMP
PL6	SUB PANEL FLAME WARNING LAMP RESET SW

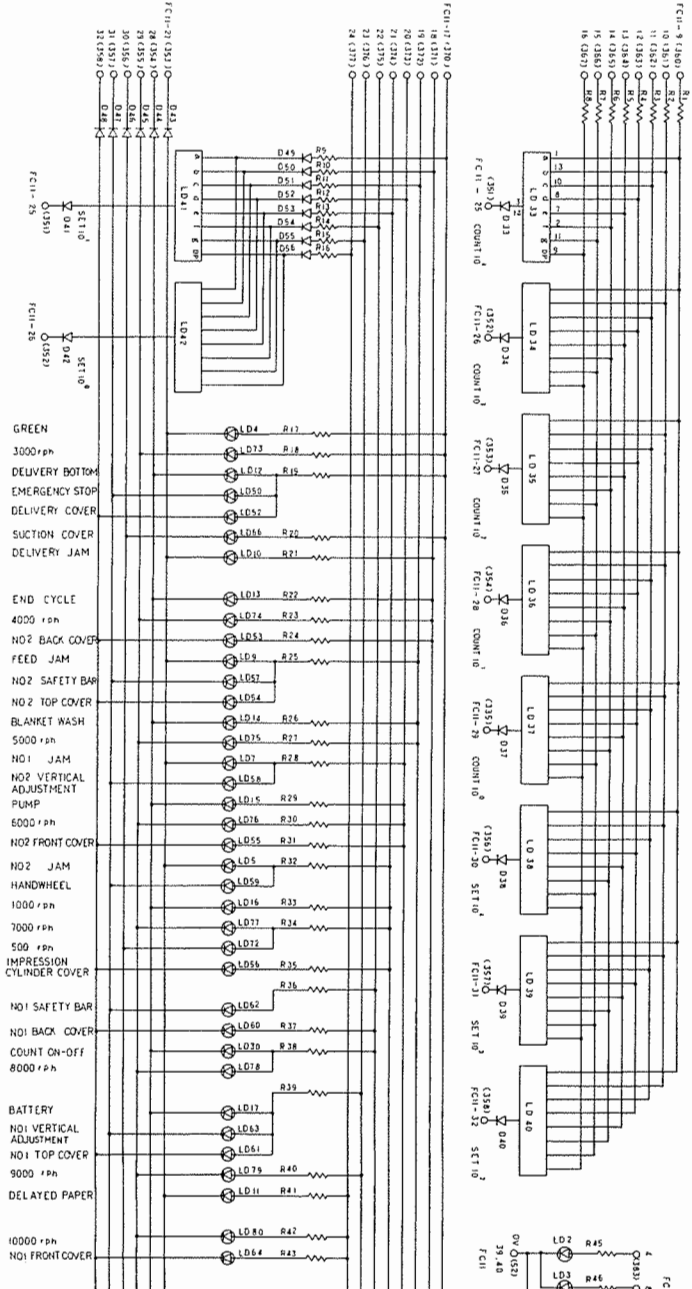
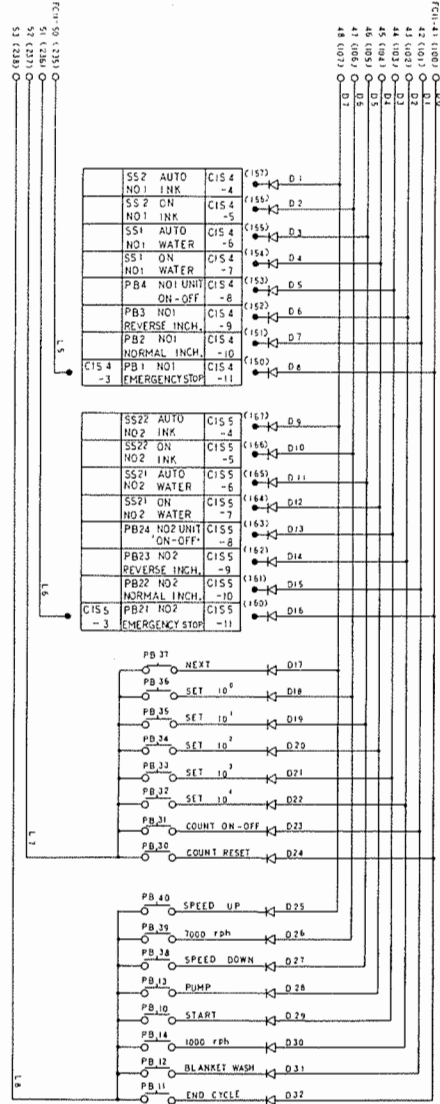
[illegible]

TO THE CONNECTOR BOARD





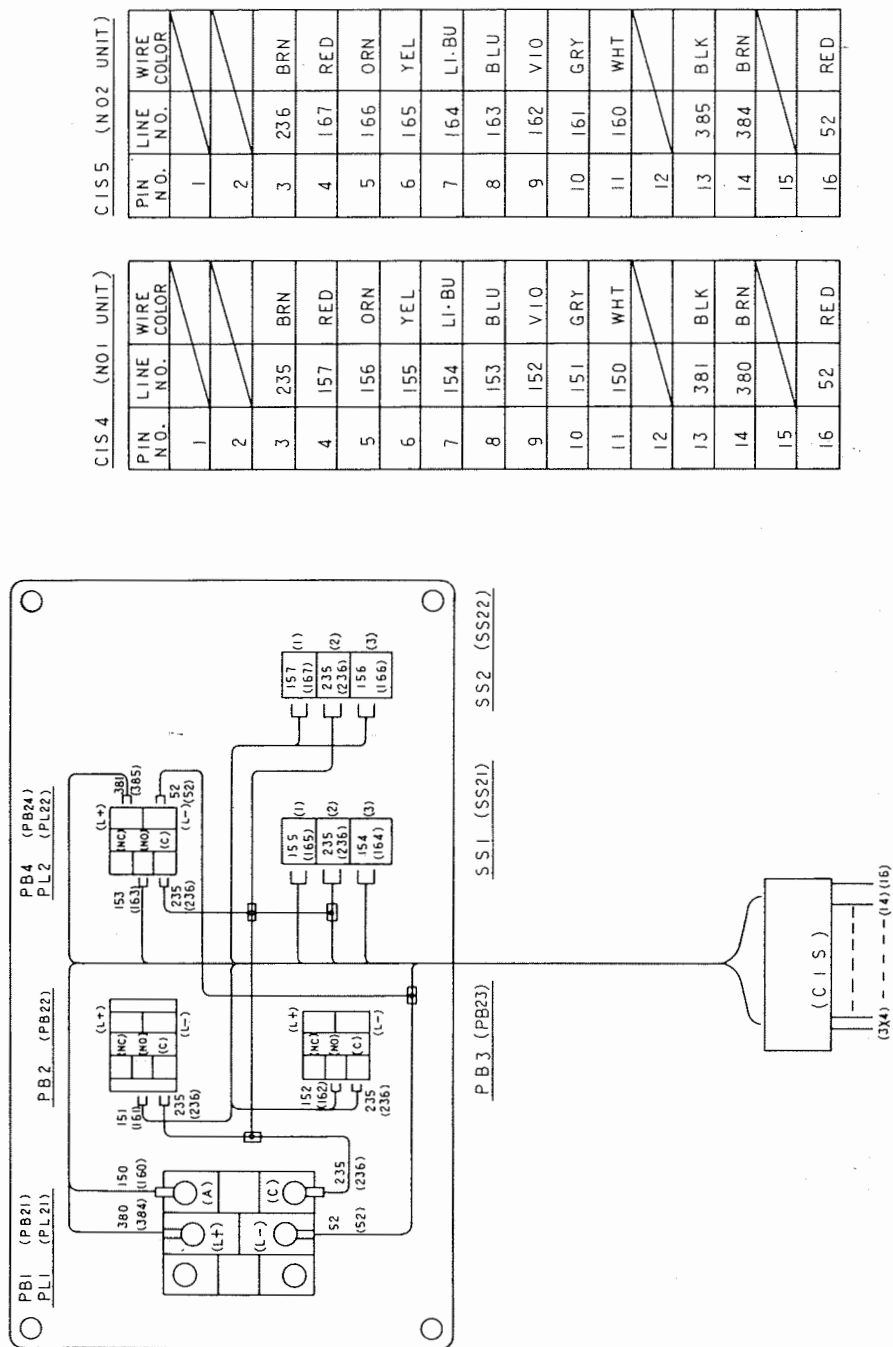
(7) Operation panel  
a) Main control panel circuit board diagram







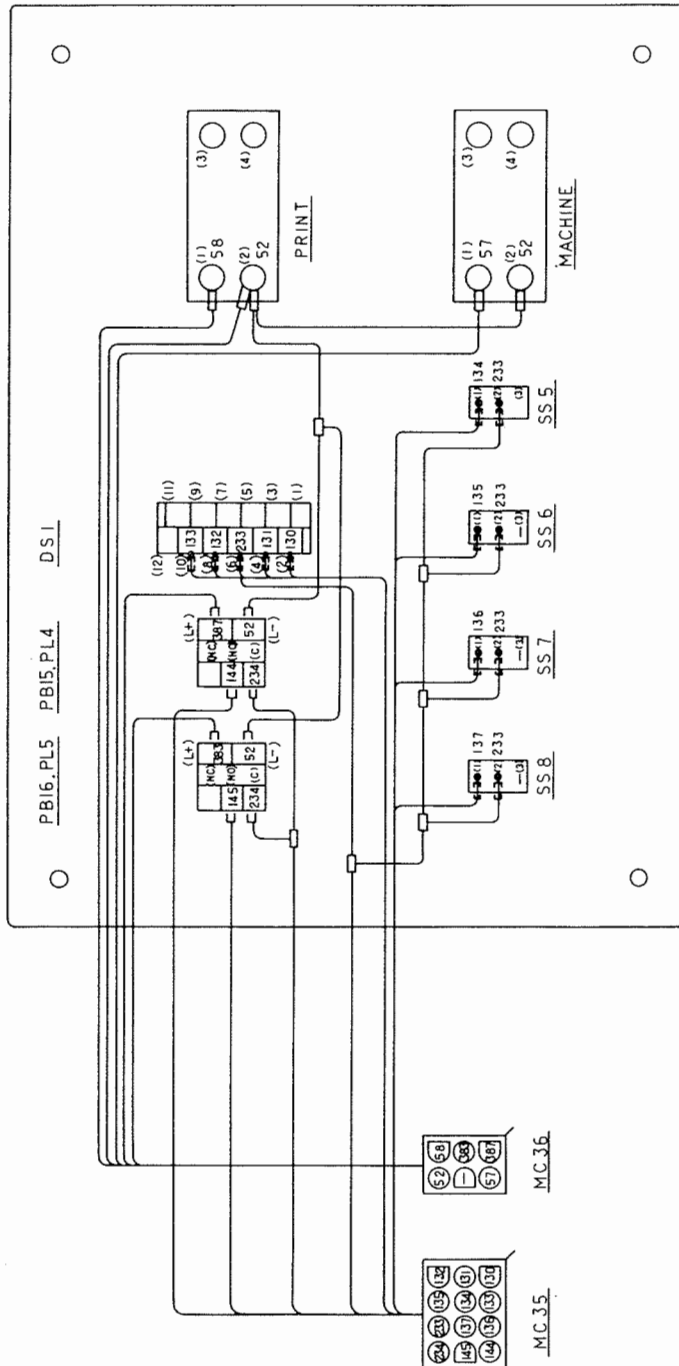
## c) Inching panel wiring diagram



CIS 4 (NO1 UNIT)			
PIN NO.	LINE NO.	WIRE NO.	WIRE COLOR
1			
2			
3	235		BRN
4	157		RED
5	156		ORN
6	155		YEL
7	154		LI-BU
8	153		BLU
9	152		VIO
10	151		GRY
11	150		WHT
12			
13	381		BLK
14	380		BRN
15			
16	52		RED

CIS 5 (NO2 UNIT)			
PIN NO.	LINE NO.	WIRE NO.	WIRE COLOR
1			
2			
3	236		BRN
4	167		RED
5	166		ORN
6	165		YEL
7	164		LI-BU
8	163		BLU
9	162		VIO
10	161		GRY
11	160		WHT
12			
13	385		BLK
14	384		BRN
15			
16	52		RED

b) Sub control panel wiring diagram



PIN NO.	LINE NO.	WIRE COLOR
1	387	BRN
2	383	RED
3	58	ORN
4	57	YEL
5		
6	52	BLU

PIN NO.	LINE NO.	WIRE COLOR
1	130	BRN
2	131	RED
3	132	ORN
4	133	YEL
5	134	LI-BU
6	135	BLU

(8) Input matrix chart

① Input = (+) is when  
② Output = (-) is when  
AC is present  
Voltage is closed  
High when sensor is closed  
Low when sensor is open

## INPUT MATRIX

	D7	D6	D5	D4	D3	D2	D1	D0
L1	SS15 OFF (FEEDER DELIVERY) FEED OFF SW.	SS15 ON (FEEDER DELIVERY) FEED ON SW.	CS1 (OP-SIDE) NO.1 PLATE POSITION	LS5 (NON-OP-SIDE) NO.1 LEVER POSITION V	LS4 (NON-OP-SIDE) NO.1 LEVER POSITION IV	LS3 (NON-OP-SIDE) NO.1 LEVER POSITION III	LS2 (NON-OP-SIDE) NO.1 LEVER POSITION II	LS1 (NON-OP-SIDE) NO.1 LEVER POSITION I
L2	LS13 (DELIVERY) CD JAM SW.	LS12 (DELIVERY) CD BOTTOM SW.	CS21 (OP-SIDE) NO.2 PLATE POSITION	LS25 (NON-OP-SIDE) NO.2 LEVER POSITION V	LS24 (NON-OP-SIDE) NO.2 LEVER POSITION IV	LS23 (NON-OP-SIDE) NO.2 LEVER POSITION III	LS22 (NON-OP-SIDE) NO.2 LEVER POSITION II	LS21 (NON-OP-SIDE) NO.2 LEVER POSITION I
L3	SS8 (SUB-PANEL) DELAYED PAPER OFF SW.	SS7 (SUB-PANEL) FEED JAM OFF SW.	SS6 (SUB-PANEL) NO.1 JAM OFF SW.	SS5 (SUB-PANEL) NO.2 JAM OFF SW.	SS4 (DELIVERY PANEL) SPRAY SW.	PH4 (TRANSFER DRUM) PHOTO SENSOR	PH3 (FEEDER) PHOTO SENSOR	
L4	CS3 (NON-OP-SIDE) TIMING SW.	CS2 (NON-OP-SIDE) DELIVERY DOWN SW.	PB16 (SUB-PANEL) OIL RESET BUTTON	PB15 (SUB-PANEL) PUMP RESET BUTTON	PB4 (NO.1 PANEL) NO.1 UNIT ON-OFF BUTTON	PB3 (NO.1 PANEL) NO.1 REVERSE INCHING BUTTON	PB2 (NO.1 PANEL) NO.1 NORMAL INCHING BUTTON	PB1 (NO.1 PANEL) NO.1 EMERGENCY STOP BUTTON
L5	SS2 AUTO (NO.1 PANEL) NO.1 INK AUTO	SS2 MANU (NO.1 PANEL) NO.1 INK MANU	SS1 AUTO (NO.1 PANEL) NO.1 WATER AUTO	SS1 MANU (NO.1 PANEL) NO.1 WATER MANU	PB4 (NO.2 PANEL) NO.2 UNIT ON-OFF BUTTON	PB3 (NO.2 PANEL) NO.2 REVERSE INCHING BUTTON	PB2 (NO.2 PANEL) NO.2 NORMAL INCHING BUTTON	PB1 (NO.2 PANEL) NO.2 EMERGENCY STOP BUTTON
L6	SS22 AUTO (NO.2 PANEL) NO.2 INK AUTO	SS22 MANU (NO.2 PANEL) NO.2 INK MANU	SS21 AUTO (NO.2 PANEL) NO.2 WATER AUTO	SS21 MANU (NO.2 PANEL) NO.2 WATER MANU	PB3 (MAIN PANEL) 10° BUTTON	PB3 (MAIN PANEL) 10° BUTTON	PB3 (MAIN PANEL) COUNT ON-OFF BUTTON	PB3 (MAIN PANEL) COUNT RESET BUTTON
L7	PB37 (MAIN PANEL) NEXT BUTTON	PB36 (MAIN PANEL) 10° BUTTON	PB35 (MAIN PANEL) 10° BUTTON	PB34 (MAIN PANEL) 10° BUTTON	PB33 (MAIN PANEL) 10° BUTTON	PB32 (MAIN PANEL) 10° BUTTON	PB31 (MAIN PANEL) COUNT ON-OFF BUTTON	PB30 (MAIN PANEL) COUNT RESET BUTTON
L8	PB40 (MAIN PANEL) SPEED UP BUTTON	PB39 (MAIN PANEL) 7000 R.P.H. BUTTON	PB38 (MAIN PANEL) SPEED DOWN BUTTON	PB13 (MAIN PANEL) PUMP BUTTON	PB10 (MAIN PANEL) START BUTTON	PB14 (MAIN PANEL) 1000R.P.H. BUTTON	PB12 (MAIN PANEL) BLANKET WASH BUTTON	PB11 (MAIN PANEL) END CYCLE BUTTON
L9	DS2-2 (CONNECTOR BOARD) BLANKET WASH	DS2-1 (CONNECTOR BOARD) BLANKET WASH	LS60 (NON-OP-SIDE) IMPRESSION CYLINDER COVER	LS56 (OP-SIDE) NO.1 BACK COVER	LS55 (NON-OP-SIDE) NO.2 FRONT COVER	LS54 (NON-OP-SIDE) NO.2 TOP COVER	LS53 (NON-OP-SIDE) NO.2 BACK COVER	LS52 (DELIVERY) DELIVERY COVER
L10	LS64 (NON-OP-SIDE) NO.1 FRONT COVER	LS61 (NON-OP-SIDE) NO.1 TOP COVER	LS62 (OP-SIDE) NO.1 SAFETY BAR	LS59 (OP-SIDE) HAND WHEEL SW.	LS58 (OP-SIDE) NO.2 VERTICAL ADJUSTMENT SW.	LS57 (OP-SIDE) NO.2 SAFETY BAR	LS56 (FEEDER) (OPTION) SUCTION SAFETY COVER	LS55 (DELIVERY) DELIVERY COVER
L11		LS63 (OP-SIDE) NO.1 VERTICAL ADJUSTMENT SW.						PB50 (DELIVERY) EMERGENCY STOP BUTTON

## INPUT INTERRUPT

IR0	PH3 (NO.1 BLANKET) PHOTO SENSOR
IR1	CS3 (NON-OP-SIDE) TIMING SW.
IR2	CS4 (NON-OP-SIDE) TIMING SW.
IR3	INTERNAL CIRCUIT
IR4	CS4 (NON-OP-SIDE) TIMING SW.
IR5	PH2 (NO.2 BLANKET) PHOTO SENSOR

## OUTPUT RELAY

R2	NO.1 INK STOP SOL.	R27	NO.2 IMPRESSION SOL.
R22	NO.2 INK STOP SOL.	R8	NO.1 WATER STOP SOL.
R3	NO.1 LEVER FORWARD SOL.	R28	NO.2 WATER STOP SOL.
R23	NO.2 LEVER FORWARD SOL.	R10	INVERTER START FORWARD
R4	NO.1 LEVER RETURN SOL.	R11	INVERTER START REVERSE
R24	NO.2 LEVER RETURN SOL.	R12	DELIVERY DOWN SOL.
R5	NO.1 BLANKET WASH SOL.	R13	DELAYED PAPER SOL.
R25	NO.2 BLANKET WASH SOL.	R15	PUMP MOTOR
R7	NO.1 IMPRESSION SOL.	R16	FEED OFF SOL.

## CHECK PROGRAM OF OUTPUT

GROUP1~4	LED ON THE MAIN PANEL
GROUP5	SPRAY PUMP BZ SOLENOID AT OP-SIDE
GROUP6	SOLENOID AT NON-OP-SIDE
GROUP7	INVERTER CONTROLLER
GROUP8	TAPE INSERTER LINE FOR INPUT MATRIX

## NOTE

SS5~SS8: LED LIGHTS AT OFF POSITION.

PH1~PH4: LED LIGHTS WHEN SOMETHING IS ON THE SENSOR.

SAFETY SW. PB50. LS52~LS66:

LED LIGHTS WHEN MACHINE CAN RUN.

Question (8)

CS3, CS4 .5~.4 VDC  
Between Ground & Center

Turning Switches





